A3G990-AW30-55

EC axial fan - HyBlade

sickle-shaped blades (S series)

for barn ventilation

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Nominal data

Type	**A3G990-AW30-55**
Motor	**M3G150-FF**

Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	820
Power consumption	W	1390
Current draw	A	6.1
Max. back pressure	Pa	70
Max. back pressure	inH2O	0.28
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	50.6	35.1
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		55.5	40
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	1.66
09 Air flow q_v	m^3/h	20430
09 Pressure increase p_{fs}	Pa	139
10 Speed (rpm) n	min^{-1}	815
11 Specific ratio*		1.00

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

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Technical description

Weight	22.8 kg
Fan size	990 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Sheet aluminum insert (painted black), sprayed with PP plastic
Number of blades	5
Blade pitch	-5°
Airflow direction	"A"
Direction of rotation	Counterclockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	F5
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on top
Condensation drainage holes	On stator side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Tach output - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Power limiter - Motor current limitation - PFC, active - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	C22.2 No.77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730

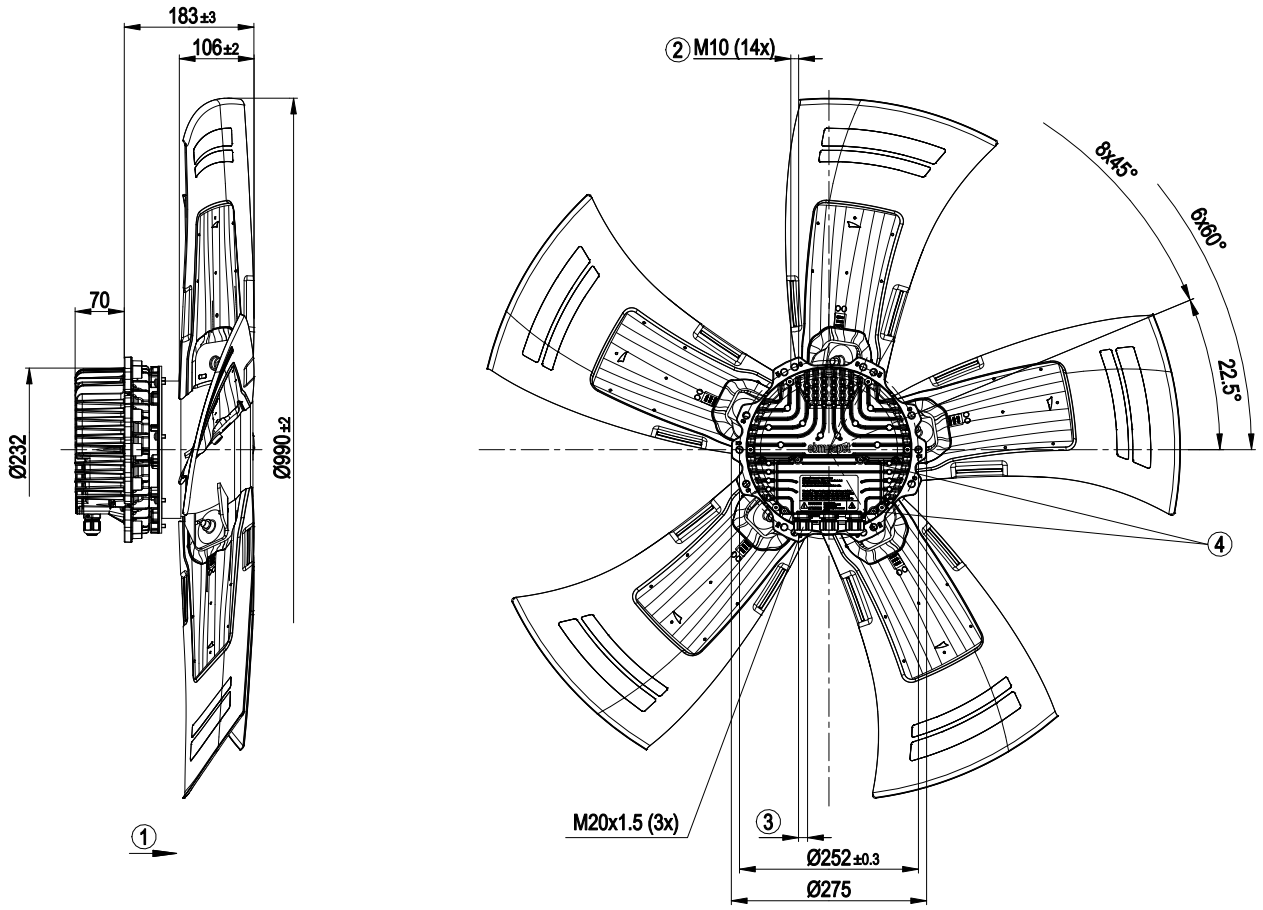
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Product drawing



1	Direction of air flow "A"
2	Max. clearance for screw 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
4	Tightening torque 3.5 ± 0.5 Nm

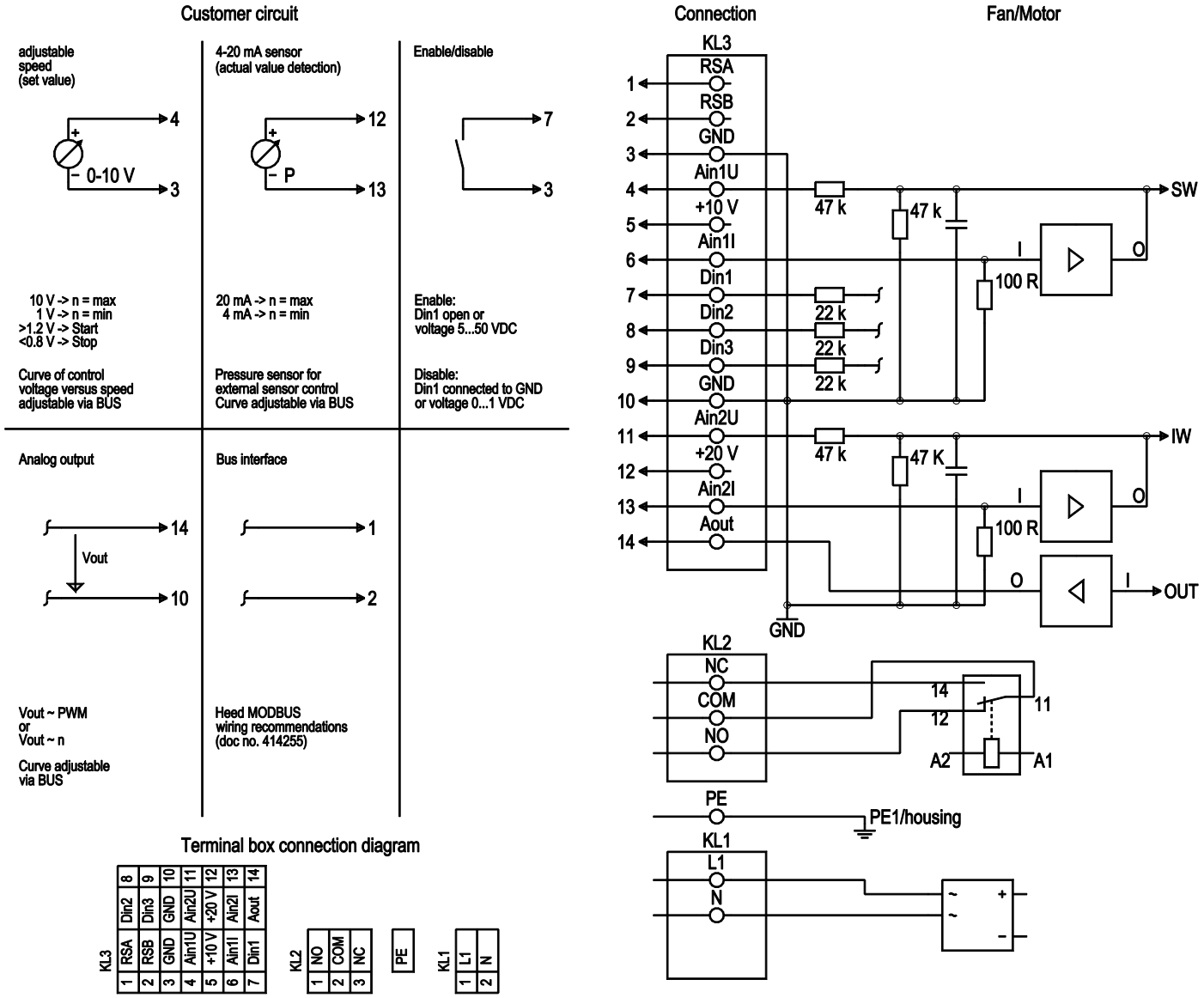
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Connection diagram



No.	Conn.	Designation	Function/assignment
KL1	1	L1	Supply connection, power supply; for nominal voltage range see technical data
KL1	2	N	Supply connection, power supply; for nominal voltage range see technical data
PE		PE	Ground connection, PE connection
KL2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating 250 VAC/ max. 2 A (AC1)/min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL3	3	GND	Reference ground for control interface; SELV
KL3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV

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No.	Conn.	Designation	Function/assignment
KL3	5	+ 10 V	Fixed voltage output 10 VDC, + 10 V +/-3%, max. 10 mA, short-circuit-proof, power supply for ext. devices (e.g. potentiometers); SELV
KL3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1 U; SELV
KL3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected via bus or digital input Din3; normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL3	10	GND	Reference ground for control interface, SELV
KL3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2 I; SELV
KL3	12	+ 20 V	Fixed voltage output 20 VDC, + 20 V +25/-10%, max. 50 mA, short-circuit-proof, power supply for ext. devices (e.g. sensors); SELV Alternatively: +24 VDC input for parameterization without line voltage
KL3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2 U; SELV
KL3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV

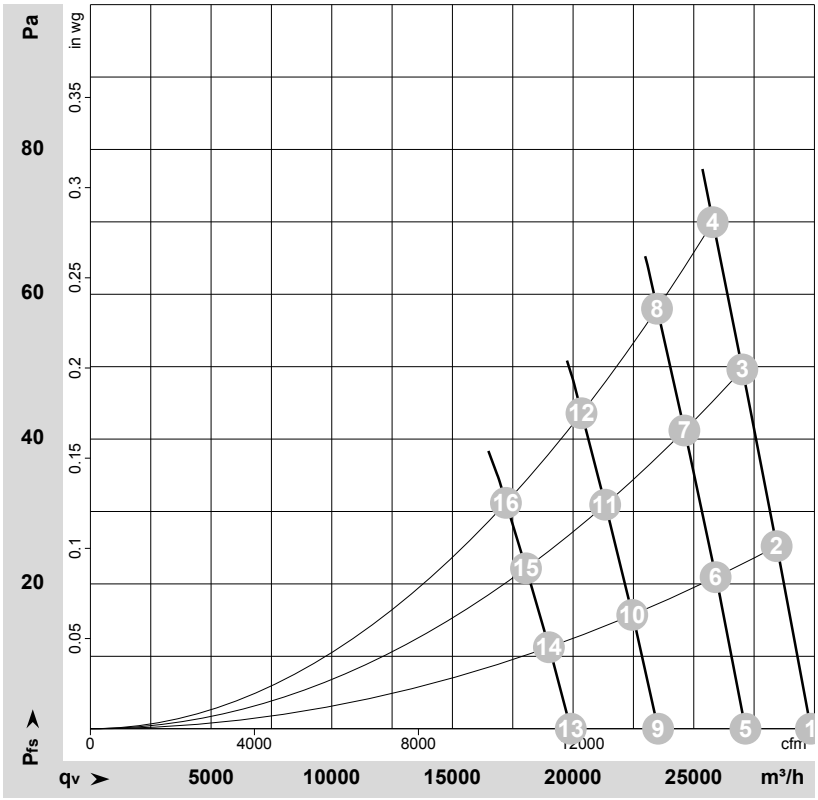
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Curves: Air performance 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-181095-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	inH2O
1	230	50	820	981	4.26	72	80	79	29855	0	17570	0.00
2	230	50	820	1117	4.86	70	79	78	28435	25	16735	0.10
3	230	50	820	1245	5.42	70	78	78	27015	50	15900	0.20
4	230	50	820	1390	6.10	70	78	78	25785	70	15175	0.28
5	230	50	750	737	3.20	69	77	77	27140	0	15975	0.00
6	230	50	750	846	3.68	68	76	76	25905	21	15245	0.08
7	230	50	750	942	4.10	67	76	75	24610	41	14485	0.16
8	230	50	750	1025	4.47	67	75	75	23480	58	13820	0.23
9	230	50	650	480	2.09	66	74	73	23525	0	13845	0.00
10	230	50	650	551	2.40	64	73	72	22450	16	13215	0.06
11	230	50	650	613	2.67	64	72	72	21330	31	12555	0.12
12	230	50	650	667	2.91	64	72	72	20350	44	11975	0.18
13	230	50	550	291	1.26	62	69	69	19905	0	11715	0.00
14	230	50	550	334	1.45	60	68	68	18995	11	11180	0.04
15	230	50	550	371	1.62	60	68	67	18050	22	10625	0.09
16	230	50	550	404	1.76	60	68	67	17215	31	10135	0.12

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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