W3G630-CE31-01

EC axial fan

sickled blades (S series)

with full square nozzle

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**W3G630-CE31-01**
Motor	**M3G112-GA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min^{-1}	1000
Power input	W	900
Current draw	A	1.8
Max. back pressure	Pa	140
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = max. load · me = max. efficiency · fa = running at free air · cs = customer specs · cu = customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.00

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}		43.5	29	33
Efficiency grade N		50.5	36	40
Power input P_{ed}	kW	0.77		
Air flow q_v	m^3/h	9205		
Pressure increase p_{fs}	Pa	121		
Speed n	min^{-1}	1005		

Data established at point of optimum efficiency

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Technical features

Mass	18.5 kg
Size	630 mm
Surface of rotor	Cast in PA plastic
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	PA plastic
Material of wall ring	Sheet steel, pre-galvanised and coated in black plastic
Material of guard grille	Steel, phosphated and coated in black plastic
Number of blades	5
Direction of air flow	"V"
Direction of rotation	Counter-clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE

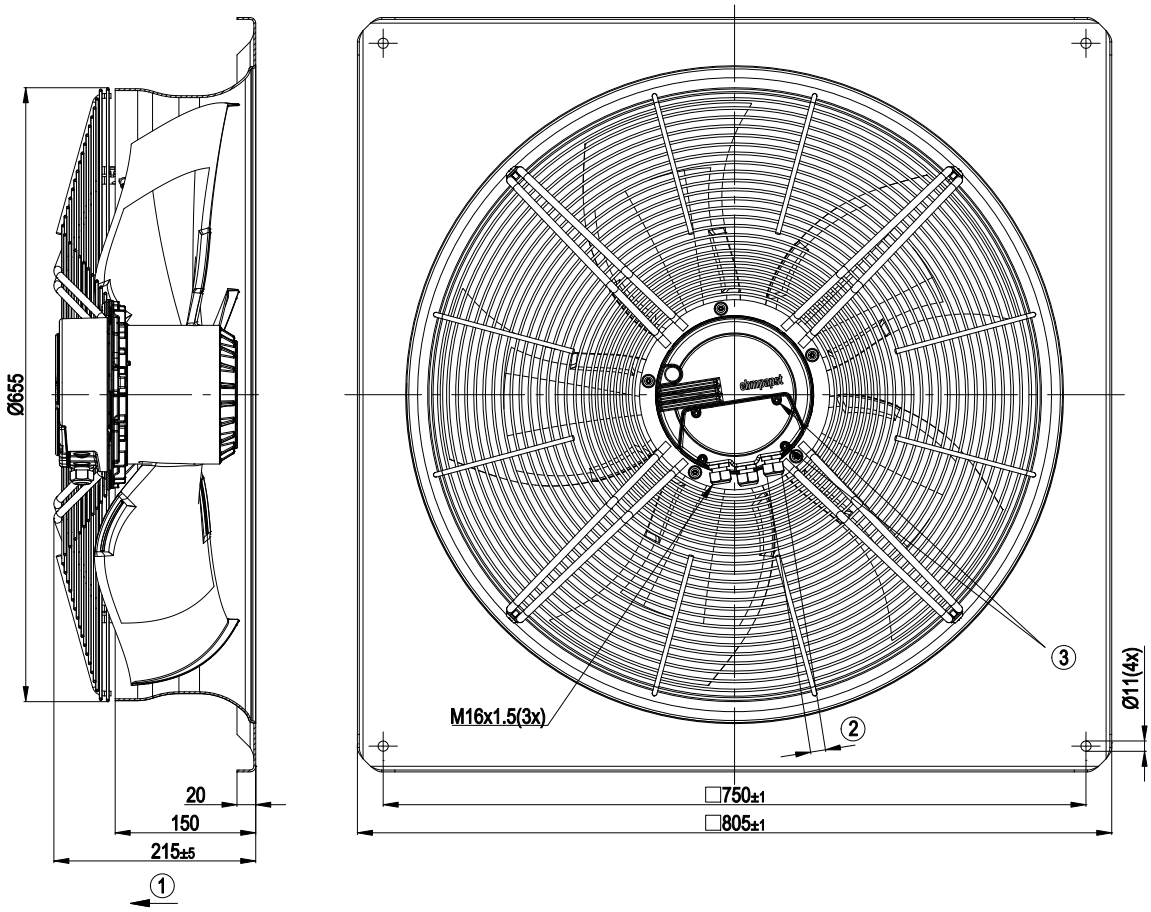
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Product drawing



1	Direction of air flow "V"
2	Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 2.5±0.4 Nm
3	Tightening torque 3.5±0.5 Nm

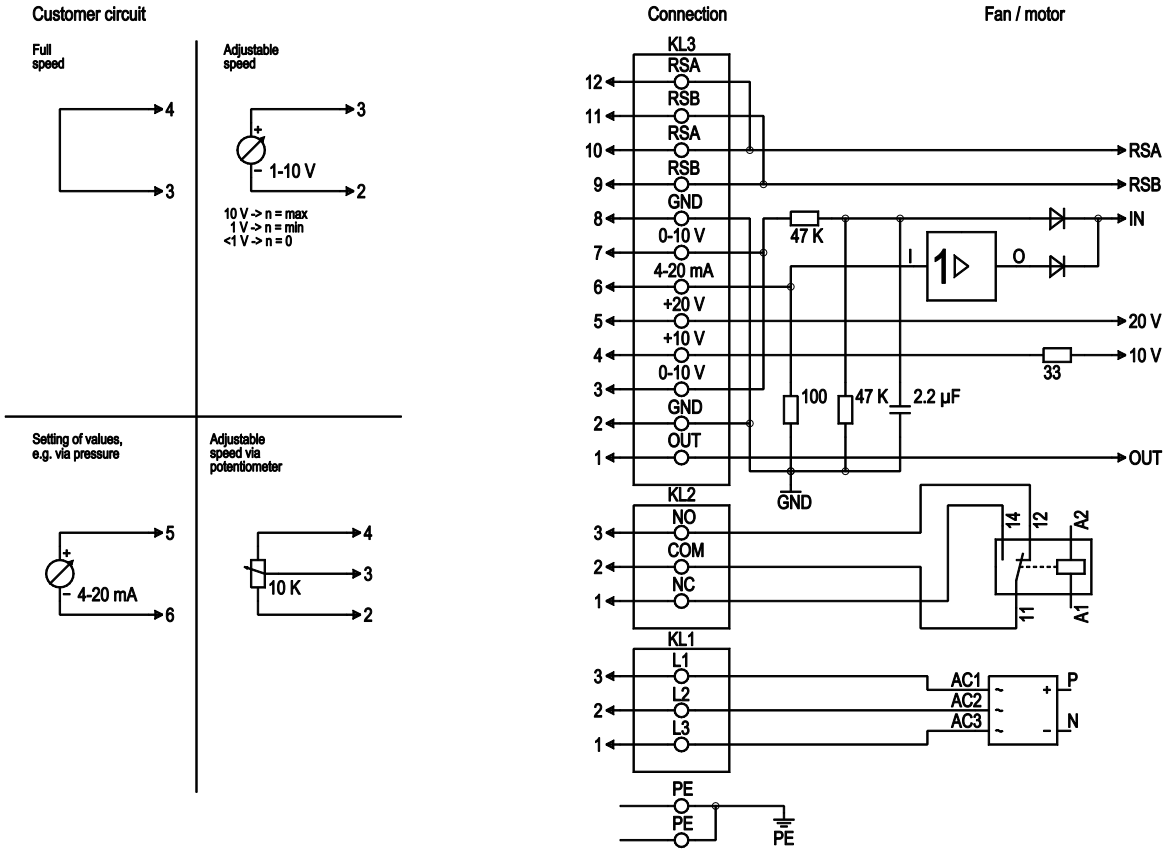
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Connection screen



No.	Pin	Signal	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, 50/60 Hz
KL2	1	NC	Floating status message contact, normally closed connection
KL2	2	COM	Floating status message contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status message contact, normally open connection
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of the current level control coefficient: 1 V equates to 10% level control coefficient. 10 V equate to 100% level control coefficient.
KL3	2, 8	GND	Reference mass for control interface, SELV
KL3	3, 7	0-10 V	Use control / actual value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3%), max. 10 mA, supply voltage for external devices (e.g. potentiometers), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, supply voltage for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / actual value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBus, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBus, RSA, SELV

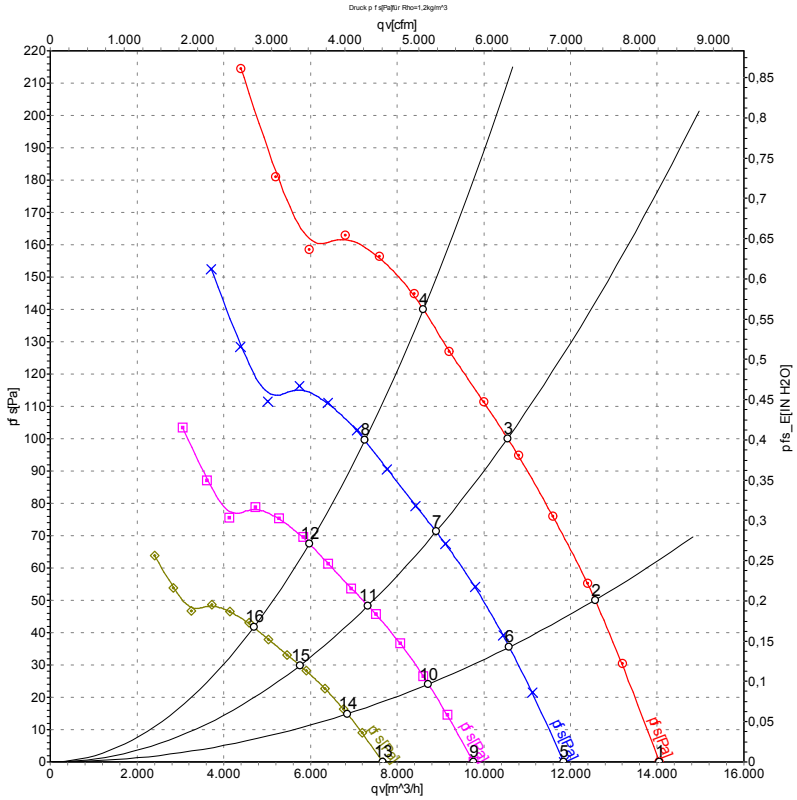
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Charts: Air flow 50 Hz



Measurement: LU-101979

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	m^3/h	Pa
1	400	50	1000	622	1.10	70	75	14050	0
2	400	50	1000	709	1.27	70	77	12570	50
3	400	50	1000	767	1.35	72	78	10550	100
4	400	50	1000	830	1.50	72	79	8605	140
5	400	50	850	373	0.66	66	72	11850	0
6	400	50	850	424	0.76	67	73	10590	36
7	400	50	850	461	0.81	68	75	8900	71
8	400	50	850	483	0.87	69	75	7255	100
9	400	50	700	208	0.37	62	68	9755	0
10	400	50	700	237	0.43	62	69	8720	24
11	400	50	700	257	0.45	64	70	7330	48
12	400	50	700	270	0.49	65	71	5975	68
13	400	50	550	101	0.18	56	62	7665	0
14	400	50	550	115	0.21	57	63	6850	15
15	400	50	550	125	0.22	59	65	5760	30
16	400	50	550	131	0.24	59	66	4695	42

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · qv = Air flow
p_{fs} = Pressure increase

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