K3G310-AV69-61

EC centrifugal module - RadiPac

backward-curved, single-intake

with support bracket

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**K3G310-AV69-61**
Motor	**M3G112-EA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min^{-1}	3040
Power consumption	W	1420
Current draw	A	2.2
Min. ambient temperature	°C	-40
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	56.3	53
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		65.3	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	1.38
09 Air flow q_v	m^3/h	2800
09 Pressure increase p_{fs}	Pa	929
10 Speed (rpm) n	min^{-1}	3000
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

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Technical description

Weight	17.9 kg
Fan size	310 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum, painted black
Support plate material	Sheet steel, galvanized and painted black
Support bracket material	Steel, painted black
Inlet nozzle material	Sheet steel, galvanized and painted black
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE

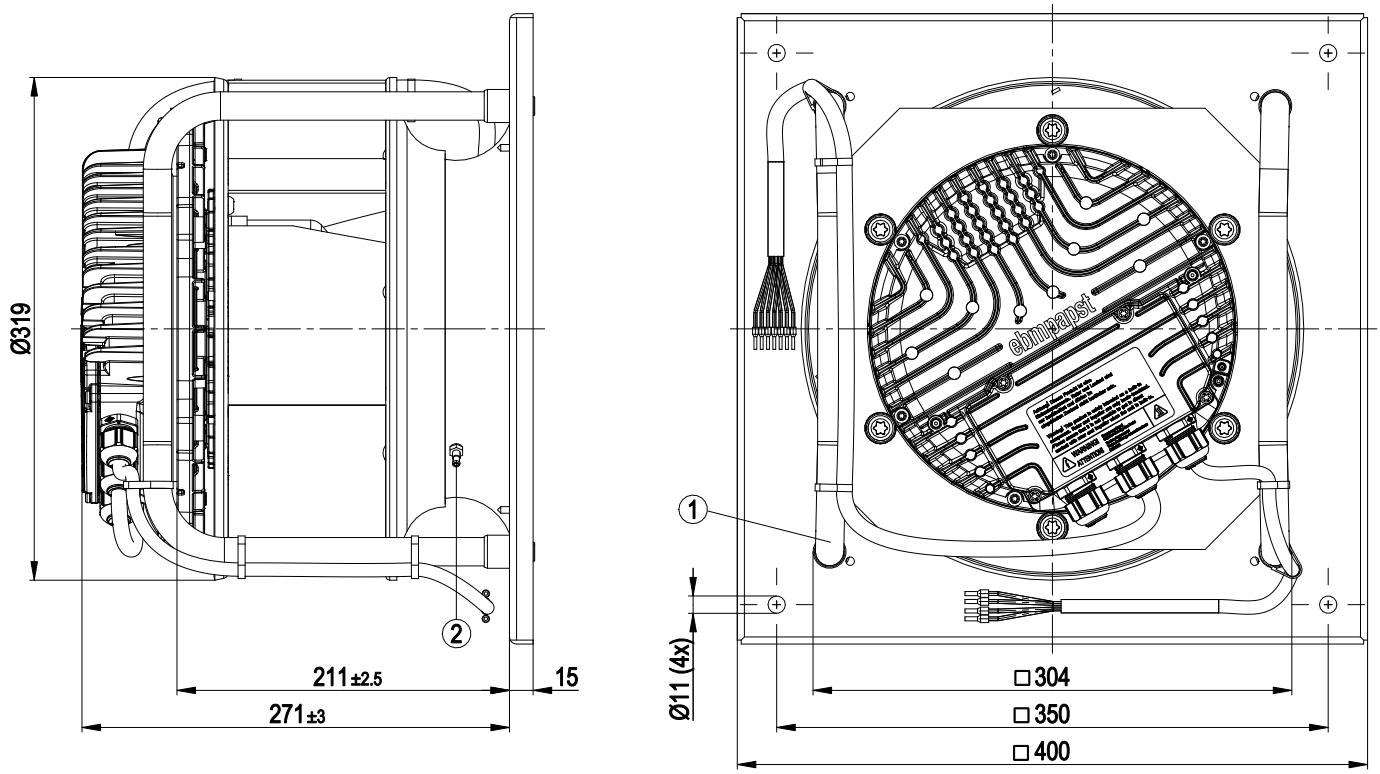
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Product drawing



1	Installed position: shaft horizontal (install support struts only vertically as illustrated) or rotor on bottom; rotor on top on request
2	Inlet ring with pressure tap (k-factor: 108)

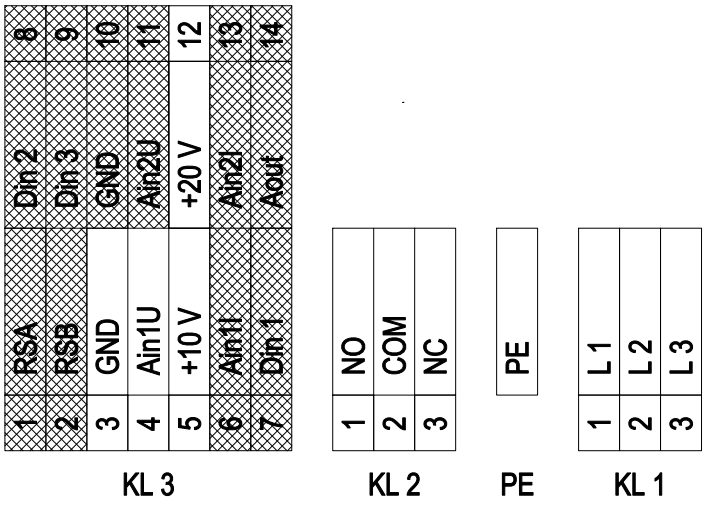
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Connection diagram



shaded gray => not brought out via leads

No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL 2	2	COM	Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL 2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS RTU
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS RTU
KL 3	3 / 10	GND	Reference ground for control interface
KL 3	4	Ain1 U	Analog input 1 (set value), 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1I
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot)
KL 3	6	Ain1 I	Analog input 1 (set value), 4-20 mA, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1U
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5...50 VDC: disable: bridge to GND or applied voltage < 1 VDC; reset function: triggers software reset after a level change to < 1 V (SELV)
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2; according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC; parameter set 2: bridge to GND or applied voltage < 1 VDC
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input; normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC
KL 3	11	Ain2 U	Analog input 2 (measured value), 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors)
KL 3	13	Ain2 I	Analog input 2 (measured value), 4-20 mA, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2U
KL 3	14	Aout	Analog output 0-10 V, max. 5 mA, output of current motor modulation level / of the current motor speed. Adjustable curve.

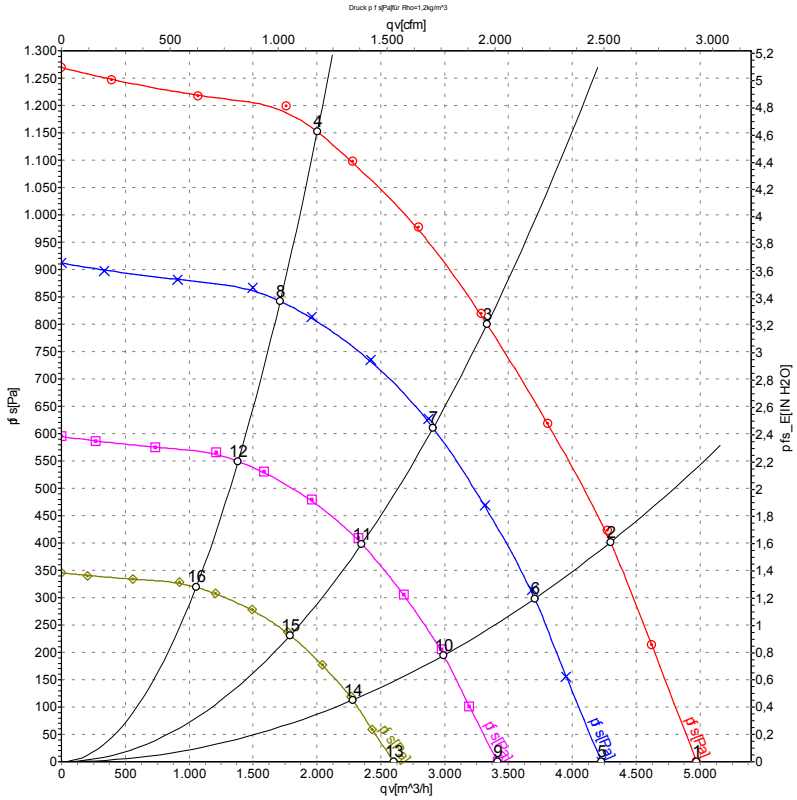
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Curves: Air performance 50 Hz



Measurement: LU-126842-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	400	50	3040	1154	1.77	82	89	95	4975	0	2930	0.00
2	400	50	3040	1330	2.04	78	85	91	4300	400	2530	1.61
3	400	50	3040	1420	2.20	76	83	89	3330	800	1960	3.21
4	400	50	3040	1315	2.01	79	88	90	2005	1150	1180	4.62
5	400	50	2600	709	1.09	78	85	91	4230	0	2490	0.00
6	400	50	2600	852	1.30	75	82	88	3705	304	2180	1.22
7	400	50	2600	949	1.45	73	80	86	2910	615	1715	2.47
8	400	50	2600	823	1.26	75	84	87	1715	842	1010	3.38
9	400	50	2100	374	0.58	73	81	87	3415	0	2010	0.00
10	400	50	2100	449	0.69	70	78	83	2990	198	1760	0.79
11	400	50	2100	500	0.77	68	75	81	2350	401	1385	1.61
12	400	50	2100	434	0.66	71	80	82	1385	550	815	2.21
13	400	50	1600	165	0.25	68	75	81	2600	0	1530	0.00
14	400	50	1600	199	0.30	64	72	78	2280	115	1340	0.46
15	400	50	1600	221	0.34	62	69	75	1790	233	1055	0.94
16	400	50	1600	192	0.29	65	74	77	1055	319	620	1.28

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase

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