# Operating instructions

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## 1. SAFETY REGULATIONS AND INFORMATION

Read these operating instructions carefully before starting work on the device. Observe the following warnings to prevent malfunctions or danger to persons.
These operating instructions are to be regarded as part of the device. The device is only to be sold or passed on together with the operating instructions.
These operating instructions may be duplicated and distributed to inform about potential dangers and their prevention.

### 1.1 Hazard levels for warnings

These operating instructions use the following hazard levels to indicate potentially hazardous situations and important safety regulations:



**DANGER**
Indicates an imminently hazardous situation which will result in death or serious injury if the specified actions are not taken. Compliance with the instructions is imperative.

**WARNING**
Indicates a potentially hazardous situation which can result in death or serious injury if the specified actions are not taken. Exercise extreme caution while working.

**CAUTION**
Indicates a potentially hazardous situation which can result in minor or moderate injury or damage to property if the specified actions are not taken.

**NOTE**
A potentially harmful situation can occur and, if not avoided, can lead to property damage.

### 1.2 Staff qualifications

The device may only be transported, unpacked, installed, operated, maintained and otherwise used by suitably qualified, trained and authorized technical staff.
Only authorized specialists are permitted to install the device, to carry out a test run and to perform work on the electrical installation.

### 1.3 Basic safety rules

The safety hazards associated with the device must be assessed again following installation in the final product.
Note the following when working on the device:

⇒ Do not perform any modifications, additions or conversions on the device without the approval of ebm-papst.

### 1.4 Voltage

⇒ Check the device's electrical equipment at regular intervals; see Chapter 6.2 Safety inspection.

⇒ Replace loose connections and defective cables immediately.



**DANGER**
**Electrically charged device**
Risk of electric shock

→ When working on an electrically charged device, stand on a rubber mat.

**WARNING**
**Live terminals and connections even with device switched off**
Electric shock

Translation of the original operating instructions

→ Wait five minutes after disconnecting the voltage at all poles before opening the device.

**CAUTION**
**In the event of a fault, the rotor and the impeller will be energized**
The rotor and the impeller have basic insulation.

→ Do not touch the rotor and impeller once installed.

**CAUTION**
**If control voltage or a stored speed set value is applied, the motor will restart automatically, e.g. after a power failure.**
Risk of injury

→ Keep out of the device danger zone.

→ When working on the device, switch off the line voltage and ensure that it cannot be switched back on.

→ After working on the device, remove any tools or other objects from the device.

### 1.5 Safety and protective features

**DANGER**
**Protective device missing and protective device not functioning**
Without a protective device there is a risk of serious injury, for instance if the hands reach or are sucked into the device during operation.

→ Operate the device only with a fixed protective device and guard grille.# The fixed protective device must be able to withstand the kinetic energy of a fan blade that becomes detached at maximum speed. There must not be any gaps which it is possible to reach into with the fingers, for example.

→ The device is a built-in component. As the operator, you are responsible for ensuring that the device is secured adequately.

→ Stop the device immediately if you notice a missing or ineffective protective device.

### 1.6 Electromagnetic radiation

Interference from electromagnetic radiation is possible, e.g. in conjunction with open- and closed-loop control devices.
If impermissible radiation levels occur following installation, appropriate shielding measures have to be taken by the user.

**NOTE**
**Electrical or electromagnetic interference after installing the device in customer equipment.**

→ Verify that the entire setup is EMC-compliant.

### 1.7 Mechanical movement

**DANGER**
**Rotating device**
Risk of injury to body parts coming into contact with the rotor or the impeller.

→ Secure the device against accidental contact.

→ Before working on the system/machine, wait until all parts have come to a standstill.

**DANGER**
**Ejected parts**
Missing protective devices may cause balancing weights or broken fan blades to be ejected and cause injuries.

→ Take appropriate safety measures.

**WARNING**
**Rotating device**
Long hair and dangling items of clothing, jewelry and the like can become entangled and be pulled into the device. Injuries can result.

→ Do not wear any loose-fitting or dangling clothing or jewelry while working on rotating parts.#Protect long hair with a cap.

### 1.8 Emissions

**WARNING**
**Depending on the installation and operating conditions, the sound pressure level may exceed 70 dB(A).**
Risk of noise-induced hearing loss

→ Take appropriate technical safety measures.

→ Protect operating personnel with appropriate safety equipment such as hearing protection.

→ Also observe the requirements of local agencies.

### 1.9 Hot surface

**CAUTION**
**High temperature on electronics housing**
Risk of burns

→ Ensure sufficient protection against accidental contact.

### 1.10 Storage

⇒ Store the device, partially or fully assembled, in a dry and weatherproof manner in the original packaging in a clean environment.

⇒ Protect the device against environmental effects and dirt until final installation.

⇒ We recommend storing the device for no longer than one year in order to guarantee trouble-free operation and the longest possible service life.

⇒ Even devices explicitly intended for outdoor use are to be stored as described prior to commissioning.

⇒ Maintain the storage temperature, see Chapter 3.6 Transport and storage conditions.

⇒ Make sure that all cable glands are fitted with dummy plugs.

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## 2. INTENDED USE

The device is exclusively designed as a built-in device for conveying air according to its technical data.
Any other usage above and beyond this does not conform with the intended purpose and constitutes misuse of the device.
Customer equipment must be capable of withstanding the mechanical and thermal stresses that can arise from this product. This applies for the entire service life of the equipment in which this product is installed.

**Intended use also includes**

- Using the device only in power systems with grounded neutral (TN/ TT power systems).
- Using the device only in stationary systems.
- Performing all maintenance work.
- conveying air at an ambient air pressure between 750 mbar and 1050 mbar.
- Using the device within the permitted ambient temperature range; see Chapter 3.6 Transport and storage conditions and Chapter 3.2 Nominal data.
- Operating the device with all protective devices.
- Following the operating instructions.

**Improper use**

In particular, operating the device in the following ways is prohibited and could be hazardous:

- Operating the device in an unbalanced state, e.g. due to dirt deposits or ice formation.
- Operation in medical equipment with a life-sustaining or life-support function.
- Operation with external vibrations.
- Conveying solids in the flow medium.
- Painting the device
- Connections (e.g. screws) coming loose during operation.
- Opening the terminal box during operation.
- Conveying air that contains abrasive particles.
- Conveying highly corrosive air, e.g. salt spray. Exception: devices designed for salt spray and correspondingly protected.
- Conveying air with high dust content, e.g. suctioning off sawdust.
- Operating the device close to flammable materials or components.
- Operating the device in an explosive atmosphere.
- Using the device as a safety component or to perform safety-related functions.
- Operation with completely or partially disassembled or manipulated protective devices.
- In addition, all applications not listed among the intended uses.

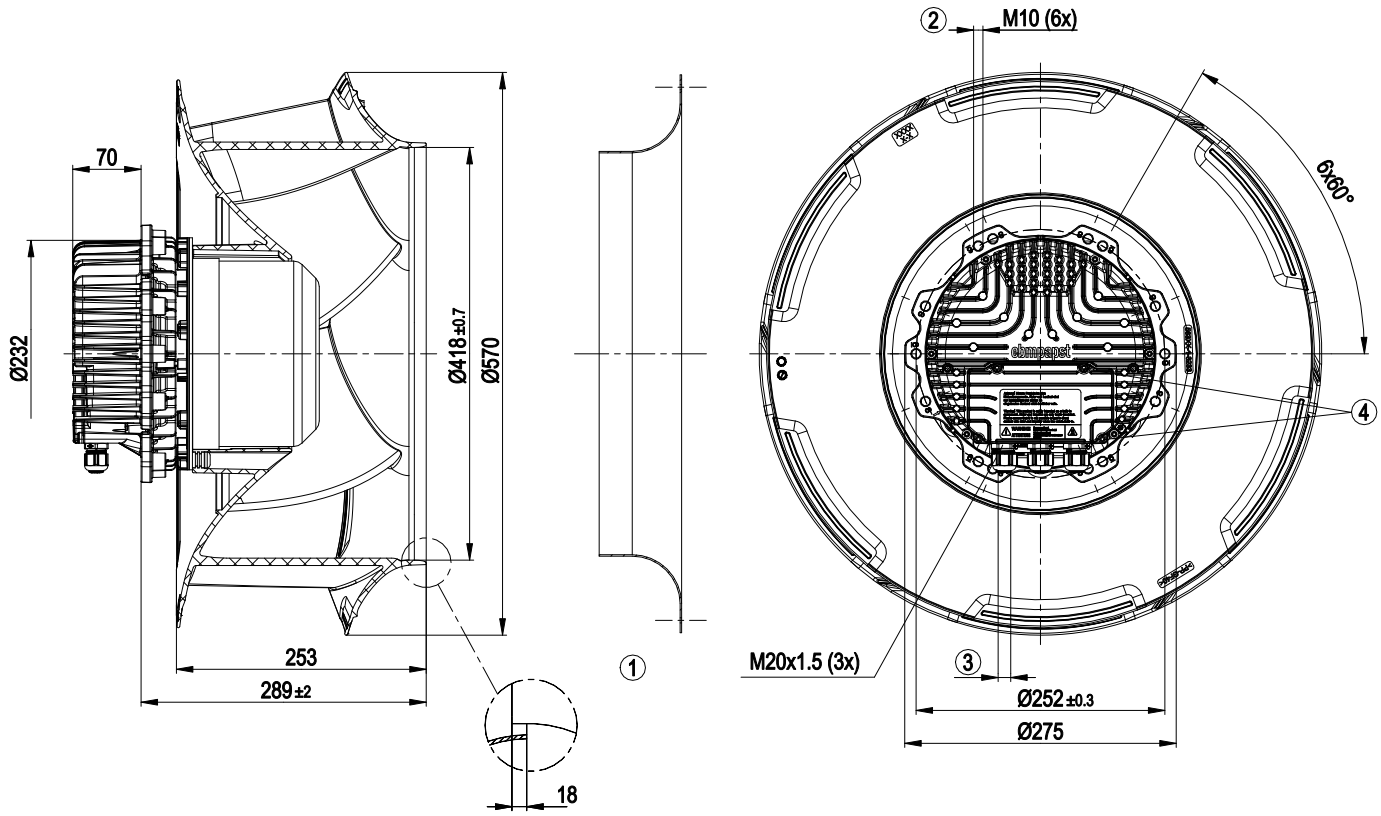
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## 3. TECHNICAL DATA

### 3.1 Product drawing




All dimensions in mm.

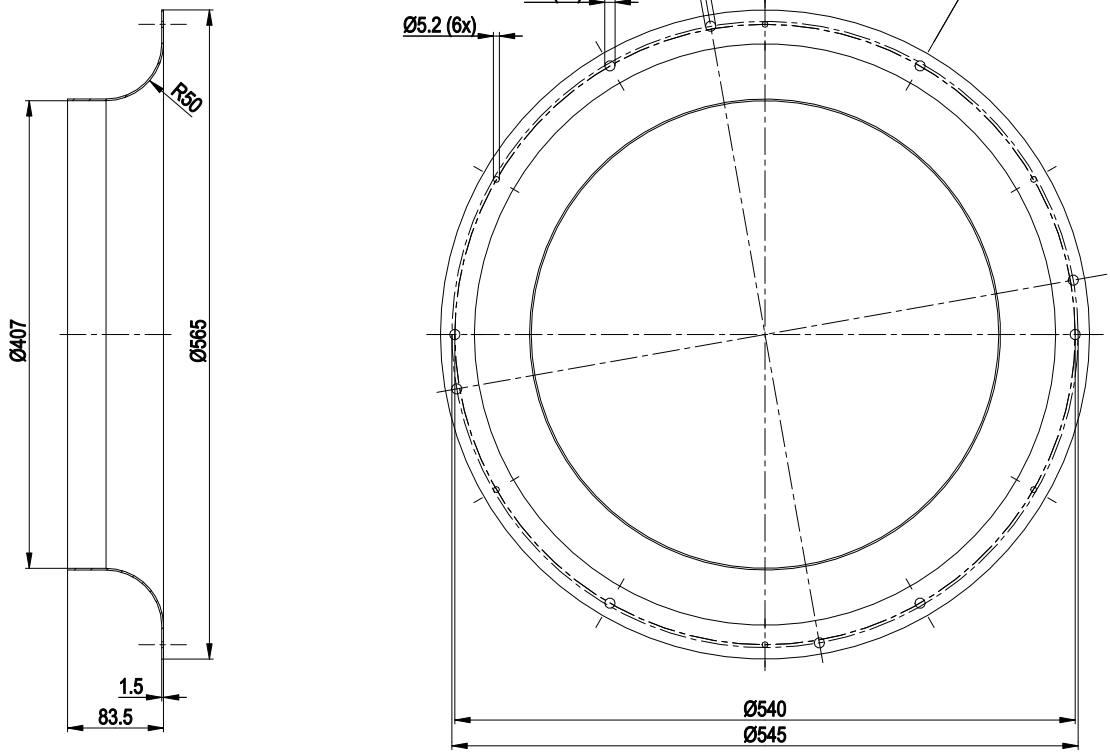
| | |
|---|---|
| 1 | Accessory part: inlet ring 54482-2-4013 not included in scope of delivery |
| 2 | Max. clearance for screw 25 mm |
| 3 | Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm |
| 4 | Tightening torque 3.5 ± 0.5 Nm |

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# Operating instructions




All dimensions in mm.

| | |
|---|---|
| | Accessory part: inlet ring 54482-2-4013 not included in scope of delivery |

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### 3.2 Nominal data

| | |
|---|---|
| **Motor** | M3G150-IF |

| | |
|---|---|
| **Phase** | 3~ |
| **Nominal voltage / VAC** | 400 |
| **Nominal voltage range / VAC** | 380 .. 480 |
| **Frequency / Hz** | 50/60 |

| | |
|---|---|
| **Method of obtaining data** | ml |
| **Speed / min$^{-1}$** | 1650 |
| **Power consumption / W** | 2900 |
| **Current draw / A** | 4.43 |
| **Min. ambient temperature / °C** | -25 |
| **Max. ambient temperature / °C** | 50 |

ml = Max. load · me = Max. efficiency · fa = Free air
cs = Customer specification · ce = Customer equipment

Subject to change

### 3.3 Data according to ErP Directive

| | Actual | Req. 2015 |
|---|---|---|
| **01 Overall efficiency $\eta_{es}$ / %** | 66.9 | 56.4 |
| **02 Measurement category** | A | |
| **03 Efficiency category** | Static | |
| **04 Efficiency grade N** | 72.5 | 62 |
| **05 Variable speed drive** | Yes | |
| **06 Year of manufacture** | The year of manufacture is specified on the product's rating label. | |
| **07 Manufacturer** | ebm-papst Mulfingen GmbH & Co. KG<br>Amtsgericht (court of registration) Stuttgart · HRA 590344<br>D-74673 Mulfingen | |
| **08 Type** | R3G560-RB32-10 | |
| **09 Power consumption $P_{ed}$ / kW** | 2.93 | |
| **09 Air flow $q_v$ / m³/h** | 9440 | |
| **09 Pressure increase total $p_{sf}$ / Pa** | 710 | |
| **10 Speed n / min$^{-1}$** | 1655 | |
| **11 Specific ratio*** | 1.01 | |
| **12 Recycling/disposal** | Information on recycling and disposal is provided in the operating instructions. | |
| **13 Maintenance** | Information on installation, operation and maintenance is provided in the operating instructions. | |
| **14 Additional components** | Components used to calculate the energy efficiency that are not apparent from the measurement category are detailed in the CE declaration. | |

* Specific ratio = 1 + $p_{fs}$ / 100 000 Pa

Data obtained at optimum efficiency level. The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

### 3.4 Technical description

| | |
|---|---|
| **Weight** | 27.8 kg |
| **Fan size** | 560 mm |
| **Rotor surface** | Painted black |
| **Electronics housing material** | Die-cast aluminum |
| **Impeller material** | PP plastic |
| **Number of blades** | 6 |
| **Direction of rotation** | Clockwise, viewed toward rotor |
| **Degree of protection** | IP55 |
| **Insulation class** | "F" |
| **Moisture (F) / Environmental (H) protection class** | F4-1 |
| **Installation position** | Shaft horizontal or rotor on bottom |
| **Condensation drainage holes** | On rotor side |
| **Mode** | S1 |
| **Motor bearing** | Ball bearing |
| **Technical features** | - Output 10 VDC, max. 10 mA<br>- Output 20 VDC, max. 50 mA<br>- Output for slave 0-10 V<br>- Operation and alarm display<br>- Input for sensor 0-10 V or 4-20 mA<br>- External 24 V input (parameter setting)<br>- External release input<br>- Alarm relay<br>- Integrated PID controller<br>- Motor current limitation<br>- PFC, passive<br>- RS-485 MODBUS-RTU<br>- Soft start<br>- Control input 0-10 VDC / PWM<br>- Control interface with SELV potential safely disconnected from the mains<br>- Thermal overload protection for electronics/motor<br>- Line undervoltage / phase failure detection |
| **Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)** | <= 3.5 mA |
| **Leakage current (measuring circuit according to IEC 60990, Fig. 4, TN system); normal operation** | <= 3.5 mA |
| **Leakage current (measured with TrueRMS ammeter); normal operation** | < 6 mA |
| **Electrical hookup** | Via terminal box |
| **Motor protection** | Reverse polarity and locked-rotor protection |
| **Protection class** | I (with customer connection of protective earth) |
| **Conformity with standards** | EN 61800-5-1; CE |

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| | |
|---|---|
| **Approval** | C22.2 No.77 + CAN/CSA-E60730-1;<br>UL 1004-7 + 60730 |

With regard to cyclic speed loads, note that the rotating parts of the device are designed for a maximum of one million load cycles. If you have special questions, consult ebm-papst for support.

### 3.5 Mounting data

⇒ Secure the screws against unintentional loosening (e.g. use self-locking screws).

| | |
|---|---|
| **Strength class of screws** | 8.8 |

Any further mounting data required can be taken from the product drawing.

### 3.6 Transport and storage conditions

⇒ Use the device in accordance with its degree of protection.

| | |
|---|---|
| **Max. permitted ambient temp. for motor (transport/ storage)** | +80 °C |
| **Min. permitted ambient temp. for motor (transport/ storage)** | -40 °C |

### 3.7 Electromagnetic compatibility

| | |
|---|---|
| **EMC immunity to interference** | According to EN 61000-6-2 (industrial environment) |
| **EMC interference emission** | According to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used equipment with a total rated power greater than 1 kW |

If several devices are switched in parallel on the supply side so that the line current of the arrangement is in the range of 16-75 A, then this arrangement conforms to IEC 61000-3-12 provided that the short-circuit power $S_{sc}$ at the connection point of the customer system to the public power system is greater than or equal to 120 times the rated output of the arrangement. It is the responsibility of the installation engineer or operator/ owner of the device to ensure, if necessary after consultation with the network operator, that this device is only connected to a connection point with a $S_{sc}$ value that is greater than or equal to 120 times the rated output of the arrangement.

## 4. CONNECTION AND STARTUP

### 4.1 Mechanical connection

**CAUTION**
**Cutting and crushing hazard when removing fan from packaging**

→ Carefully remove the device from its packaging, by the fan impeller. Strictly avoid shocks.

→ Wear safety shoes and cut-resistant safety gloves.

**CAUTION**
**Heavy load when unpacking device**
Risk of physical injury, such as back injuries.

→ Two people should work together to remove the device from its packaging.

⇒ Check the device for transport damage. Damaged devices are not to be installed.

⇒ Install the undamaged device in accordance with your application.

**CAUTION**
**Possible damage to the device**
If the device slips during installation, serious damage can result.

→ Ensure that the device is securely positioned at its place of installation until all fastening screws have been tightened.

### 4.2 Electrical connection

**DANGER**
**Voltage on the device**
Electric shock

→ Always connect a protective earth first.

→ Check the protective earth.

**DANGER**
**Faulty insulation**
Risk of fatal injury from electric shock

→ Use only cables that meet the specified installation regulations for voltage, current, insulation material, capacity, etc.

→ Route cables so that they cannot be touched by any rotating parts.

**DANGER**
**Electrical charge (>50 µC) between phase conductor and protective earth connection after switching off supply with multiple devices connected in parallel.**
Electric shock, risk of injury

→ Ensure sufficient protection against accidental contact. Before working on the electrical hookup, short the supply and PE connections.

**CAUTION**
**Voltage**
The fan is a built-in component and has no disconnecting switch.

→ Only connect the fan to circuits that can be switched off with an all-pole disconnection switch.

→ When working on the fan, secure the system/machine in which the fan is installed so as to prevent it from being switched back on.

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**NOTE**
**Device malfunctions possible**
Route the device's control lines separately from the supply line.
→ Maintain the greatest possible clearance.
Recommendation: clearance > 10 cm (separate cable routing)

**NOTE**
**Water ingress into wires or cables**
Water ingress at the customer end of the cable can damage the device.
→ Make sure the end of the cable is connected in a dry environment.

Only connect the device to circuits that can be switched off with an all-pole disconnection switch.

#### 4.2.1 Requirements

⇒ Check whether the data on the nameplate match the connection data.

⇒ Before connecting the device, make sure the power supply matches the device voltage.

⇒ Only use cables designed for the current level indicated on the nameplate.
For determining the cross-section, note the sizing criteria according to EN 61800-5-1. The protective earth must have a cross-section equal to or greater than that of the phase conductor.
We recommend the use of 105 °C cables. Ensure that the minimum cable cross-section is at least
AWG 26 / 0.13 mm².

**Ground conductor contact resistance according to EN 61800-5-1**

Compliance with the impedance specifications according to EN 61800-5-1 for the protective earth connection circuit must be verified in the end application.
Depending on the circumstances of installation, it may be necessary to connect an additional protective earth conductor to the extra protective earth terminal on the device.
The protective earth terminal is on the housing and has a ground conductor symbol and a bore hole.

#### 4.2.2 Supply connection and fuses

Assignment of supply cable cross-sections and their required fuses (line protection only, no equipment protection).

| Nominal voltage | Fuse | | Automatic circuit breaker | Cable cross-section | Cable cross-section |
|---|---|---|---|---|---|
| | VDE | UL | VDE | mm² | *AWG |
| 3/PE AC 380-480 VAC | 16 A | 15 A | C16A | 1.5 | 16 |
| 3/PE AC 380-480 VAC | 20 A | 20 A | C20A | 2.5 | 14 |
| 3/PE AC 380-480 VAC | 25 A | 25 A | C25A | 4.0 | 12 |
| 3/PE AC 380-480 VAC | 32 A | 30 A | C32A | 6.0 | 10 |

* AWG = American Wire Gauge

#### 4.2.3 Reactive currents

Because of the EMC filter integrated for compliance with EMC limits (interference emission and immunity to interference), reactive currents can be measured in the supply line even when the motor is at a standstill and the line voltage is switched on.

- The values are typically less than 250 mA.
- At the same time, the effective power in this operating state (operational readiness) is typically < 5 W.

#### 4.2.4 Residual current circuit breaker (RCCB)

Only universal residual current devices (type B or B+) are allowed. As with variable frequency drives, residual current devices cannot provide personal safety while operating the device.
When the device's power supply is switched on, pulsed charging currents from the capacitors in the integrated EMC filter can lead to the residual current devices tripping without delay. We recommend the use of residual current circuit breakers with a trip threshold of 300 mA and delayed tripping (super-resistant, characteristic K).

#### 4.2.5 Leakage current

For asymmetrical power systems or if a phase fails, the leakage current can increase to a multiple of the nominal value.

#### 4.2.6 Locked-rotor protection

Due to the locked-rotor protection, the starting current (LRA) is equal to or less than the nominal current (FLA).

### 4.3 Connection in terminal box

#### 4.3.1 Preparing cables for connection

Only strip the cable as far as necessary, ensuring that the cable gland is sealed and there is no strain on the connections. For tightening torques, see Chapter 3.1 Product drawing.

**NOTE**
**Tightness and strain relief are dependent on the cable used.**
→ This must be checked by the user.

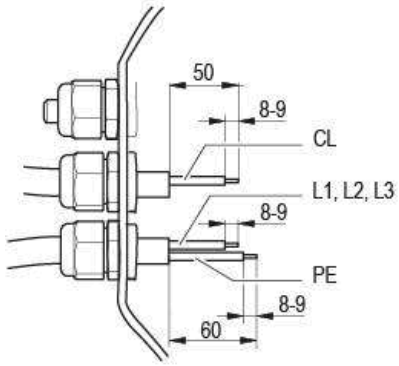



*Fig. 1: Recommended stripped lengths in mm (inside terminal box)*
*Legend: CL = control lines*

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#### 4.3.2 Connecting wires to terminals

**WARNING**
**Live terminals and connections even with device switched off**
Electric shock
→ Wait five minutes after disconnecting the voltage at all poles before opening the device.

⇒ Remove the cap from the cable gland.

Only remove caps where cables are fed in.

⇒ Equip the cable glands with the seals provided in the terminal box.

⇒ Route the wire(s) (not included in scope of delivery) into the terminal box.

⇒ First connect the "PE" (protective earth).

⇒ Connect the wires to the corresponding terminals.

Use a screwdriver to do so.
When connecting, ensure that no wire ends fan out.

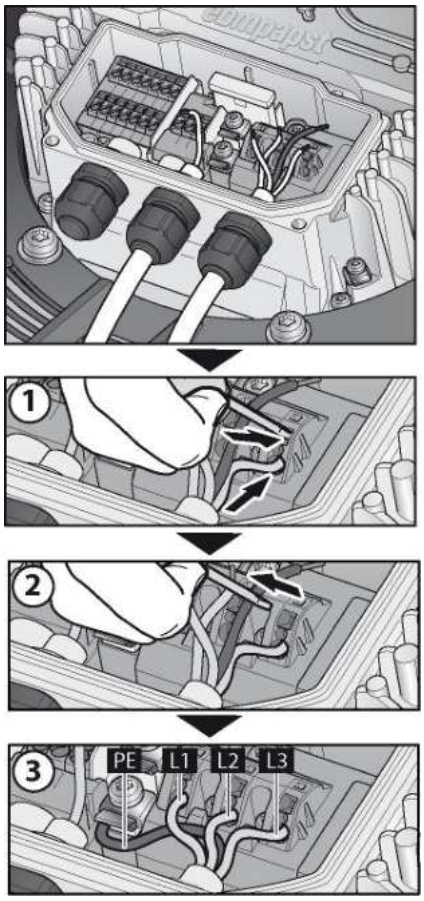



*Fig. 2: Connecting wires to terminals*

⇒ Seal the terminal box.

#### 4.3.3 Cable routing

Water must be prevented from reaching the cable gland along the cable. When routing the cable, make sure that the cable glands are located at the bottom. The cables must always be routed downward.

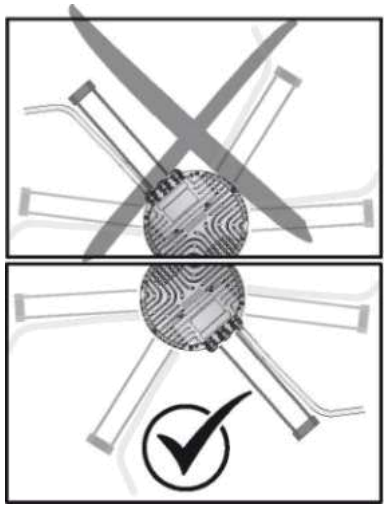


*Fig. 3: Cable routing for fans installed upright.*

### 4.4 Factory settings

Factory settings made for the device by ebm-papst.

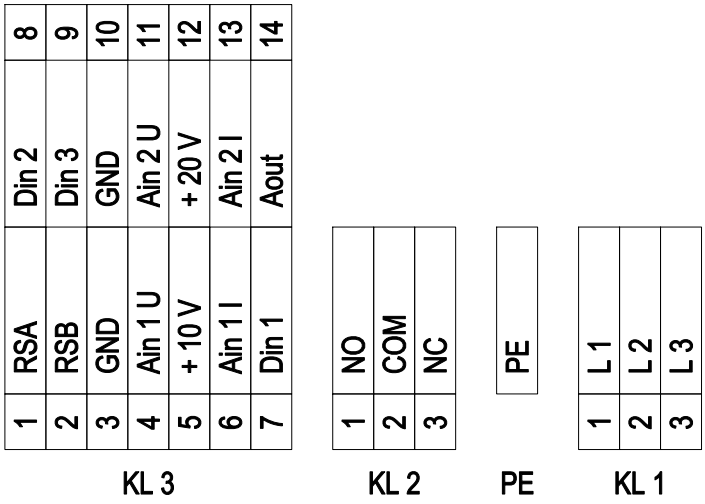
| | |
|---|---|
| **Mode parameter set 1** | Speed control |
| **Mode parameter set 2** | Speed control |
| **Fan/device address** | 01 |
| **Max. PWM / %** | 100 |
| **Min. PWM / %** | 5 |
| **Save set value to EEPROM** | Yes |
| **Set value requirement** | Analog (linear) |
| **Direction of action parameter set 1** | Positive (heating) |
| **Direction of action parameter set 2** | Positive (heating) |

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### 4.5 Connection diagram




| No. | Conn. | Designation | Function/assignment |
|---|---|---|---|
| **KL 1** | **1** | **L1** | Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz |
| **KL 1** | **2** | **L2** | Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz |
| **KL 1** | **3** | **L3** | Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz |
| **PE** | | **PE** | Ground connection, PE connection |
| **KL 2** | **1** | **NO** | Status relay, floating status contact; make for failure |
| **KL2** | **2** | **COM** | Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA |
| **KL2** | **3** | **NC** | Status relay, floating status contact; break for failure |
| **KL 3** | **1** | **RSA** | Bus connection RS485, RSA, MODBUS-RTU; SELV |
| **KL 3** | **2** | **RSB** | Bus connection RS485, RSB, MODBUS-RTU; SELV |
| **KL 3** | **3 / 10** | **GND** | Reference ground for control interface; SELV |
| **KL 3** | **4** | **Ain1 U** | Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV |
| **KL 3** | **5** | **+ 10 V** | Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV |
| **KL 3** | **6** | **Ain1 I** | Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1U; SELV |
| **KL 3** | **7** | **Din1** | Digital input 1: enable electronics,<br>enable: pin open or applied voltage 5-50 VDC<br>disable: bridge to GND or applied voltage < 1 VDC<br>reset function: triggers software reset after a level change to < 1 VDC; SELV |
| **KL 3** | **8** | **Din2** | Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2.<br>Parameter set 1: pin open or applied voltage 5-50 VDC<br>Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV |
| **KL 3** | **9** | **Din3** | Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input<br>normal: pin open or applied voltage 5-50 VDC<br>inverse: bridge to GND or applied voltage < 1 VDC; SELV |
| **KL 3** | **11** | **Ain2 U** | Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I; SELV |
| **KL 3** | **12** | **+ 20 V** | Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV |
| **KL 3** | **13** | **Ain2 I** | Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2U; SELV |
| **KL 3** | **14** | **Aout** | Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV |

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### 4.6 Checking connections

⇒ Ensure isolation from supply (all phases).
⇒ Make sure a restart is impossible
⇒ Check the cables for proper fit.
⇒ Screw the terminal box cover back on again. Terminal box tightening torque, see Chapter 3.1 Product drawing.
⇒ Route the cables in the terminal box so that the terminal box cover closes without resistance.
⇒ Use all screw plugs. Insert the screws by hand to avoid damage to the threads.
⇒ Make sure the terminal box is completely closed and sealed and that all screws and cable glands have been properly tightened.

### 4.7 Switching on the device

The device may only be switched on if it has been installed properly and in accordance with its intended use, including the required safety mechanisms and professional electrical hookup. This also applies for devices which have already been equipped with plugs and terminals or similar connectors by the customer.



**WARNING**
**Hot motor housing**
Risk of fire
→ Ensure that no combustible or flammable materials are located close to the fan.

⇒ Before switching on, check the device for visible external damage and make sure the protective devices are functional.
⇒ Check the fan's air flow paths for foreign matter and remove any foreign matter found.
⇒ Apply the nominal supply voltage.
⇒ Start the device by changing the input signal.

### 4.8 Switching off the device

Switching off the device during operation:
⇒ Switch off the device via the control input.
⇒ Do not switch the motor (e.g. in cyclic operation) on and off via power supply.

Switching off the device for maintenance:
⇒ Switch off the device via the control input.
⇒ Do not switch the motor (e.g. in cyclic operation) on and off via power supply.
⇒ Disconnect the device from the power supply.
⇒ When disconnecting, be sure to disconnect the ground connection last.

## 5. INTEGRATED PROTECTIVE FEATURES

The integrated protective functions cause the motor to switch off automatically in the event of the faults described in the table.

| **Fault** | **Safety feature description/ function** |
|---|---|
| Rotor position detection error | An automatic restart follows. |
| Blocked rotor | ⇒ After the blockage is removed, the motor restarts automatically. |
| Line undervoltage (line voltage outside of permitted nominal voltage range) | ⇒ If the line voltage returns to permitted values, the motor restarts automatically. |
| Phase failure | A phase of the supply voltage fails for at least 5 s.<br>⇒ When all phases are correctly supplied again, the motor automatically restarts after 10-40 s. |

## 6. MAINTENANCE, MALFUNCTIONS, POSSIBLE CAUSES AND REMEDIES

Do not perform any repairs on your device. Send the device to ebm-papst for repair or replacement.

**WARNING**
**Live terminals and connections even with device switched off**
Electric shock
→ Wait five minutes after disconnecting the voltage at all poles before opening the device.

**CAUTION**
**If control voltage or a stored speed set value is applied, the motor will restart automatically, e.g. after a power failure.**
Risk of injury
→ Keep out of the device danger zone.
→ When working on the device, switch off the line voltage and ensure that it cannot be switched back on.
→ After working on the device, remove any tools or other objects from the device.



If the device is out of use for over four months, we recommend switching it on for at least three hours at full speed to allow any condensation to evaporate and to move the bearings.

| **Malfunction/fault** | **Possible cause** | **Possible remedy** |
|---|---|---|
| **Impeller not running smoothly** | Imbalance in rotating parts | Clean the device; replace it if imbalance persists after cleaning. Make sure no weight clips are removed during cleaning. |
| **Motor not turning** | Mechanical blockage | Switch off, isolate from supply and remove mechanical blockage. |

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| | | |
|---|---|---|
| | Line voltage faulty | Check line voltage, restore power supply. Attention! The error message resets automatically. Device restarts automatically without warning. |
| | Faulty connection | Isolate from supply, correct connection; see connection diagram. |
| | Broken motor winding | Replace device |
| | Deficient cooling | Improve cooling. Let the device cool down. To reset the error message, switch off the line voltage for at least 25 s and then switch it on again. Alternatively, reset the error message by applying a control signal of < 0.5 V to Din1 or by shorting Din1 to GND. |
| | Ambient temperature too high | Reduce the ambient temperature. Let the device cool down. To reset the error message, switch off the line voltage for at least 25 s and then switch it on again. Alternatively, reset the error message by applying a control signal of < 0.5 V to Din1 or by shorting Din1 to GND. |
| | Impermissible point of operation (e.g. back pressure too high) | Correct the operating point. Let the device cool down. To reset the error message, switch off the line voltage for at least 25 s and then switch it on again. Alternatively, reset the error message by applying a control signal of < 0.5 V to Din1 or by shorting Din1 to GND. |

In the event of further malfunctions, contact ebm-papst.

## 6.1 Cleaning

**NOTE**
**Damage to the device during cleaning**
Malfunction possible

→ Do not clean the device using a high-pressure cleaner.# Do not use acid, alkali or solvent-based cleaning agents.

→ Do not use any pointed or sharp-edged objects for cleaning

## 6.2 Safety inspection

**NOTE**
**High-voltage test**
The integrated EMC filter has Y capacitors. The tripping current is exceeded when AC testing voltage is applied.

→ Test the device with DC voltage when you perform the legally required high-voltage test. The voltage to be used corresponds to the peak value of the AC voltage required by the standard.

| What to check | How to check | How often | What action? |
|---|---|---|---|
| Contact protection cover for intactness or damage | Visual inspection | At least every 6 months | Repair or replacement of device |
| Device for damage to blades and housing | Visual inspection | At least every 6 months | Replacement of device |
| Fastening the cables | Visual inspection | At least every 6 months | Fasten |
| Insulation of cables for damage | Visual inspection | At least every 6 months | Replace cables |
| Impeller for wear/deposits/ corrosion and damage | Visual inspection | At least every 6 months | Clean or replace impeller |
| Tightness of cable gland | Visual inspection | At least every 6 months | Retighten, replace if damaged |
| Condensation drainage holes for clogging, where necessary | Visual inspection | At least every 6 months | Open holes |

## 6.3 Disposal

For ebm-papst, environmental protection and resource preservation are top priority corporate goals.
ebm-papst operates an environmental management system which is certified in accordance with ISO 14001 and rigorously implemented around the world on the basis of German standards.
Right from the development stage, ecological design, technical safety and health protection are fixed criteria.
The following section contains recommendations for ecological disposal of the product and its components.

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### 6.3.1 Country-specific legal requirements

**NOTE**
**Country-specific legal requirements**
Always observe the applicable country-specific legal regulations with regard to the disposal of products or waste occurring in the various phases of the life cycle. The corresponding disposal standards are also to be heeded.

### 6.3.2 Disassembly

Disassembly of the product must be performed or supervised by qualified personnel with the appropriate technical knowledge.
The product is to be disassembled into suitable components for disposal employing standard procedures for motors.

**WARNING**
**Heavy parts of the product may drop off. Some of the product components are heavy. These components could drop off during disassembly.**
This can result in fatal or serious injury and material damage.
→ Secure components before unfastening to stop them falling.

### 6.3.3 Component disposal

The products are mostly made of steel, copper, aluminum and plastic. Metallic materials are generally considered to be fully recyclable.
Separate the components for recycling into the following categories:

- Steel and iron
- Aluminum
- Non-ferrous metal, e.g. motor windings
- Plastics, particularly with brominated flame retardants, in accordance with marking
- Insulating materials
- Cables and wires
- Electronic scrap, e.g. circuit boards

Only ferrite magnets and not rare earth magnets are used in external rotor motors from ebm-papst Mulfingen GmbH & Co. KG.

⇒ Ferrite magnets can be disposed of in the same way as normal iron and steel.

Electrical insulating materials on the product, in cables and wires are made of similar materials and are therefore to be treated in the same manner.
The materials concerned are as follows:

- Miscellaneous insulators used in the terminal box
- Power cables
- Cables for internal wiring
- Electrolytic capacitors

Dispose of electronic components employing the proper procedures for electronic scrap.

→ Please contact ebm-papst for any other questions on disposal.

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