K3G560-RB31-71/F04

EC centrifugal fan - RadiCal

backward-curved, single-intake

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Nominal data

Type	**K3G560-RB31-71/F04**
Motor	**M3G150-IF**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	1650
Power consumption	W	2900
Current draw	A	4.43
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	55

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	67.9	56.4
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		73.5	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	2.92
09 Air flow q_v	m^3/h	9845
09 Pressure increase p_{fs}	Pa	688
10 Speed (rpm) n	min^{-1}	1645
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

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Technical description

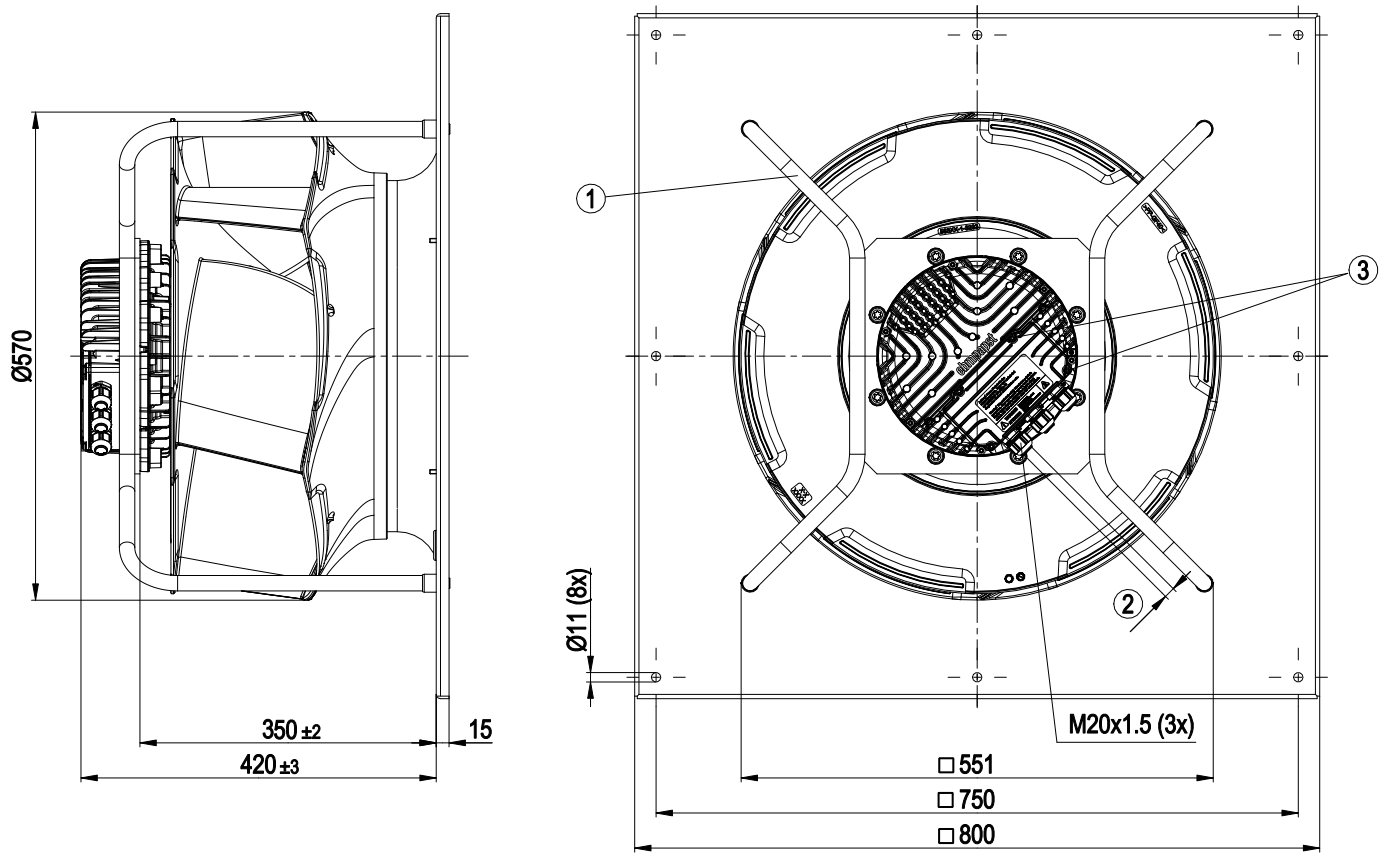
Weight	42.6 kg
Fan size	560 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	PP plastic
Material of mounting plate	Sheet steel, galvanised
Material of support bracket	Steel, coated in black
Material of inlet nozzle	Sheet steel, galvanised
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	F4-1
Ambient temperature note	Occasional start-up between -40°C and -25°C is permissible. For continuous operation at temperatures below -25°C (e.g. refrigeration applications) we recommend our fan design with special low-temperature bearings.
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 55022 (Class B, household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer to the housing's connection point)
Approval	EAC

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Product drawing

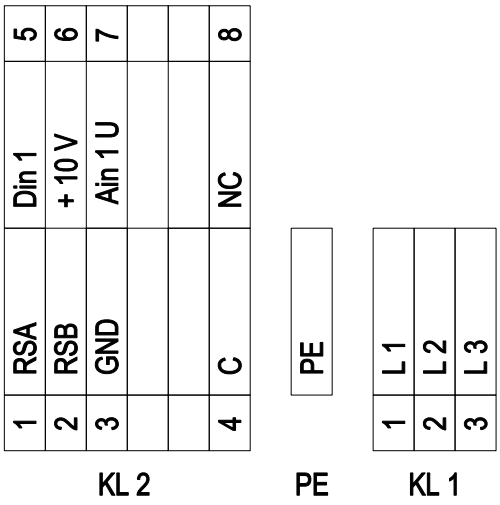


1	Mounting position: shaft horizontal (install the support struts only vertically as shown in the view!) or rotor on bottom; rotor on top on request
2	Cable diameter: min. 4 mm, max. 10 mm; tightening torque: 4±0.6 Nm
3	Tightening torque 3.5±0.5 Nm

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Connection diagram

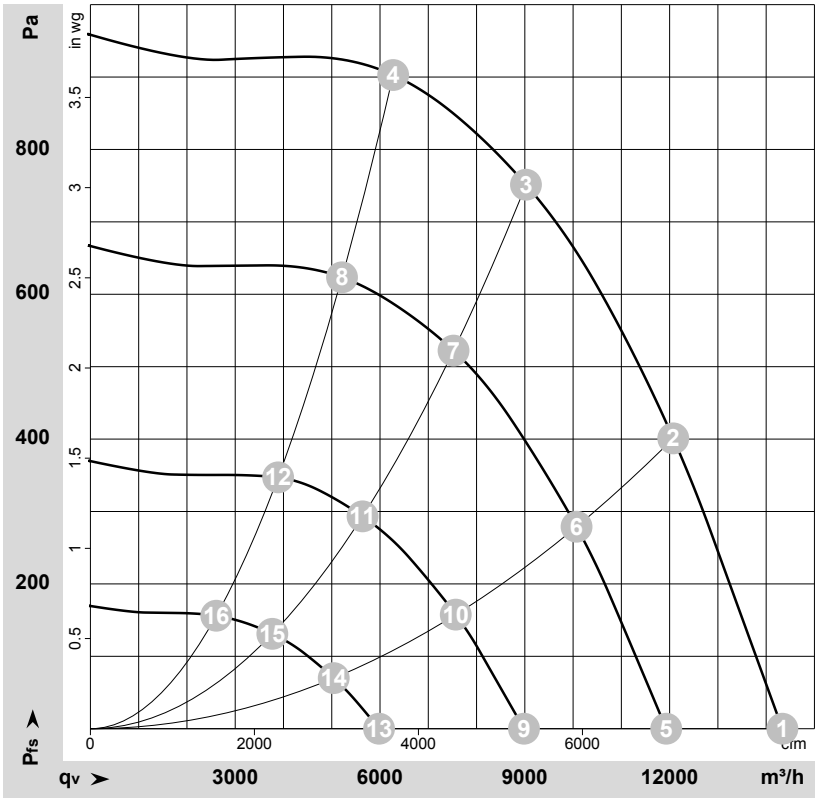


No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 2	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 2	3	GND	Reference ground for control interface; SELV
KL2	4	C	Status relay, floating status contact, break for failure; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL 2	5	Din1	Digital input 1 enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 V; SELV
KL 2	6	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); SELV Or: +24 VDC input for parameter setting via MODBUS without line voltage
KL 2	7	Ain1 U	Analog input 1 (set value) 0-10 V, Ri = 100 kΩ, adjustable curve; SELV
KL2	8	NC	Status relay, floating status contact, break for failure

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Curves: Air performance 50 Hz



Measured values

	Wired	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
		V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	Y	400	50	1650	2030	3.17	79	87	90	14335	0	8440	0.00
2	Y	400	50	1650	2695	4.16	73	81	85	12075	400	7105	1.61
3	Y	400	50	1650	2900	4.43	69	77	82	9025	750	5310	3.01
4	Y	400	50	1650	2769	4.28	73	81	85	6270	900	3690	3.61
5	Y	400	50	1375	1191	1.94	75	83	86	11930	0	7020	0.00
6	Y	400	50	1375	1592	2.53	69	77	81	10070	280	5930	1.12
7	Y	400	50	1375	1705	2.70	64	73	77	7525	522	4430	2.10
8	Y	400	50	1375	1610	2.56	68	76	80	5210	624	3070	2.51
9	Y	400	50	1035	534	1.07	70	77	80	8985	0	5285	0.00
10	Y	400	50	1035	711	1.31	64	71	75	7570	158	4455	0.63
11	Y	400	50	1035	760	1.37	57	66	70	5640	293	3320	1.18
12	Y	400	50	1030	711	1.31	60	68	72	3890	347	2290	1.39
13	Y	400	50	695	189	0.60	61	69	72	5980	0	3520	0.00
14	Y	400	50	695	242	0.67	55	63	66	5040	70	2965	0.28
15	Y	400	50	695	258	0.69	47	55	60	3770	131	2220	0.53
16	Y	400	50	695	244	0.67	48	57	61	2610	156	1535	0.63

Wired = Wiring · U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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