W3G800-CF16-85

EC axial fan

sickled blades (S series)

with full round nozzle

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Nominal data

Type	**W3G800-CF16-85**
Motor	**M3G150-NA**

Phase		3~
Nominal voltage	VAC	200
Nominal voltage range	VAC	200 .. 240
Frequency	Hz	50/60
Type of data definition		fa
Speed (rpm)	min^{-1}	1430
Power input	W	2700
Current draw	A	8.5
Max. back pressure	Pa	320
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

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Technical features

Mass	56.5 kg
Size	800 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Die-cast aluminium, coated in black
Material of wall ring	Sheet steel, galvanised and plastic-coated in white aluminium (RAL 9006)
Material of guard grille	Steel, galvanised and plastic-coated in white aluminium (RAL 9006)
Number of blades	5
Blade angle	-5°
Direction of air flow	"A"
Direction of rotation	Counter-clockwise, seen on rotor
Type of protection	IP 55
Insulation class	"F"
Humidity (F)/environmental protection class (H)	H2+
Note ambient temperature	Occasional start-up between -40°C and -25°C is permissible. For continuous operation at ambient temperatures below -25°C (e.g. refrigeration applications) we recommend our fan version with special low-temperature bearings.
Max. permissible ambient motor temp. (transp./ storage)	+ 80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-4 (industrial environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA

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Leakage current (meas. network acc. IEC 60990, fig.4, TN sys.); normal operation	<= 3.5 mA
Leakage current (meas. network acc. IEC 60990, fig.4, TN sys.); loss of phase	<= 3.5 mA
Leakage current (measured with TrueRMS amperemeter); normal operation	< 6 mA
Leakage current (measured with TrueRMS amperemeter); loss of phase	< 6 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	C22.2 Nr.77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730

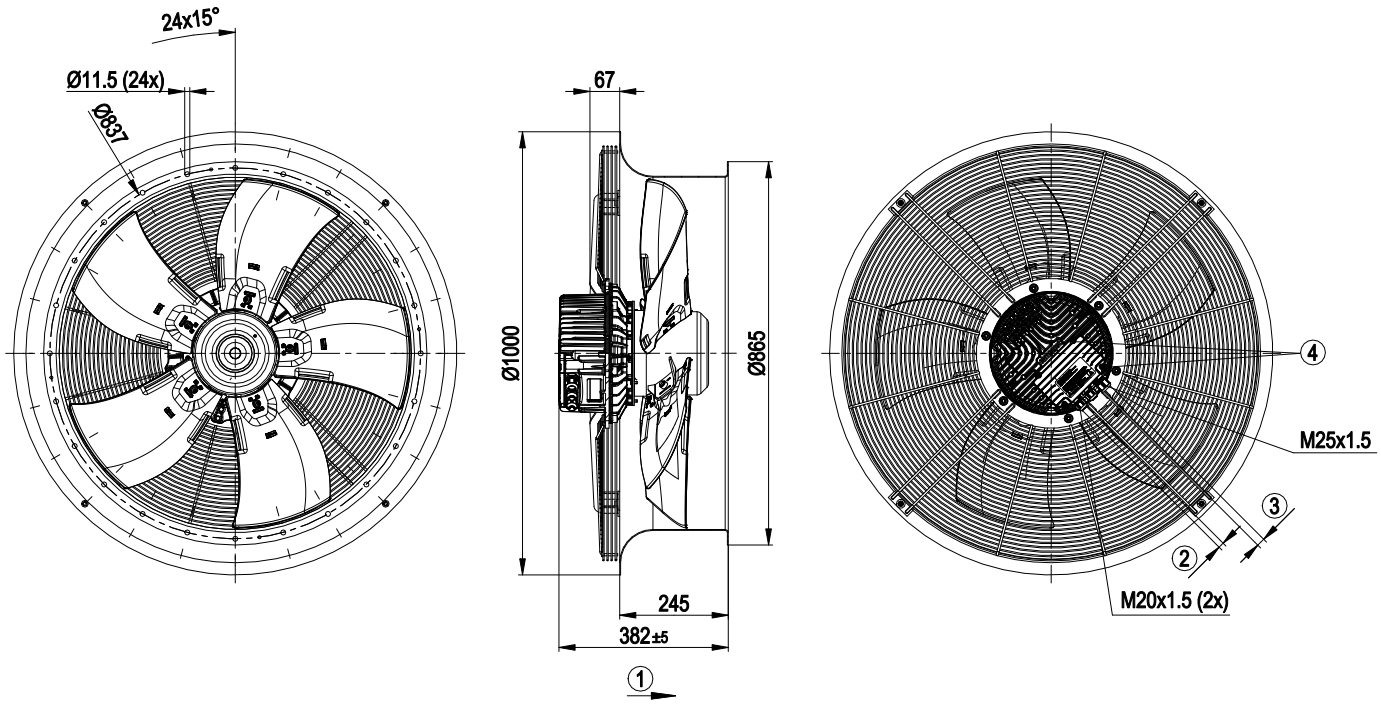
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Product drawing



1	Direction of air flow "A"
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4±0.6 Nm
3	Cable diameter min. 9 mm, max. 16 mm, tightening torque 6±0.9 Nm
4	Tightening torque 3.5±0.5 Nm

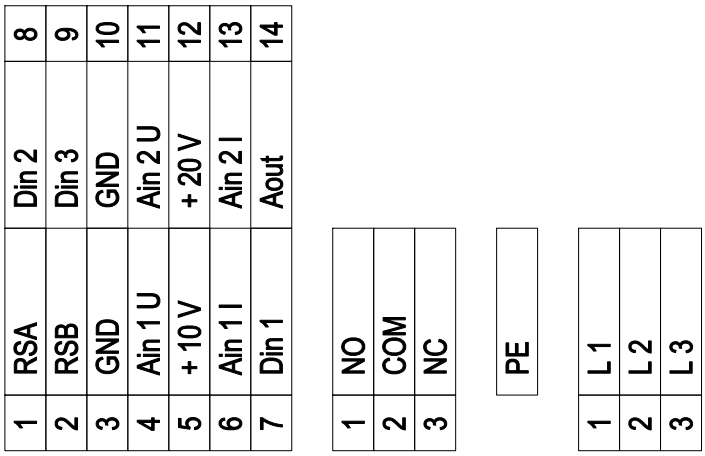
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Connection screen



No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~200-240 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~200-240 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~200-240 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Signal ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain1; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer), SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: parameter set switch 1/2, according to EEPROM setting, the valid/used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: open pin or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: controller function of integrated controller, according to EEPROM setting, the controller function of the integrated controller is normally/inversely selectable per bus or per digital input normal: open pin or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV

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No.	Conn.	Designation	Function / assignment
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV

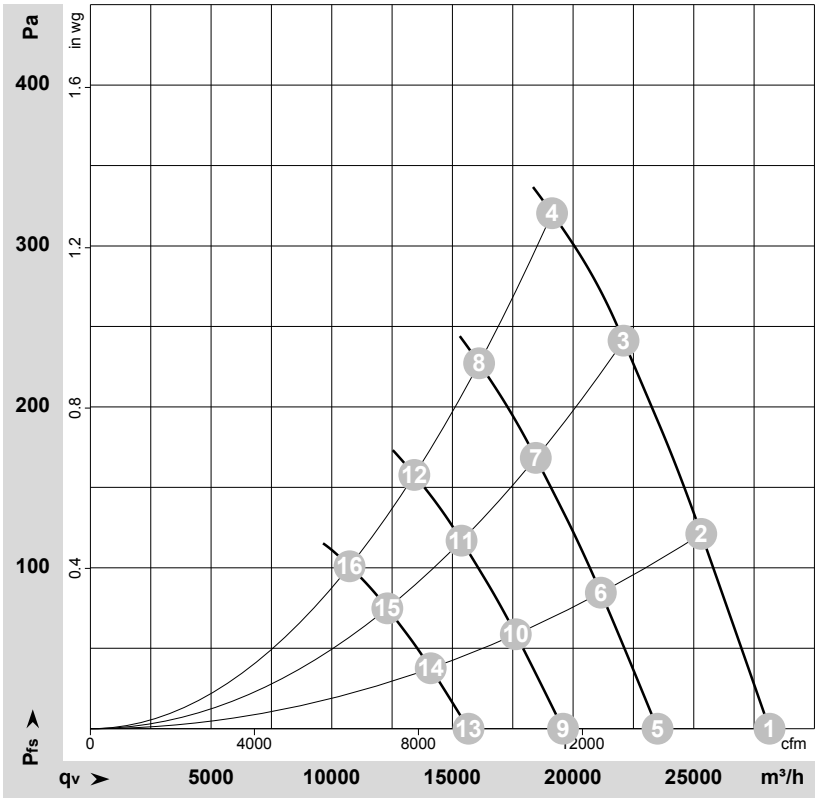
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Charts: Air flow 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-179501-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	inH2O
1	200	50	1430	2700	8.50	84	90	90	28140	0	16565	0.00
2	200	50	1430	3208	9.81	84	90	89	25310	120	14895	0.48
3	200	50	1430	3769	11.51	83	89	89	22090	240	13000	0.96
4	200	50	1430	4014	12.29	84	90	90	19130	320	11260	1.28
5	200	50	1200	1581	4.90	80	86	85	23500	0	13830	0.00
6	200	50	1200	1872	5.72	79	85	85	21150	85	12450	0.34
7	200	50	1200	2197	6.71	78	85	84	18455	168	10860	0.67
8	200	50	1200	2395	7.33	79	86	85	16105	228	9480	0.92
9	200	50	1000	915	2.84	75	81	81	19585	0	11525	0.00
10	200	50	1000	1083	3.31	74	80	80	17625	59	10375	0.24
11	200	50	1000	1272	3.88	74	80	80	15380	117	9050	0.47
12	200	50	1000	1386	4.24	75	81	81	13420	158	7900	0.63
13	200	50	800	468	1.45	69	76	75	15665	0	9220	0.00
14	200	50	800	555	1.70	69	75	75	14100	38	8300	0.15
15	200	50	800	651	1.99	68	75	74	12305	75	7240	0.30
16	200	50	800	710	2.17	69	75	75	10740	101	6320	0.41

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
q_V = Air flow · p_{fs} = Pressure increase

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