S3G800-BO84-08

EC axial fan - HyBlade

sickle-shaped blades (S series)

with guard grille for full nozzle

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**S3G800-BO84-08**
Motor	**M3G112-IA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	735
Power consumption	W	835
Current draw	A	1.4
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	44.2	33
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		51.2	40
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	0.78
09 Air flow q_v	m^3/h	12095
09 Pressure increase p_{fs}	Pa	95
10 Speed (rpm) n	min^{-1}	740
11 Specific ratio*		1.00

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-117968

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Technical description

Weight	18.7 kg
Fan size	800 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Press-fitted sheet steel blank, sprayed with PP plastic
Guard grille material	Steel, coated with black plastic (RAL 9005)
Number of blades	5
Airflow direction	"V"
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE

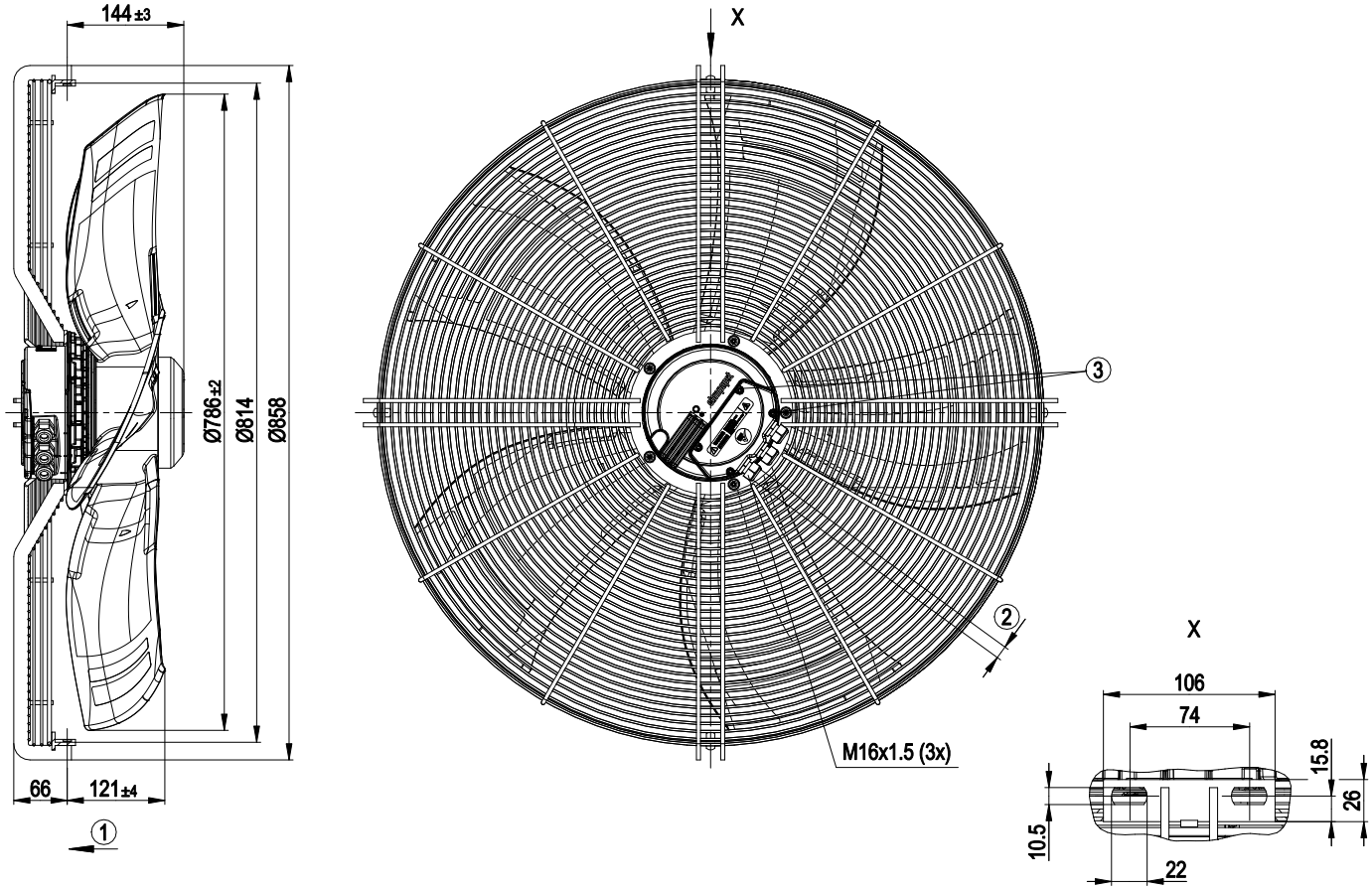
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Product drawing



1	Direction of air flow "V"
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 2.5 ± 0.4 Nm
3	Tightening torque 3.5 ± 0.5 Nm

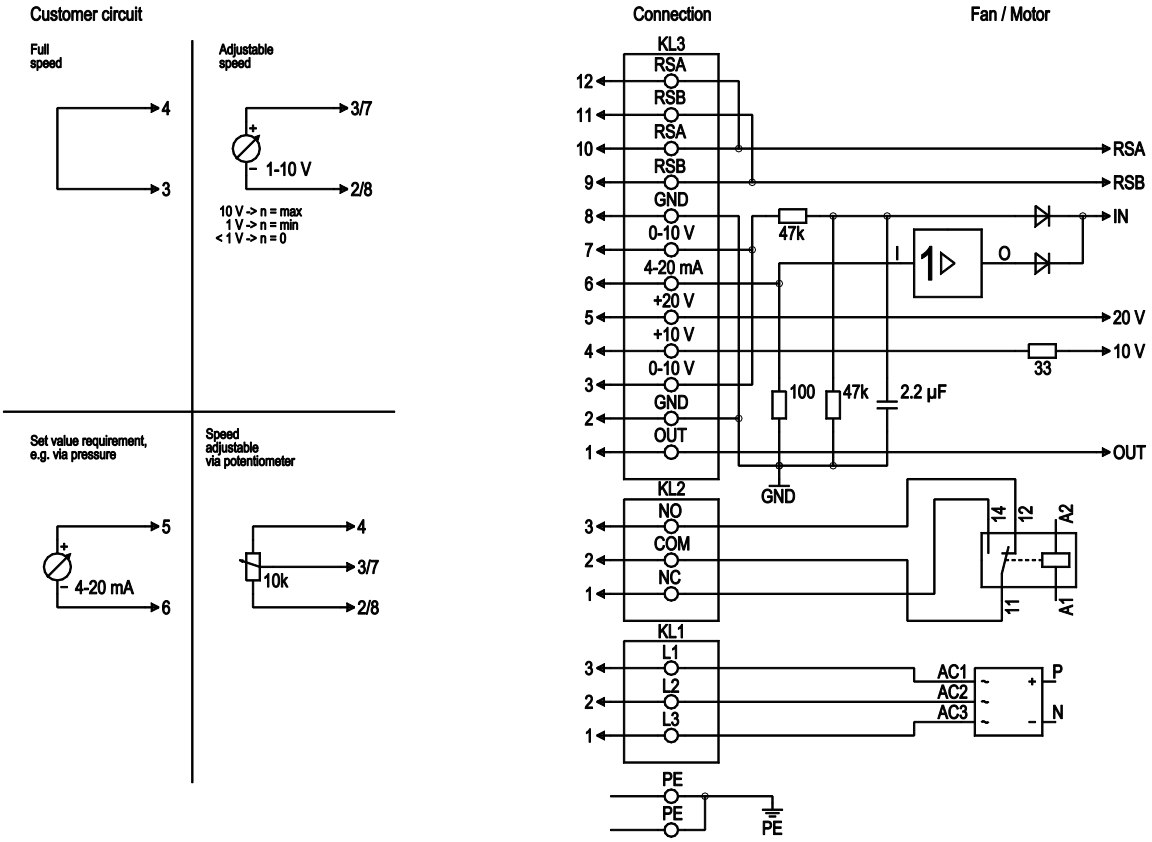
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Connection diagram



No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBUS, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBUS, RSA, SELV

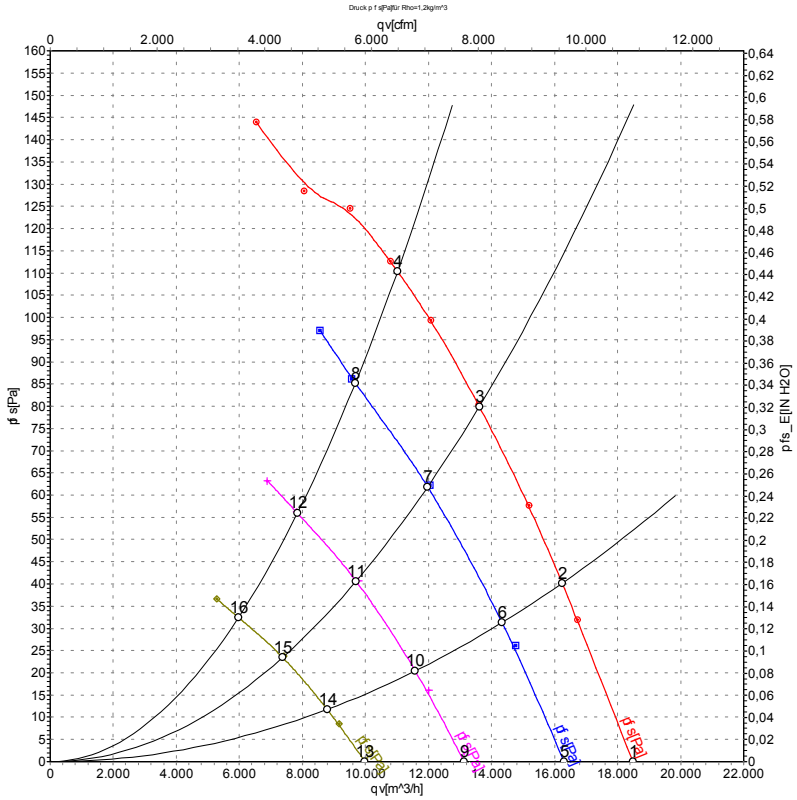
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Curves: Air performance 50 Hz



Measurement: LU-117968-1
Measurement: LU-118106-1
Measurement: LU-118107-1
Measurement: LU-118105-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	400	50	735	514	0.87	63	70	70	18480	0	10875	0.00
2	400	50	735	632	1.04	59	66	65	16240	40	9560	0.16
3	400	50	735	732	1.20	57	64	64	13610	80	8010	0.32
4	400	50	735	835	1.40	62	70	69	11020	110	6485	0.44
5	400	50	650	338	0.66	59	66	66	16290	0	9590	0.00
6	400	50	650	398	0.77	57	63	63	14330	32	8435	0.13
7	400	50	650	476	0.86	54	61	60	11970	63	7045	0.25
8	400	50	650	521	0.89	58	66	66	9685	85	5700	0.34
9	400	50	525	185	0.39	54	61	60	13120	0	7720	0.00
10	400	50	525	223	0.46	52	58	58	11580	21	6815	0.08
11	400	50	525	253	0.51	49	56	55	9705	41	5710	0.16
12	400	50	525	276	0.55	53	60	60	7845	56	4615	0.22
13	400	50	400	90	0.23	48	54	54	9985	0	5875	0.00
14	400	50	400	107	0.26	46	52	52	8785	12	5170	0.05
15	400	50	400	120	0.28	43	50	50	7375	24	4340	0.10
16	400	50	400	127	0.29	45	52	52	5975	32	3515	0.13

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase

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