W3G710-GO81-90

EC axial fan - HyBlade®

sickled blades (S series)

with full square nozzle

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**W3G710-GO81-90**
Motor	**M3G112-IA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min^{-1}	900
Power input	W	930
Current draw	A	1.5
Max. back pressure	Pa	125
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	+60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.00

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}		41.9	29.3	33.3
Efficiency grade N		48.6	36	40
Power input P_{ed}	kW	0.86		
Air flow q_v	m^3/h	11370		
Pressure increase p_{fs}	Pa	105		
Speed n	min^{-1}	905		

Data established at point of optimum efficiency.

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Technical features

Mass	27.2 kg
Size	710 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Aluminium sheet insert, sprayed with PP plastic
Material of wall ring	Sheet steel, pre-galvanised and coated in black plastic (RAL 9005)
Material of guard grille	Steel, coated in black plastic (RAL9005)
Number of blades	5
Blade angle	0°
Direction of air flow	"V"
Direction of rotation	Counter-clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Cable exit	Variable
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	GOST; UL 1004-7 + 60730

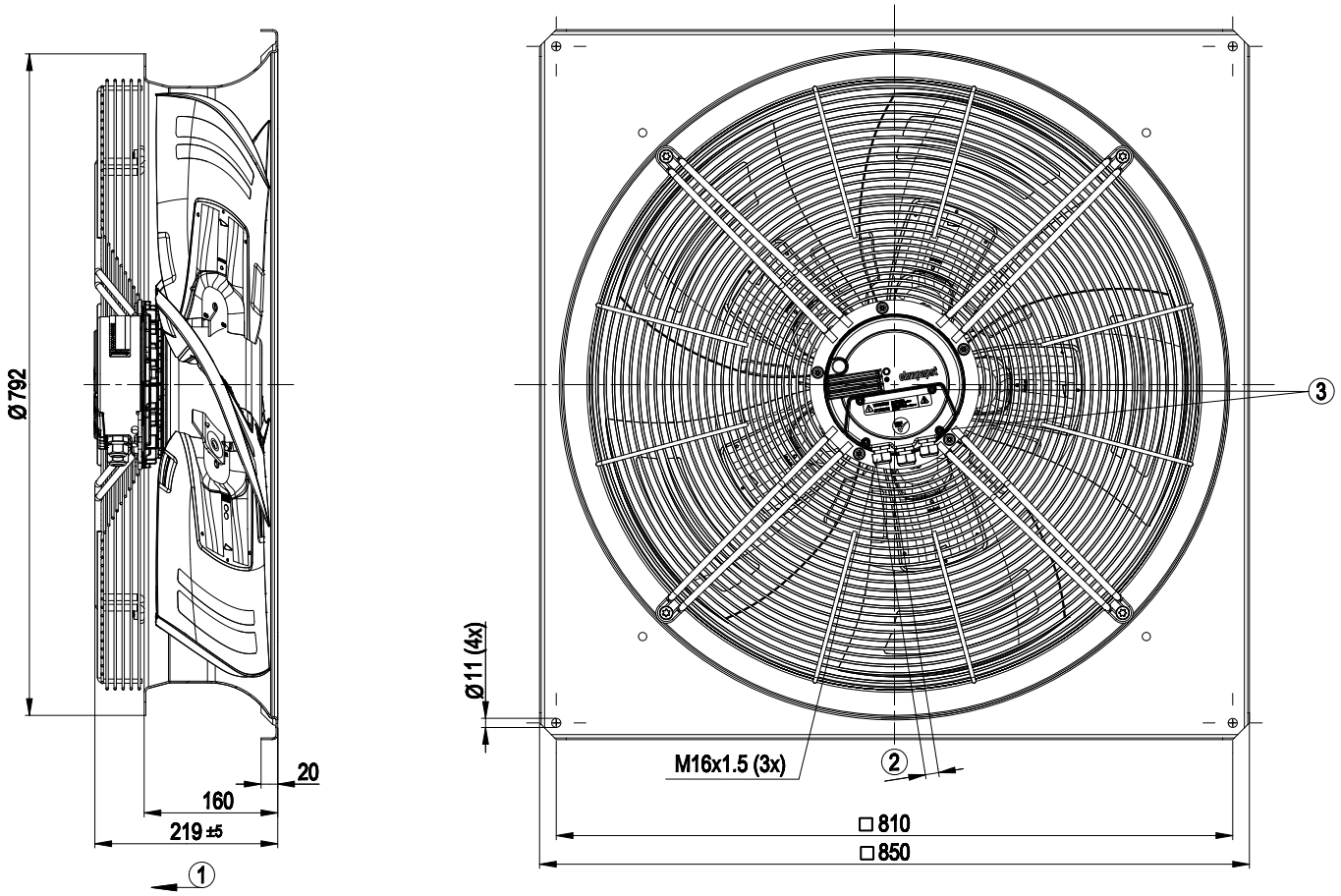
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Product drawing



1	Direction of air flow "V"
2	Cable diameter: min. 4 mm, max. 10 mm; tightening torque: 2±0.3 Nm
3	Tightening torque 3.5±0.5 Nm

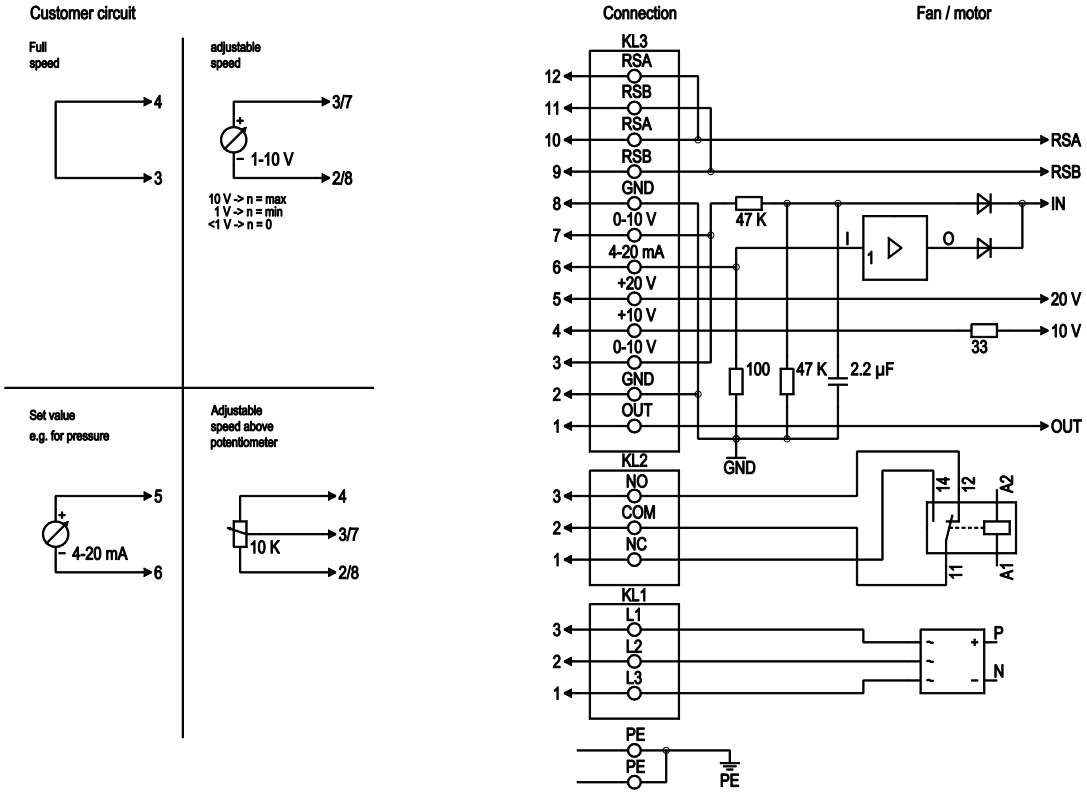
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Connection screen



No.	Pin	Signal	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, voltage range (see type plate), 50/60 Hz
KL2	1	NC	Floating status contact, break with error
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, close with error
KL3	1	OUT	Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the actual motor duty cycle (PWM): 1 V corresponds to 10% PWM, 10 V correspond to 100% PWM.
KL3	2, 8	GND	Signal ground for control interface, SELV
KL3	3, 7	0-10 V	Set value / actual sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, supply voltage for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Set value / actual sensor value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

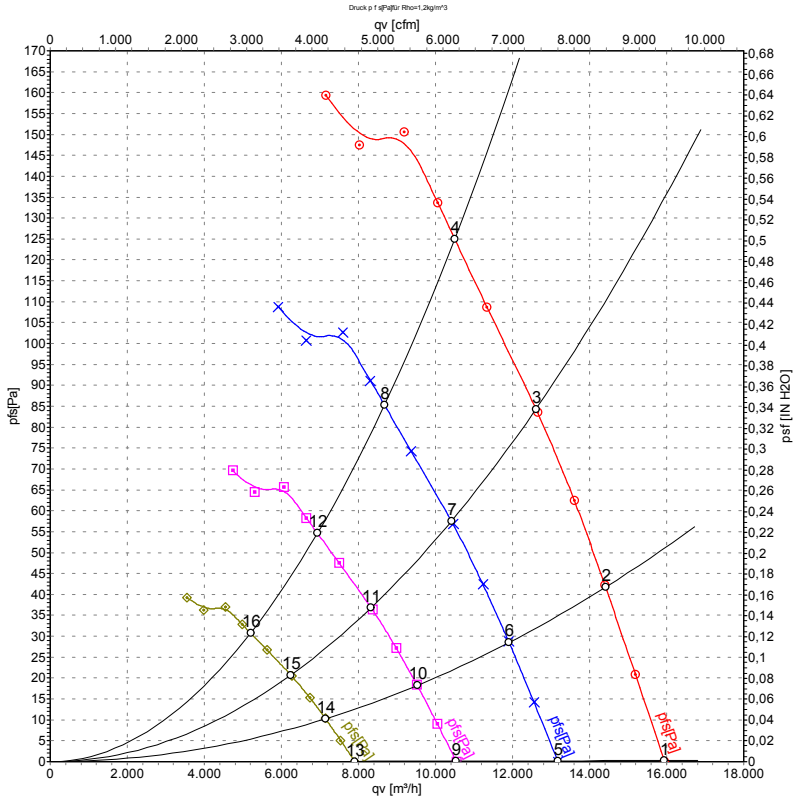
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Charts: Air flow 50 Hz



Measurement: LU-123826

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa
1	400	50	900	602	1.02	64	70	71	15940	0
2	400	50	900	718	1.17	63	69	69	14420	42
3	400	50	900	827	1.30	63	70	70	12610	85
4	400	50	900	930	1.50	69	75	75	10500	125
5	400	50	750	340	0.58	60	66	67	13170	0
6	400	50	750	405	0.66	59	65	65	11910	29
7	400	50	750	465	0.73	59	65	66	10410	58
8	400	50	750	523	0.82	65	71	71	8670	85
9	400	50	600	174	0.30	55	61	62	10540	0
10	400	50	600	208	0.34	54	60	60	9530	18
11	400	50	600	238	0.38	54	61	61	8330	37
12	400	50	600	268	0.42	60	66	66	6940	55
13	400	50	450	73	0.12	49	55	55	7905	0
14	400	50	450	88	0.14	47	54	54	7145	10
15	400	50	450	100	0.16	48	54	55	6245	21
16	400	50	450	113	0.18	54	60	60	5205	31

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
qv = Air flow · p_{fs} = Pressure increase

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