W3GB20-IQ07-01

EC axial fan

Airfoil blade

Double-flange fan housing

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**W3GB20-IQ07-01**
Motor	**M3G200-QA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed	min^{-1}	1550
Power consumption	W	9500
Current draw	A	14.6
Max. back pressure	Pa	530
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	49.1	39.8
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		49.3	40
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	9.52
09 Air flow q_v	m^3/h	35795
09 Pressure increase p_{fs}	Pa	452
10 Speed n	min^{-1}	1510
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-160363

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Technical description

Weight	195 kg
Fan size	1120 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Die-cast aluminum
Fan housing material	Sheet steel, galvanized
Number of blades	5
Blade pitch	23°
Airflow direction	"V"
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	F4-1
Ambient temperature note	Occasional start-up between -40°C and -25°C is permissible. For continuous operation at temperatures below -25°C (e.g. refrigeration applications) we recommend our fan design with special low-temperature bearings.
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1

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Approval	EAC; UL 1004-7 + 60730; C22.2 No.77 + CAN/CSA-E60730-1

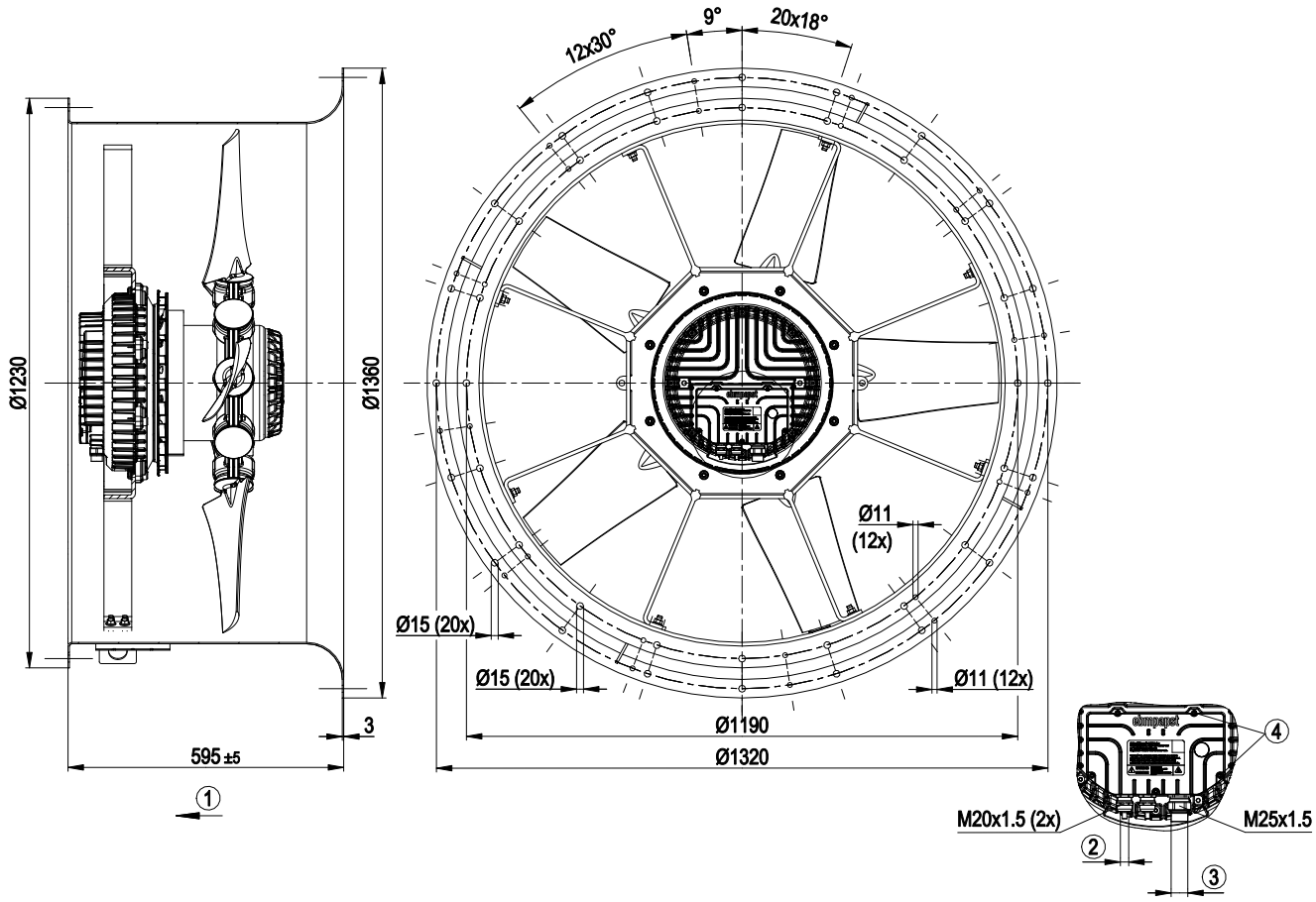
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Product drawing



1	Direction of air flow "V"
2	Cable diameter min. 5 mm, max. 13 mm; tightening torque 6 ± 0.9 Nm
3	Cable diameter min. 16 mm, max. 20.5 mm, tightening torque 6 ± 0.9 Nm
4	Tightening torque 3.5 ± 0.5 Nm

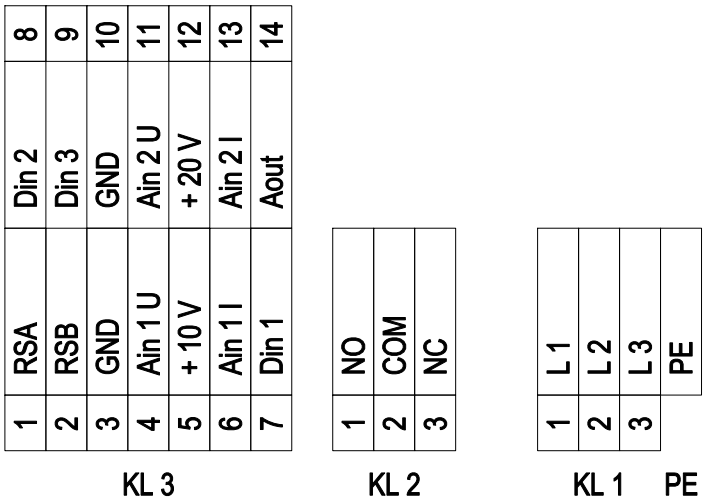
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Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS RTU
KL 3	2	RSB	Bus connection RS485, RSA, MODBUS RTU
KL 3	3 / 10	GND	Reference ground for control interface
KL 3	4	Ain1 U	Analog input 1 (set value), 0-10 V, Ri = 100 kΩ, adjustable curves, only usable as alternative to input Ain1I
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%; max. 10 mA; short-circuit-proof; power supply for external devices (e.g. pot)
KL 3	6	Ain1 I	Analog input 1 (set value), 4-20 mA, Ri = 100 Ω, adjustable curves, only usable as alternative to input Ain1U
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5...50 VDC: disable: bridge to GND or applied voltage < 1 VDC; reset function: triggers software reset after a level change to < 1 V
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2; according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC; parameter set 2: bridge to GND or applied voltage < 1 VDC
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input; normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC
KL 3	11	Ain2 U	Analog input 2, measured value 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, 20 V +25/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors)
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2U
KL 3	14	Aout	Analog output 0-10 V, max. 5 mA, output of current motor modulation level / of the current motor speed. Adjustable curve.

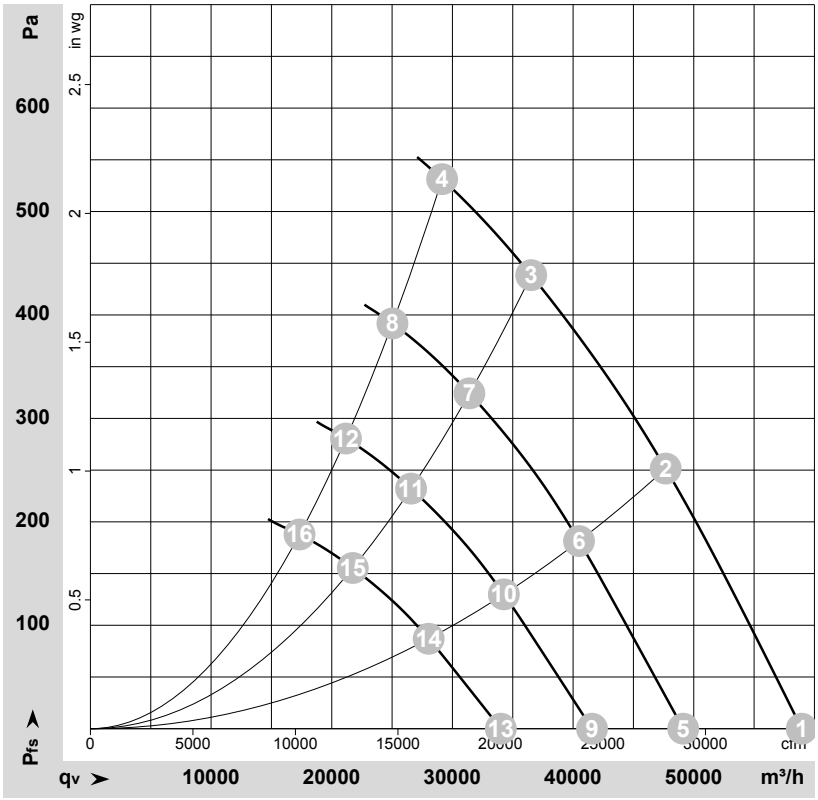
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Curves: Air performance 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-160363

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa
1	400	50	1550	7716	11.93	98	105	104	58950	0
2	400	50	1530	9122	14.05	95	103	102	47675	250
3	400	50	1510	9500	14.60	104	111	111	36530	440
4	400	50	1515	9385	14.43	105	113	112	29145	530
5	400	50	1300	4465	6.91	93	101	100	49125	0
6	400	50	1300	5590	8.61	91	99	97	40490	183
7	400	50	1300	6052	9.30	100	108	108	31410	325
8	400	50	1300	5949	9.15	101	109	108	25030	393
9	400	50	1100	2705	4.18	89	97	95	41570	0
10	400	50	1100	3386	5.21	87	94	93	34260	131
11	400	50	1100	3667	5.63	96	103	103	26575	233
12	400	50	1100	3604	5.54	97	105	104	21180	281
13	400	50	900	1482	2.29	84	92	90	34010	0
14	400	50	900	1855	2.86	82	89	88	28035	88
15	400	50	900	2008	3.09	91	98	98	21745	156
16	400	50	900	1974	3.04	92	100	99	17330	188

U = Power supply · f = Frequency · n = Speed · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase

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