A3G630-AR85-90

EC axial fan

sickle-shaped blades (S series)

ebm-papst Mulfingen GmbH & Co. KG
Bachmühle 2 · D-74673 Mulfingen
Phone +49 7938 81-0
Fax +49 7938 81-110
info1@de.ebmpapst.com
www.ebmpapst.com

Limited partnership · Headquarters Mulfingen
Amtsgericht (court of registration) Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen
Amtsgericht (court of registration) Stuttgart · HRB 590142

Nominal data

Type	**A3G630-AR85-90**
Motor	**M3G112-IA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	1140
Power consumption	W	970
Current draw	A	1.6
Max. back pressure	Pa	170
Max. back pressure	in. wg	0.68
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	45.1	33.6
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		51.5	40
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	0.97
09 Air flow q_v	m^3/h	8935
09 Pressure increase p_{fs}	Pa	163
10 Speed (rpm) n	min^{-1}	1155
11 Specific ratio*		1.00

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

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Technical description

Weight	11.5 kg
Size	630 mm
Motor size	112
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Blade material	Press-fitted sheet steel blank, sprayed with PP plastic
Number of blades	5
Airflow direction	V
Direction of rotation	Counterclockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H2
Max. permitted ambient temp. for motor (transport/storage)	80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Conformity with standards	EN 61800-5-1; CE
Approval	CCC; EAC; UL 1004-7 + 60730-1

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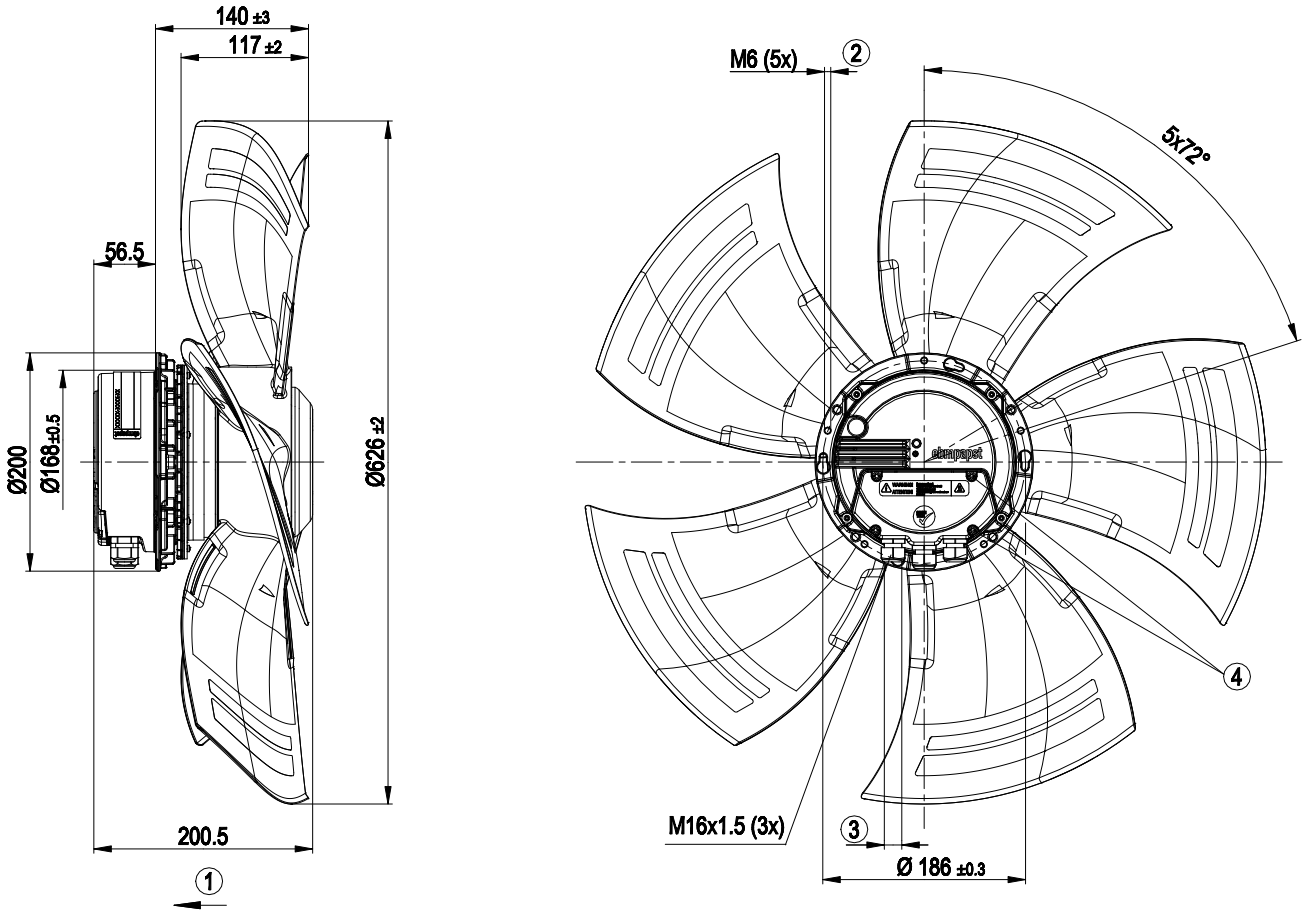
Comment	Maximum permissible operating altitude 4000 m above sea level according to DIN 61800-5-1_2008_Sec. 4.3.6.4.1 overvoltage category II. Up to 2000 m above sea level, overvoltage category III applies.

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Product drawing



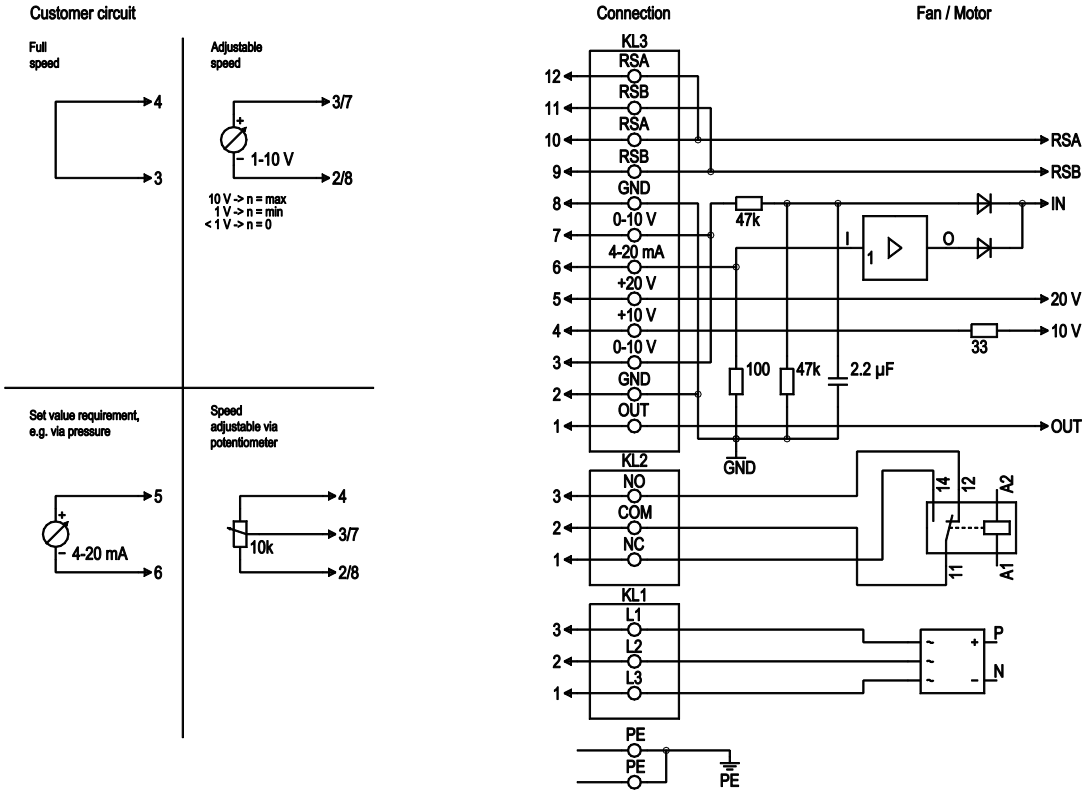
1	Direction of air flow "V"
2	Max. clearance for screw 16 mm
3	Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5±0.4 Nm
4	Tightening torque 3.5 ± 0.5 Nm

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Connection diagram



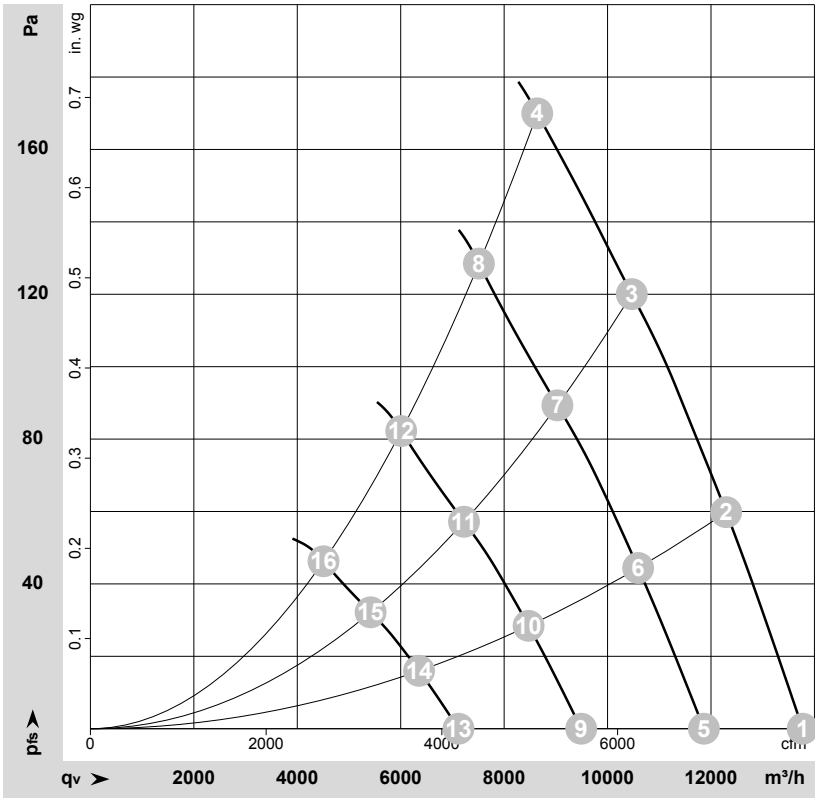
No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply, voltage range (see nameplate), 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

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Curves: Air performance 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-115687-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
		V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	3~	400	50	1140	642	1.02	67	74	74	13775	0	8105	0.00
2	3~	400	50	1140	781	1.26	64	71	71	12295	60	7235	0.24
3	3~	400	50	1140	902	1.44	66	73	72	10470	120	6160	0.48
4	3~	400	50	1140	970	1.60	68	74	74	8640	170	5085	0.68
5	3~	400	50	1000	410	0.65	64	70	70	11865	0	6980	0.00
6	3~	400	50	1000	499	0.80	60	67	67	10590	45	6235	0.18
7	3~	400	50	1000	579	0.92	63	69	68	9030	89	5315	0.36
8	3~	400	50	1000	646	1.04	64	71	70	7510	128	4420	0.51
9	3~	400	50	800	210	0.33	58	65	65	9490	0	5585	0.00
10	3~	400	50	800	255	0.41	55	62	61	8475	29	4985	0.12
11	3~	400	50	800	297	0.47	57	63	62	7225	57	4250	0.23
12	3~	400	50	800	331	0.53	59	65	64	6010	82	3535	0.33
13	3~	400	50	600	89	0.14	51	57	57	7120	0	4190	0.00
14	3~	400	50	600	108	0.17	47	54	54	6355	16	3740	0.06
15	3~	400	50	600	125	0.20	50	56	55	5420	32	3190	0.13
16	3~	400	50	600	140	0.22	52	58	57	4505	46	2655	0.18

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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