R3G560-AH32-61

EC centrifugal fan - Plug fan

backward curved, single inlet

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**R3G560-AH32-61**
Motor	**M3G150-IF**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
State		prelim.
Speed	min^{-1}	1580
Power input	W	3550
Current draw	A	5.5
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = max. load · me = max. efficiency · fa = running at free air · cs = customer specs · cu = customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive integrated	Integrated
Specific ratio*	1,01

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}		61	53,2	57,2
Efficiency grade N		65,8	58	62
Power input P_{ed}	kW	3,51		
Air flow q_v	m^3/h	9815		
Pressure increase p_{fs}	Pa	748		
Speed n	min^{-1}	1590		

Data established at point of optimum efficiency

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Technical features

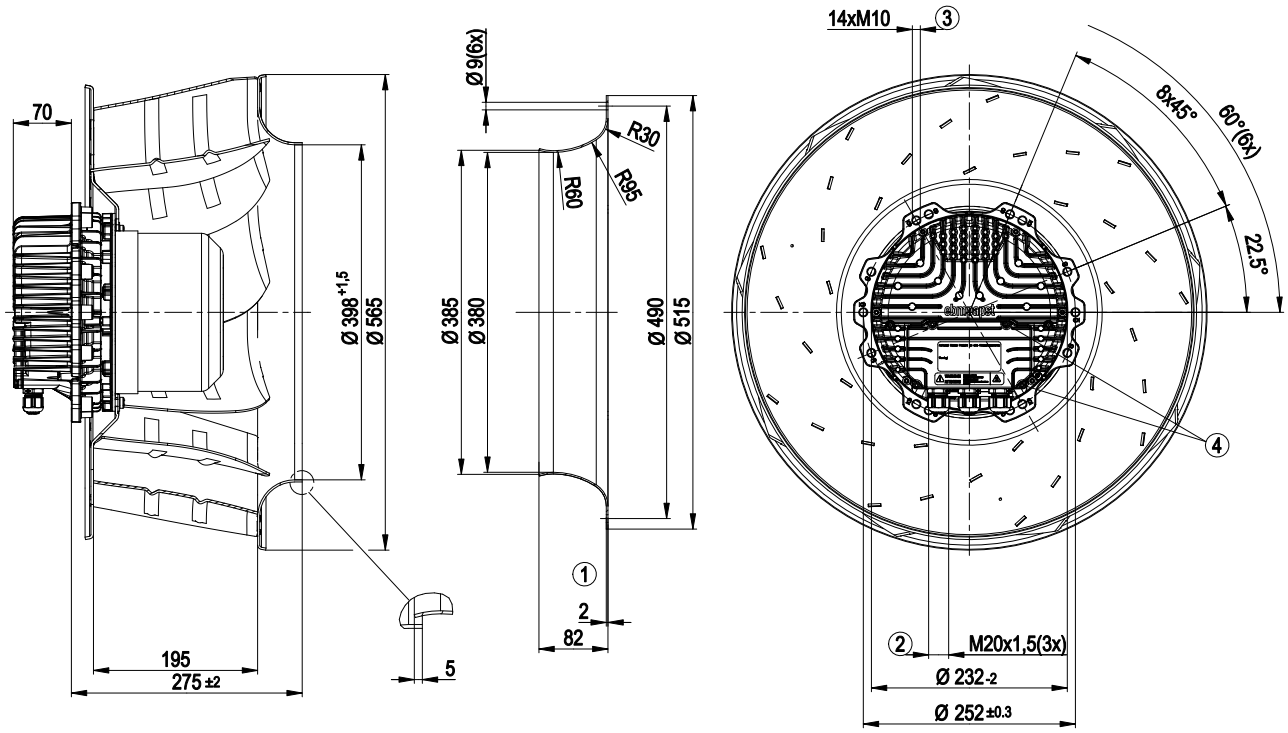
Mass	28 kg
Size	560 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Number of blades	9
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Leakage current	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE

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Product drawing



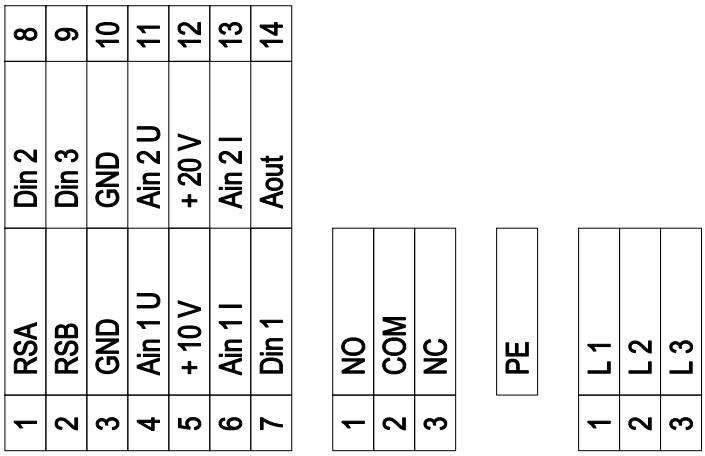
1	Accessory part: Inlet nozzle 63071-2-4013 not included in the standard scope of delivery, other inlet nozzles on request
2	Cable diameter: min. 6 mm; max. 12 mm; tightening torque: 4±0.6 Nm
3	Depth of screw max. 25 mm
4	Tightening torque of terminal box cover 3.5±0.5 Nm

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Connection screen



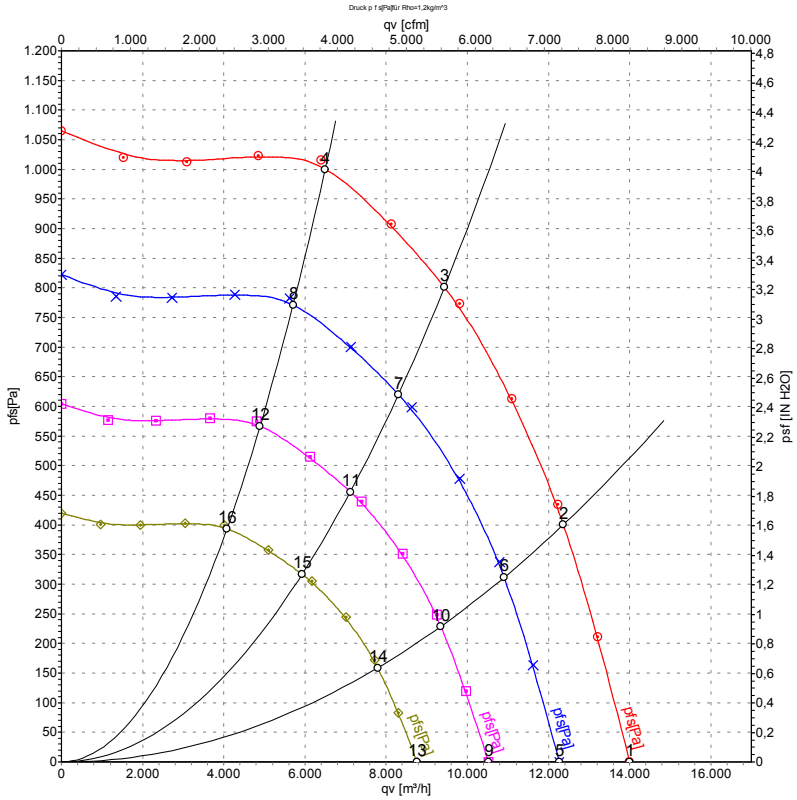
No.	Pin	Signal	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / 2 A (AC1)
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS485; RSA; MODBUS RTU
KL 3	2	RSB	Bus connection RS485; RSB; MODBUS RTU
KL 3	3 / 10	GND	Signal ground for control interface KL3
KL 3	4	Ain1 U	Analogue input 1 (set value); 0-10 V; Ri= 100 kΩ; parametrisable curves; only usable as alternative to input Ain1 I
KL 3	5	+ 10 V	Fixed voltage output 10 VDC; + 10 V +/-3%; max. 10 mA; short circuit proof; power supply for ext. devices (e.g. potentiometer)
KL 3	6	Ain1 I	Analogue input 1 (set value); 4-20 mA; Ri= 100 Ω; parametrisable curves; only usable as alternative to input Ain1 U
KL 3	7	Din1	Digital input 1: enabling of electronics; enabling: open pin or applied voltage 5 to 50 VDC; disabling: bridge to GND or applied voltage < 1 VDC; reset function: triggers software reset after a level change to <1 V
KL 3	8	Din2	Digital input 2: parameter set switch 1/2; according to EEPROM setting, the valid/used parameter set is selectable per BUS or per digital input DIN2. Parameter set 1: open pin or applied voltage 5 to 50 VDC; parameter set 2: bridge to GND or applied voltage < 1 VDC
KL 3	9	Din3	Digital input 3: Control characteristic of the integrated controller; according to EEPROM setting, the control characteristic of the integrated controller is normally/inversely selectable per BUS or per digital input; normal: open pin or applied voltage 5 to 50 VDC (control deviation = actual sensor value - set value) inverse: bridge to GND or applied voltage < 1 VDC (control deviation = set value - actual sensor value)
KL 3	11	Ain2 U	Analogue input 2; actual sensor value 0-10 V; Ri= 100 kΩ; parametrisable curve; only usable as alternative to input Ain2 I
KL 3	12	+ 20 V	Fixed voltage output 20 VDC; + 20 V +25/-10 %; max. 50 mA; short circuit proof; power supply for ext. devices (e.g. sensors)
KL 3	13	Ain2 I	Analogue input 2; actual sensor value 4-20 mA; Ri= 100 Ω; parametrisable curve; only usable as alternative to input Ain2 U
KL 3	14	Aout	Analogue output 0-10 V; max. 5 mA; output of the actual motor control factor (output voltage of electronics)/ of the actual motor speed; function selectable per bus; parametrisable curve.

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Charts: Air flow 50 Hz



Measurement: LU-131904

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	Conn.	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}
		V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa
1	Y	400	50	1580	2369	3.93	83	90	96	14000	0
2	Y	400	50	1580	3165	5.17	79	86	93	12370	400
3	Y	400	50	1580	3550	5.50	75	83	89	9435	800
4	Y	400	50	1580	3276	5.29	76	84	90	6500	1000
5	Y	400	50	1400	1596	2.65	80	87	92	12270	0
6	Y	400	50	1400	2171	3.55	76	83	90	10900	315
7	Y	400	50	1400	2389	3.88	72	80	86	8300	622
8	Y	400	50	1400	2216	3.58	73	80	86	5710	778
9	Y	400	50	1200	1005	1.67	76	83	89	10520	0
10	Y	400	50	1200	1367	2.24	72	79	86	9345	232
11	Y	400	50	1200	1504	2.44	68	76	82	7115	457
12	Y	400	50	1200	1395	2.25	69	77	82	4890	571
13	Y	400	50	1000	582	0.96	72	78	84	8765	0
14	Y	400	50	1000	791	1.29	67	75	81	7790	161
15	Y	400	50	1000	870	1.41	63	71	78	5930	317
16	Y	400	50	1000	808	1.30	65	72	78	4075	397

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