**K3G630-AT09-01**

# EC centrifugal module - RadiPac

backward curved, single inlet

in cube design

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## Nominal data

| | |
|---|---|
| **Type** | **K3G630-AT09-01** |
| **Motor** | **M3G200-QA** |

| | | |
|---|---|---|
| Phase | | 3~ |
| Nominal voltage | VAC | 400 |
| Nominal voltage range | VAC | 380 .. 480 |
| Frequency | Hz | 50/60 |
| Type of data definition | | ml |
| Speed (rpm) | $min^{-1}$ | 2200 |
| Power input | W | 13750 |
| Current draw | A | 21.0 |
| Min. ambient temperature | °C | -40 |
| Max. ambient temperature | °C | 40 |

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

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## Technical features

| | |
|---|---|
| **Mass** | 148 kg |
| **Size** | 630 mm |
| **Motor size** | 200 |
| **Surface of rotor** | Coated in black |
| **Material of electronics housing** | Die-cast aluminium, coated in black |
| **Material of impeller** | Aluminium sheet |
| **Material of inlet nozzle** | Sheet steel, galvanised and plastic-coated in light grey (RAL 7035) |
| **Material of support structure** | Sheet steel, galvanised and plastic-coated in light grey (RAL 7035) |
| **Number of blades** | 7 |
| **Direction of rotation** | Clockwise, seen on rotor |
| **Type of protection** | IP55 |
| **Insulation class** | "F" |
| **Humidity (F) / environmental protection class (H)** | H1 |
| **Note ambient temperature** | Occasional start-up between -40 °C and -25 °C is permissible. For continuous operation at ambient temperatures below -25 °C (e.g. refrigeration applications), a fan version with special low-temperature bearings must be used. |
| **Max. permissible ambient motor temp. (transp./ storage)** | +80 °C |
| **Min. permissible ambient motor temp. (transp./storage)** | -40 °C |
| **Mounting position** | Shaft horizontal (base mounting only); rotor on top or rotor on bottom on request |
| **Condensation drainage holes** | Rotor-side |
| **Operation mode** | S1 |
| **Motor bearing** | Ball bearing |
| **Technical features** | - Output 10 VDC, max. 10 mA<br>- Output 20 VDC, max. 50 mA<br>- Output for slave 0-10 V<br>- Operation and alarm display<br>- Input for sensor 0-10 V or 4-20 mA<br>- External 24 V input (programming)<br>- External release input<br>- Alarm relay<br>- Integrated PID controller<br>- Output limit<br>- Motor current limit<br>- PFC, passive<br>- RS485 MODBUS RTU<br>- Soft start<br>- Control input 0-10 VDC / PWM<br>- Control interface with SELV potential safely disconnected from the mains<br>- Temperature derating<br>- Over-temperature protected electronics / motor<br>- Line undervoltage / phase failure detection |
| **EMC interference immunity** | Acc. to EN 61000-6-2 (industrial environment) |
| **EMC interference emission** | Acc. to EN 61000-6-4 (industrial environment) |
| **Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)** | <= 3.5 mA |
| **Electrical connection** | Terminal box |



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| | |
|---|---|
| **Motor protection** | Reverse polarity and locked-rotor protection |
| **Safety classification** | I; If a protective earth is connected by the customer<br>This component to be built-in can have several local protection class ratings. The specification refers to the basic design of this component.<br>The final protection class is based on the intended installation and connection of the component. |
| **Product conforming to standard** | EN 61800-5-1 |
| **Note on CE** | Operation only permitted outside the European Economic Area |
| **Approval** | UL 1004-7 + 60730-1; EAC; CSA C22.2 no. 77 + CAN/CSA-E60730-1 |



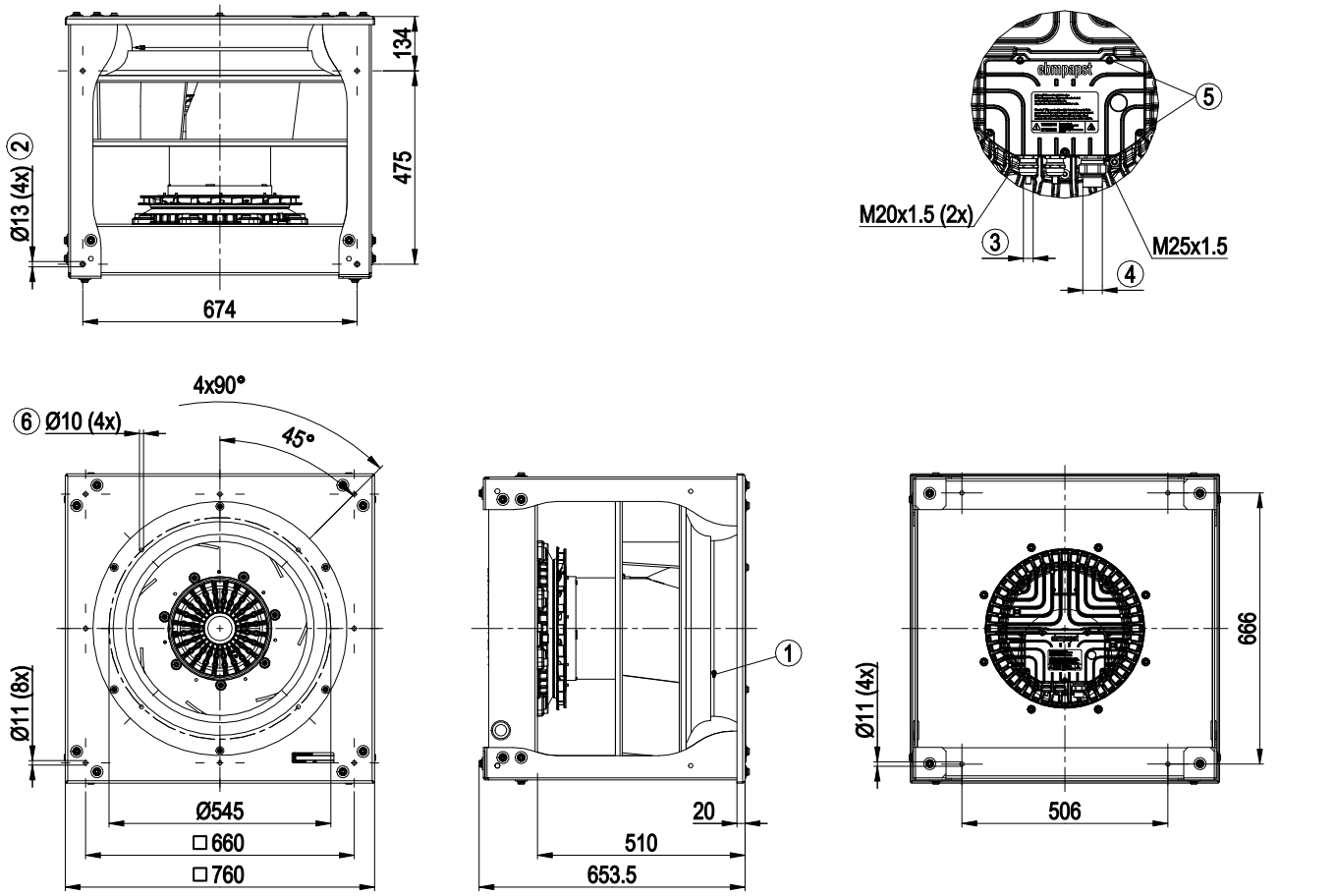
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## Product drawing




| | |
|---|---|
| 1 | Inlet nozzle with pressure tap (k-factor: 438) |
| 2 | Screw-on position for vibration-absorbing elements, tightening torque max. 40 Nm |
| 3 | Cable diameter min. 5 mm, max. 13 mm, tightening torque 6±0.9 Nm |
| 4 | Cable diameter min. 16 mm, max. 20.5 mm, tightening torque 6±0.9 Nm |
| 5 | Tightening torque 3.5±0.5 Nm |
| 6 | Attachment holes for FlowGrid 00630-2-2957 (not included in scope of delivery) |



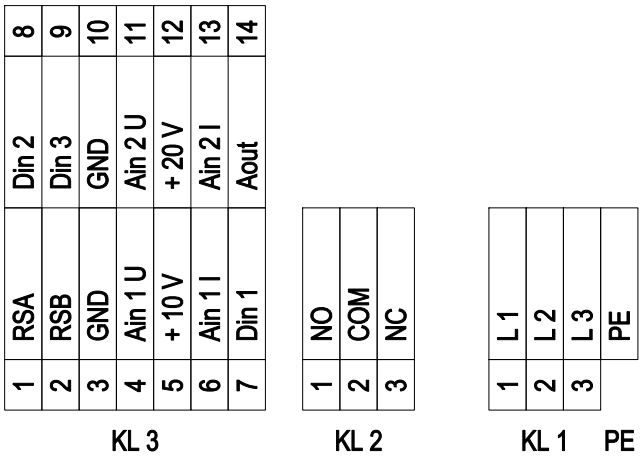
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## Connection screen




| No. | Conn. | Designation | Function / assignment |
|---|---|---|---|
| KL 1 | 1 | L1 | Mains supply connection, supply voltage 3-phase 380-480 VAC; 50/60 Hz |
| KL 1 | 2 | L2 | Mains supply connection, supply voltage 3-phase 380-480 VAC; 50/60 Hz |
| KL 1 | 3 | L3 | Mains supply connection, supply voltage 3-phase 380-480 VAC; 50/60 Hz |
| PE | | PE | Earth connection, PE connection |
| KL 2 | 1 | NO | Status relay, floating status contact; normally open; make for failure |
| KL2 | 2 | COM | Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA |
| KL2 | 3 | NC | Status relay, floating status contact; break for failure |
| KL 3 | 1 | RSA | Bus connection RS485; RSA; MODBUS RTU |
| KL 3 | 2 | RSB | Bus connection RS485; RSB; MODBUS RTU |
| KL 3 | 3 / 10 | GND | Reference ground for control interface |
| KL 3 | 4 | Ain1 U | Analogue input 1 (set value); 0-10 V; Ri= 100 kΩ; parametrisable curves; only usable as alternative to input Ain1 I |
| KL 3 | 5 | + 10 V | Fixed voltage output 10 VDC; + 10 V +/-3%; max. 10 mA; short circuit proof; power supply for ext. devices (e.g. potentiometer) |
| KL 3 | 6 | Ain1 I | Analogue input 1 (set value); 4-20 mA; Ri= 100 Ω; parametrisable curves; only usable as alternative to input Ain1 U |
| KL 3 | 7 | Din1 | Digital input 1: enabling of electronics; enabling: open pin or applied voltage 5 to 50 VDC; disabling: bridge to GND or applied voltage < 1 VDC; reset function: triggers software reset after a level change to <1 V |
| KL 3 | 8 | Din2 | Digital input 2: parameter set switch 1/2; according to EEPROM setting, the valid/used parameter set is selectable per BUS or per digital input DIN2. Parameter set 1: open pin or applied voltage 5 to 50 VDC; parameter set 2: bridge to GND or applied voltage < 1 VDC |
| KL 3 | 9 | Din3 | Digital input 3: Control characteristic of the integrated controller; according to EEPROM setting, the control characteristic of the integrated controller is normally/inversely selectable per BUS or per digital input; normal: open pin or applied voltage 5 to 50 VDC (control deviation = actual sensor value - set value) inverse: bridge to GND or applied voltage < 1 VDC (control deviation = set value - actual sensor value) |
| KL 3 | 11 | Ain2 U | Analogue input 2; actual sensor value 0-10 V; Ri= 100 kΩ; parametrisable curve; only usable as alternative to input Ain2 I |
| KL 3 | 12 | + 20 V | Fixed voltage output 20 VDC; + 20V +25/-10%; max. 50 mA; short circuit proof; supply voltage for ext. devices (e.g. sensors) |
| KL 3 | 13 | Ain2 I | Analogue input 2; actual sensor value 4-20 mA; Ri= 100 Ω; parametrisable curve; only usable as alternative to input Ain2 U |
| KL 3 | 14 | Aout | Analogue output 0-10 V; max. 5 mA; output of the actual motor control factor (output voltage of electronics)/ of the actual motor speed. Parametrisable curve. |



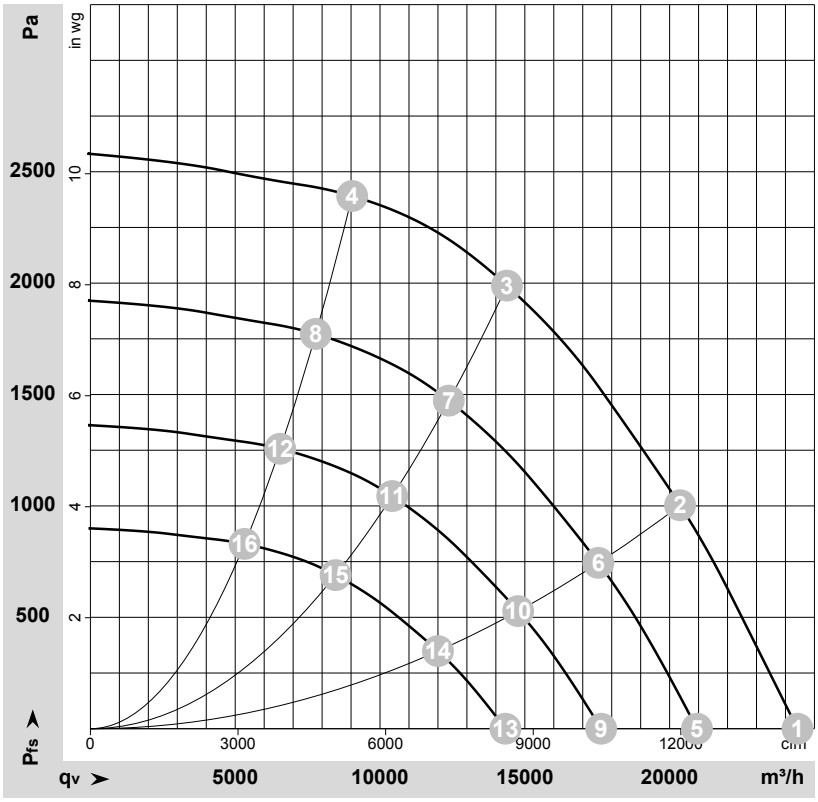
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## Charts: Air flow 50 Hz




ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-174526-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

## Measured values

| | Conn. | U | f | n | $P_{ed}$ | I | $LpA_{in}$ | $LwA_{in}$ | $LwA_{out}$ | $q_V$ | $p_{fs}$ | $q_V$ | $p_{fs}$ |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| | | V | Hz | $min^{-1}$ | W | A | dB(A) | dB(A) | dB(A) | $m^3/h$ | Pa | cfm | in. wg |
| 1 | 3~ | 400 | 50 | 2200 | 8678 | 13.55 | 98 | 107 | 111 | 24415 | 0 | 14370 | 0.00 |
| 2 | 3~ | 400 | 50 | 2200 | 12002 | 18.49 | 94 | 100 | 104 | 20360 | 1000 | 11985 | 4.01 |
| 3 | 3~ | 400 | 50 | 2200 | 13750 | 21.00 | 86 | 94 | 100 | 14380 | 2000 | 8465 | 8.03 |
| 4 | 3~ | 400 | 50 | 2200 | 12352 | 18.92 | 92 | 99 | 102 | 9040 | 2400 | 5320 | 9.64 |
| 5 | 3~ | 400 | 50 | 1900 | 5477 | 8.55 | 94 | 103 | 107 | 20945 | 0 | 12325 | 0.00 |
| 6 | 3~ | 400 | 50 | 1900 | 7670 | 11.82 | 90 | 96 | 101 | 17540 | 747 | 10325 | 3.00 |
| 7 | 3~ | 400 | 50 | 1900 | 8744 | 13.38 | 82 | 90 | 96 | 12375 | 1475 | 7285 | 5.92 |
| 8 | 3~ | 400 | 50 | 1900 | 7881 | 12.07 | 88 | 95 | 99 | 7780 | 1776 | 4580 | 7.13 |
| 9 | 3~ | 400 | 50 | 1600 | 3271 | 5.11 | 90 | 99 | 103 | 17635 | 0 | 10380 | 0.00 |
| 10 | 3~ | 400 | 50 | 1600 | 4581 | 7.06 | 85 | 92 | 96 | 14770 | 530 | 8695 | 2.13 |
| 11 | 3~ | 400 | 50 | 1600 | 5222 | 7.99 | 78 | 86 | 92 | 10420 | 1046 | 6135 | 4.20 |
| 12 | 3~ | 400 | 50 | 1600 | 4706 | 7.21 | 84 | 91 | 94 | 6550 | 1260 | 3855 | 5.06 |
| 13 | 3~ | 400 | 50 | 1300 | 1754 | 2.74 | 84 | 94 | 98 | 14330 | 0 | 8435 | 0.00 |
| 14 | 3~ | 400 | 50 | 1300 | 2457 | 3.78 | 80 | 86 | 91 | 12000 | 350 | 7065 | 1.41 |
| 15 | 3~ | 400 | 50 | 1300 | 2801 | 4.29 | 73 | 81 | 87 | 8465 | 691 | 4985 | 2.77 |
| 16 | 3~ | 400 | 50 | 1300 | 2524 | 3.87 | 78 | 85 | 89 | 5325 | 832 | 3135 | 3.34 |

Conn. = Connection · U = Supply voltage · f = Frequency · n = Speed (rpm) · $P_{ed}$ = Power input · I = Current draw · $LpA_{in}$ = Sound pressure level inlet side · $LwA_{in}$ = Sound power level inlet side
$LwA_{out}$ = Sound power level outlet side · $q_V$ = Air flow · $p_{fs}$ = Pressure increase



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