R3G560-AG07-03

EC centrifugal fan

backward curved, single inlet



ebm-papst Mulfingen GmbH & Co. KG
Bachmühle 2 · D-74673 Mulfingen
Phone +49 7938 81-0
Fax +49 7938 81-110
info1@de.ebmpapst.com
www.ebmpapst.com

Limited partnership · Headquarters Mulfingen
County court Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen
County court Stuttgart · HRB 590142

ErP2015 EXCEEDS THE NORM

Nominal data

Type	**R3G560-AG07-03**	
Motor	**M3G150-FF**	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min^{-1}	1350
Power input	W	2300
Current draw	A	3.6
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}	%	59.8	51.4	55.4
Efficiency grade N		66.4	58	62
Power input P_{ed}	kW	2.36		
Air flow q_v	m^3/h	8010		
Pressure increase p_{fs}	Pa	599		
Speed n	min^{-1}	1360		

Data definition with optimum efficiency. LU-108580
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

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Technical features

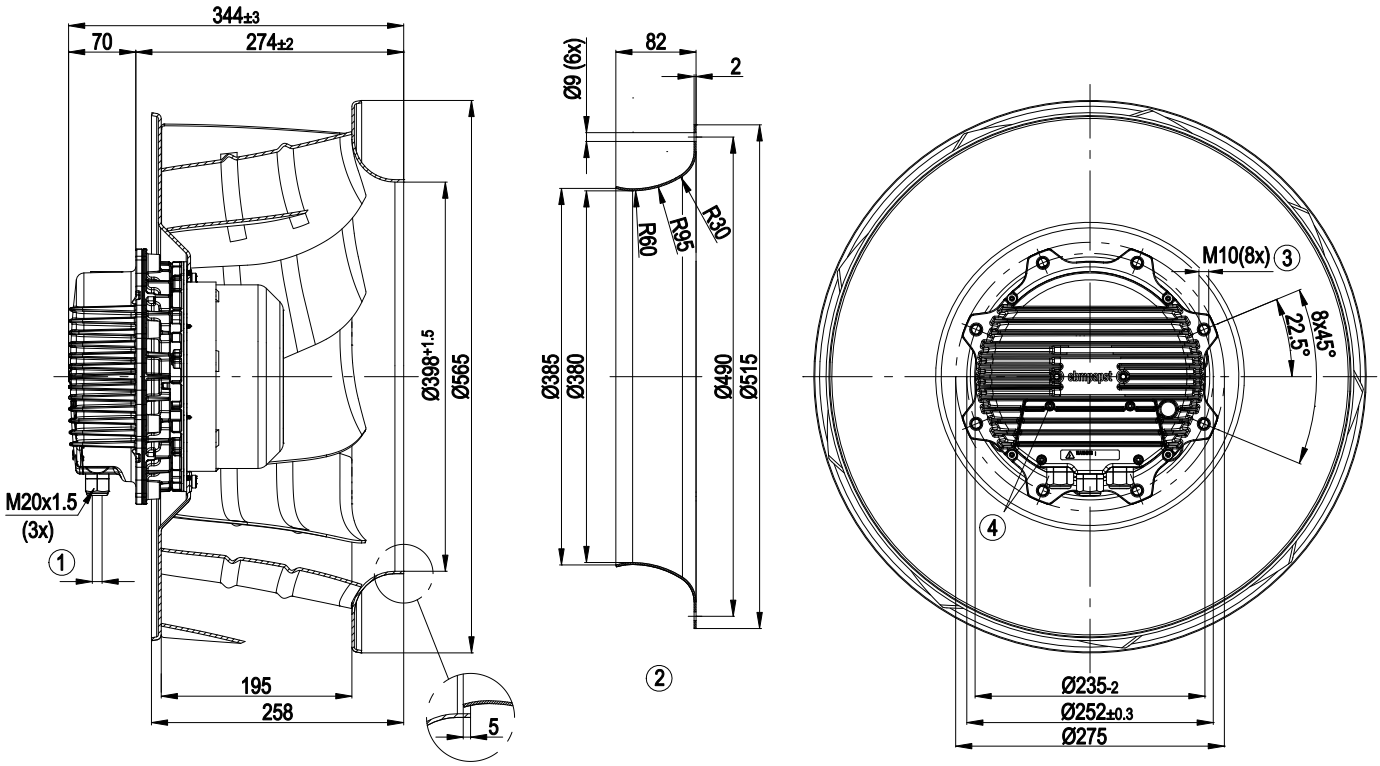
Mass	23.5 kg
Size	560 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminum
Material of impeller	Aluminium sheet
Number of blades	9
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	UL 2111; VDE; EAC; CSA C22.2 Nr.77

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Product drawing



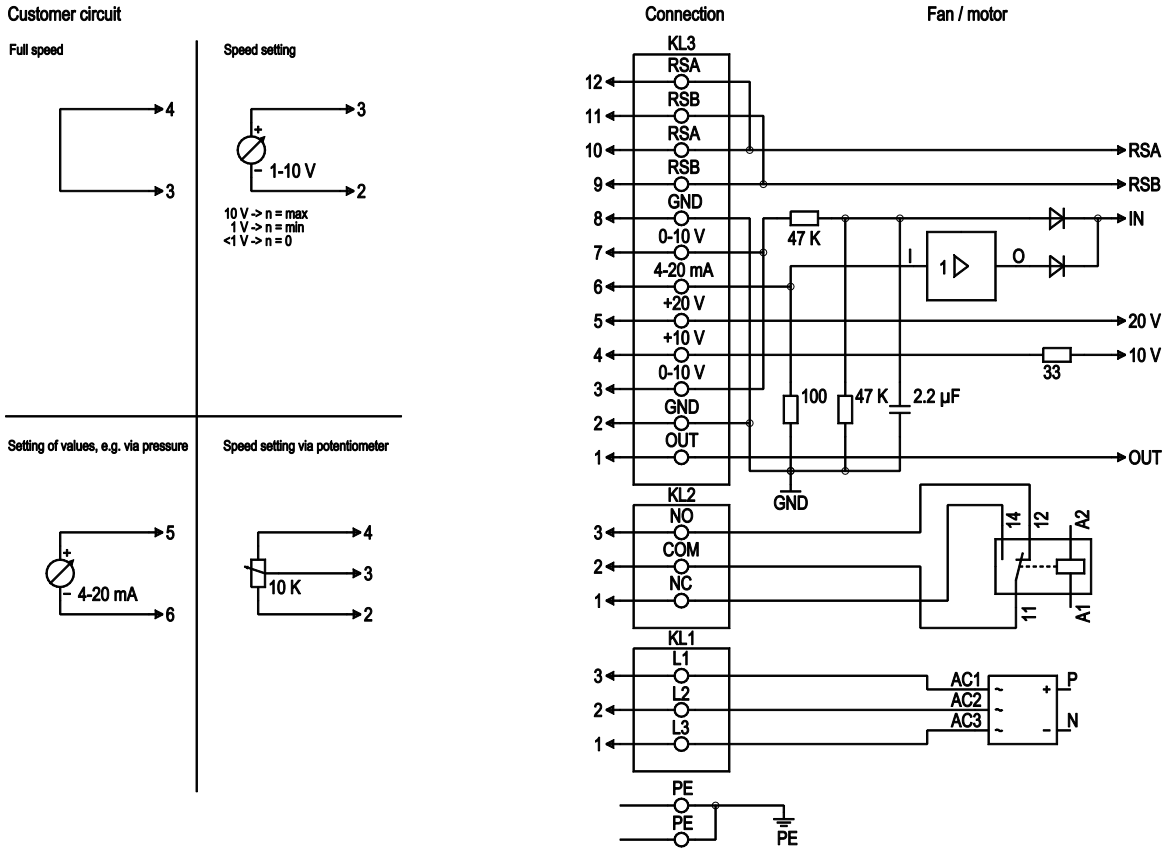
1	Cable diameter: min. 4 mm, max. 10 mm; tightening torque: 4±0.6 Nm
2	Accessory part: Inlet nozzle 63071-2-4013 not included in delivery, other inlet nozzles on request
3	Depth of screw max. 25 mm
4	Tightening torque, terminal box cover 3.5±0.5 Nm

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Connection screen



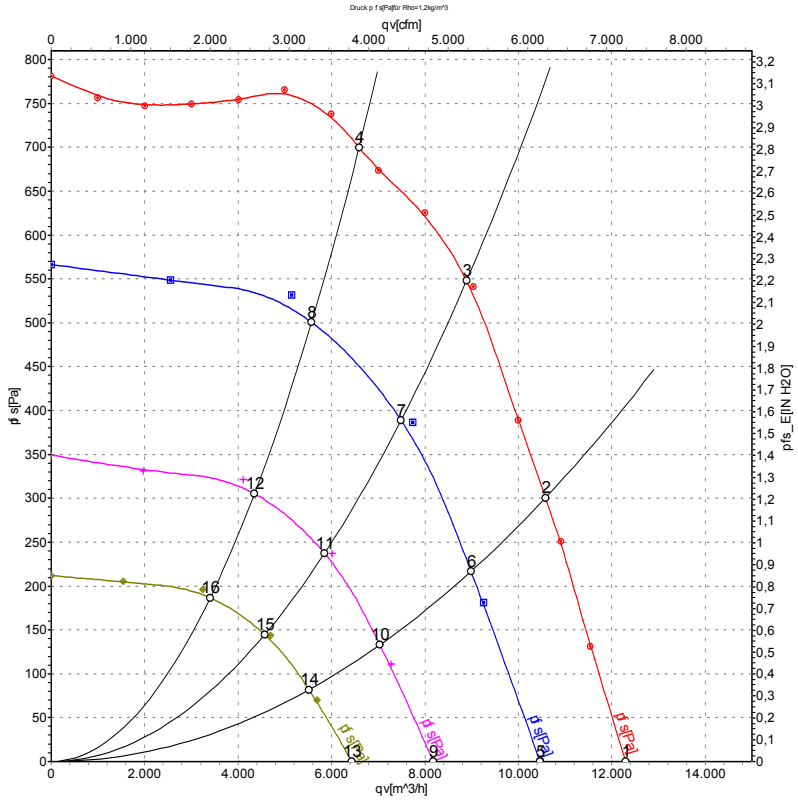
No.	Conn.	Designation	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, 50/60 Hz
KL2	1	NC	Floating status message contact, normally closed connection
KL2	2	COM	Floating status message contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status message contact, normally open connection
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of the current level control coefficient: 1 V equates to 10 % level control coefficient. 10 V equate to 100 % level control coefficient.
KL3	2, 8	GND	Reference mass for control interface, SELV
KL3	3, 7	0-10 V	Use control / actual value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3 %), max. 10 mA, supply voltage for ext. devices (e.g. potentiometers), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25 %/-10 %), max. 50 mA, supply voltage for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / actual value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBus, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBus, RSA, SELV

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Charts: Air flow 50 Hz



Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa
1	400	50	1350	1429	2.18	76	83	90	12300	0
2	400	50	1350	1983	3.03	74	81	88	10580	300
3	400	50	1350	2300	3.60	73	80	86	8890	550
4	400	50	1350	2225	3.39	73	80	86	6590	700
5	400	50	1150	842	1.32	72	79	85	10470	0
6	400	50	1150	1141	1.77	70	76	83	8985	218
7	400	50	1150	1320	2.03	68	75	81	7490	401
8	400	50	1150	1246	1.92	69	75	81	5575	508
9	400	50	900	420	0.74	65	72	78	8180	0
10	400	50	900	555	0.92	64	71	76	7035	134
11	400	50	900	642	1.04	63	70	75	5850	244
12	400	50	900	606	0.99	62	69	75	4350	311
13	400	50	700	213	0.43	60	68	73	6435	0
14	400	50	700	269	0.52	59	67	72	5520	83
15	400	50	700	304	0.58	58	67	73	4570	148
16	400	50	700	288	0.55	55	63	69	3400	190

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
qv = Air flow · p_{fs} = Pressure increase

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