R3G500-RA34-19

EC centrifugal fan - RadiCal

backward-curved, single-intake

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Nominal data

Type	**R3G500-RA34-19**
Motor	**M3G150-FF**

Phase		3~
Nominal voltage	VAC	200
Nominal voltage range	VAC	200 .. 240
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	1700
Power consumption	W	2700
Current draw	A	8.2
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	63.7	56
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		69.7	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	2.68
09 Air flow q_v	m^3/h	6850
09 Pressure increase p_{fs}	Pa	846
10 Speed (rpm) n	min^{-1}	1710
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-168579

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Technical description

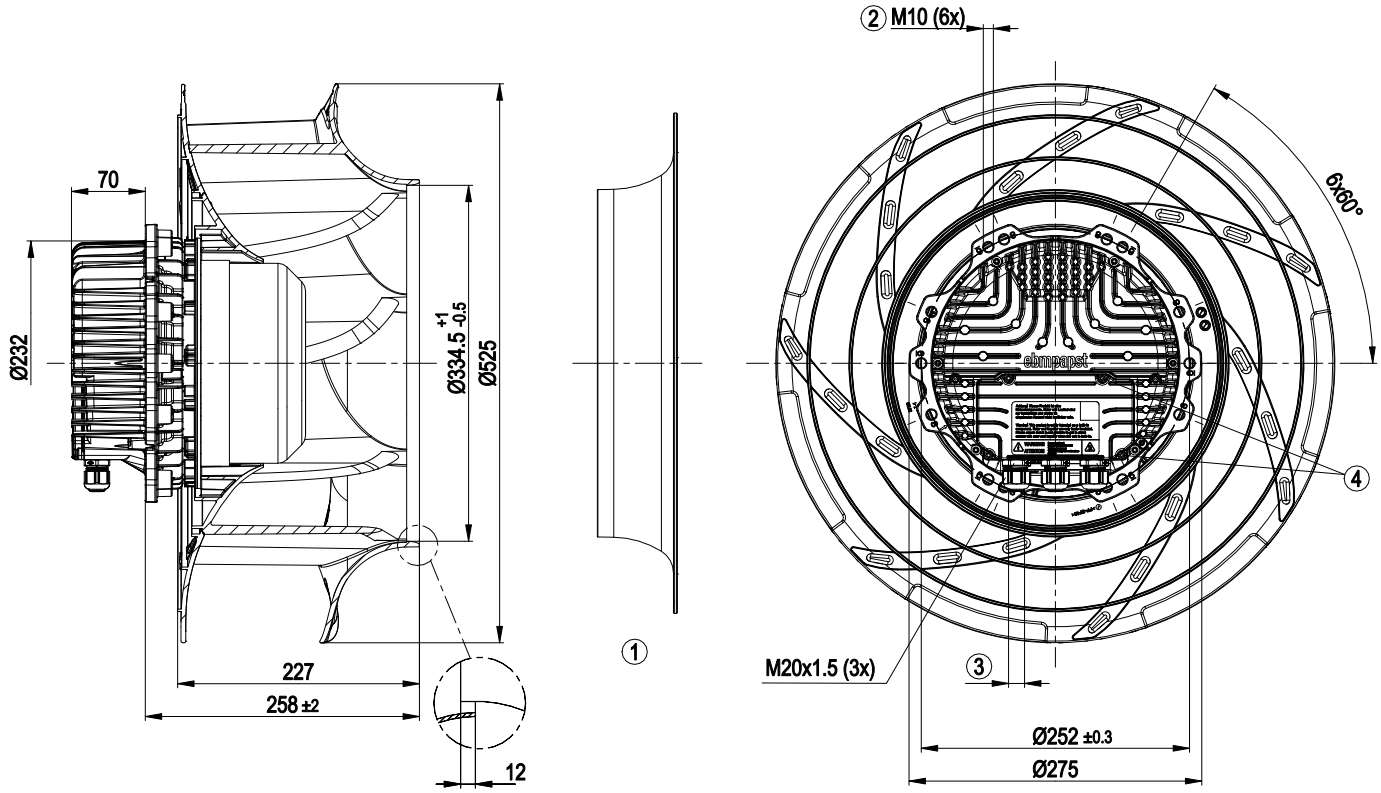
Weight	22.68 kg
Size	500 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	PP plastic
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	CSA C22.2 No. 77 + CAN/CSA-E60730-1; UL 1004-7 + 60730-1; EAC

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Product drawing



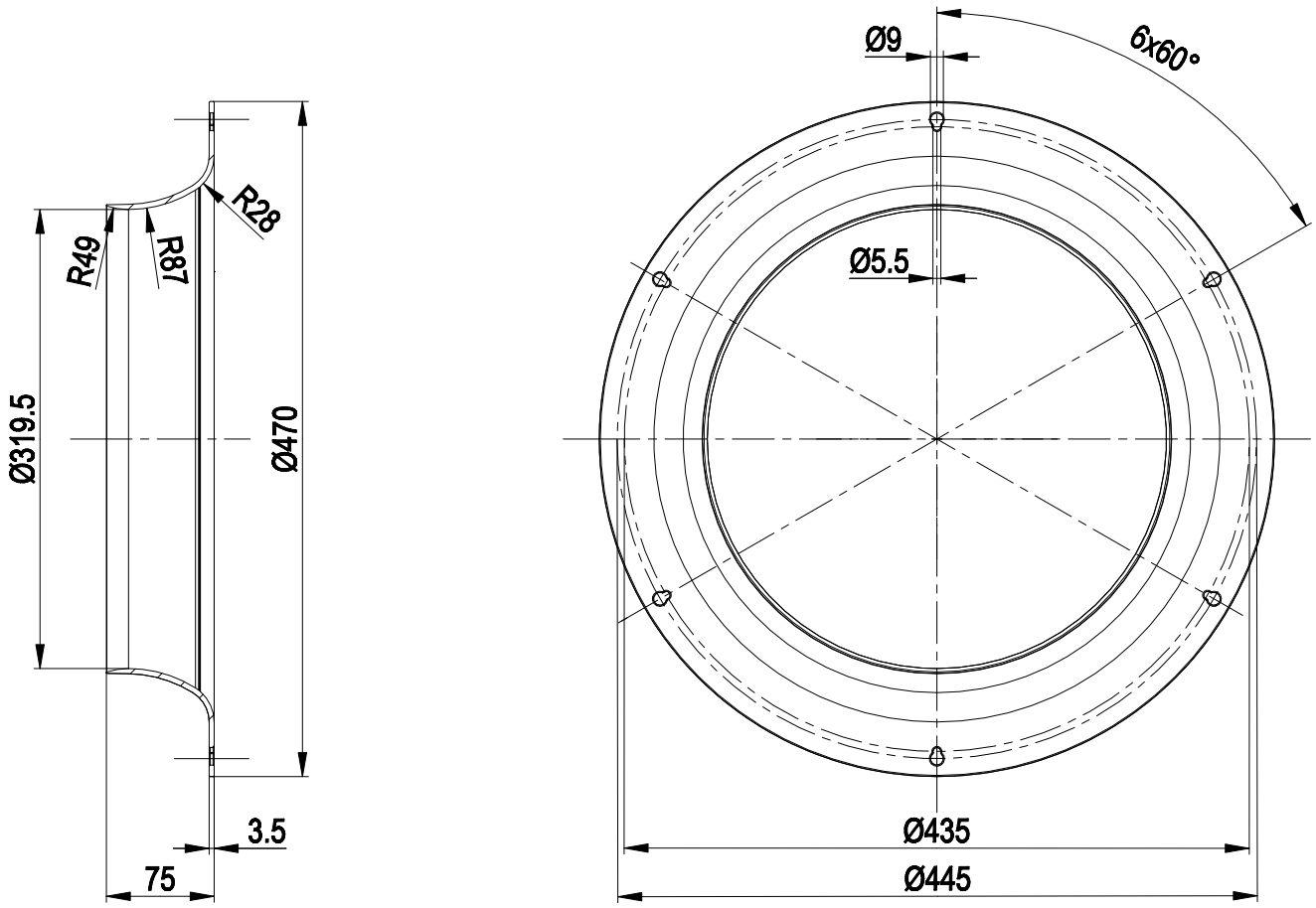
1	Accessory part: inlet ring 50901-2-2943 not included in scope of delivery
2	Max. clearance for screw 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
4	Tightening torque 3.5 ± 0.5 Nm

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Accessory part



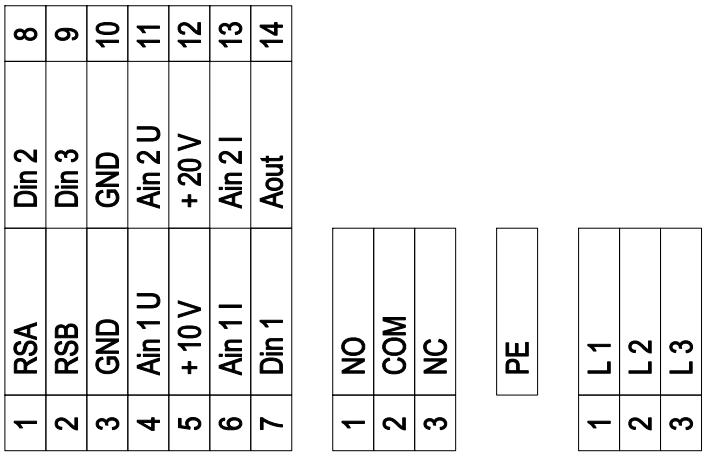
1	Accessory part: inlet ring 50901-2-2943

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Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 200-240 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 200-240 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 200-240 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1I; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV

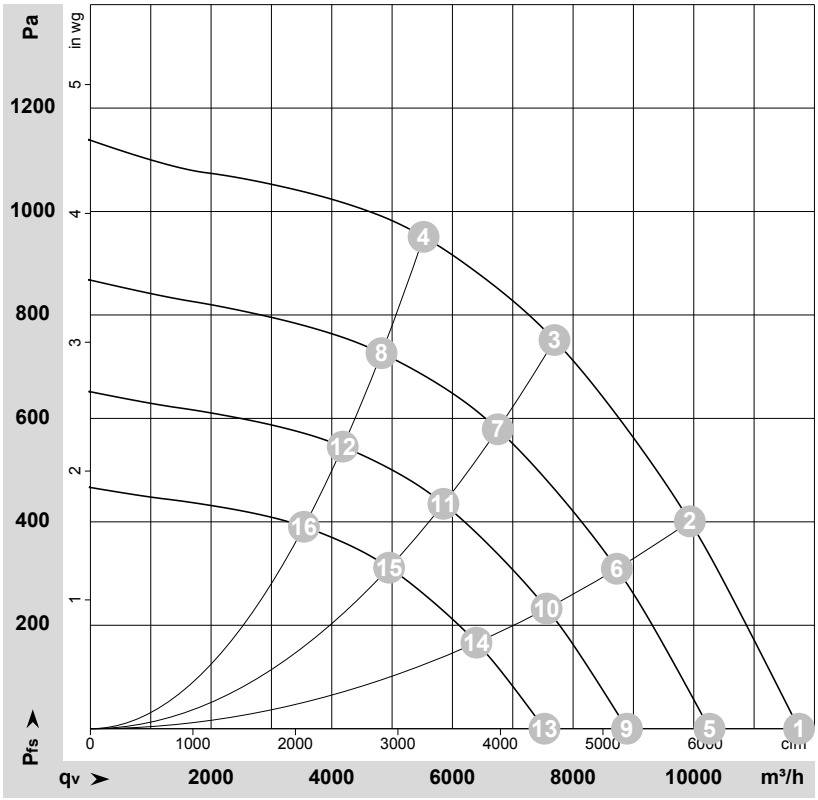
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No.	Conn.	Designation	Function/assignment
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV

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Curves: Air performance 50 Hz



ρ = 1.174 kg/m³ ± 2 %

Measurement: LU-168579-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	200	50	1700	1916	5.88	79	86	93	11745	0	6915	0.00
2	200	50	1700	2490	7.61	76	83	90	9935	400	5850	1.61
3	200	50	1700	2700	8.20	71	78	85	7690	750	4525	3.01
4	200	50	1700	2577	7.90	71	78	84	5520	950	3250	3.81
5	200	50	1500	1278	3.92	76	83	90	10260	0	6040	0.00
6	200	50	1500	1686	5.15	72	80	87	8725	313	5135	1.26
7	200	50	1500	1816	5.57	67	75	81	6750	581	3975	2.33
8	200	50	1500	1718	5.26	67	75	81	4825	729	2840	2.93
9	200	50	1300	832	2.55	72	79	86	8895	0	5235	0.00
10	200	50	1300	1098	3.35	69	76	83	7560	235	4450	0.94
11	200	50	1300	1182	3.62	64	71	78	5850	436	3445	1.75
12	200	50	1300	1118	3.43	64	71	77	4180	548	2460	2.20
13	200	50	1100	504	1.55	68	75	82	7525	0	4430	0.00
14	200	50	1100	665	2.03	65	72	79	6400	168	3765	0.67
15	200	50	1100	716	2.20	60	67	74	4950	312	2915	1.25
16	200	50	1100	677	2.08	60	67	73	3540	392	2080	1.57

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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