R3G355-AZ59-05

EC centrifugal fan

backward curved, single inlet

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**R3G355-AZ59-05**	
Motor	**M3G112-EA**	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min^{-1}	2800
Power input	W	1500
Current draw	A	2.4
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}		60.7	49	53
Efficiency grade N		69.7	58	62
Power input P_{ed}	kW	1.38		
Air flow q_v	m^3/h	3210		
Pressure increase p_{fs}	Pa	873		
Speed n	min^{-1}	2770		

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

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Technical features

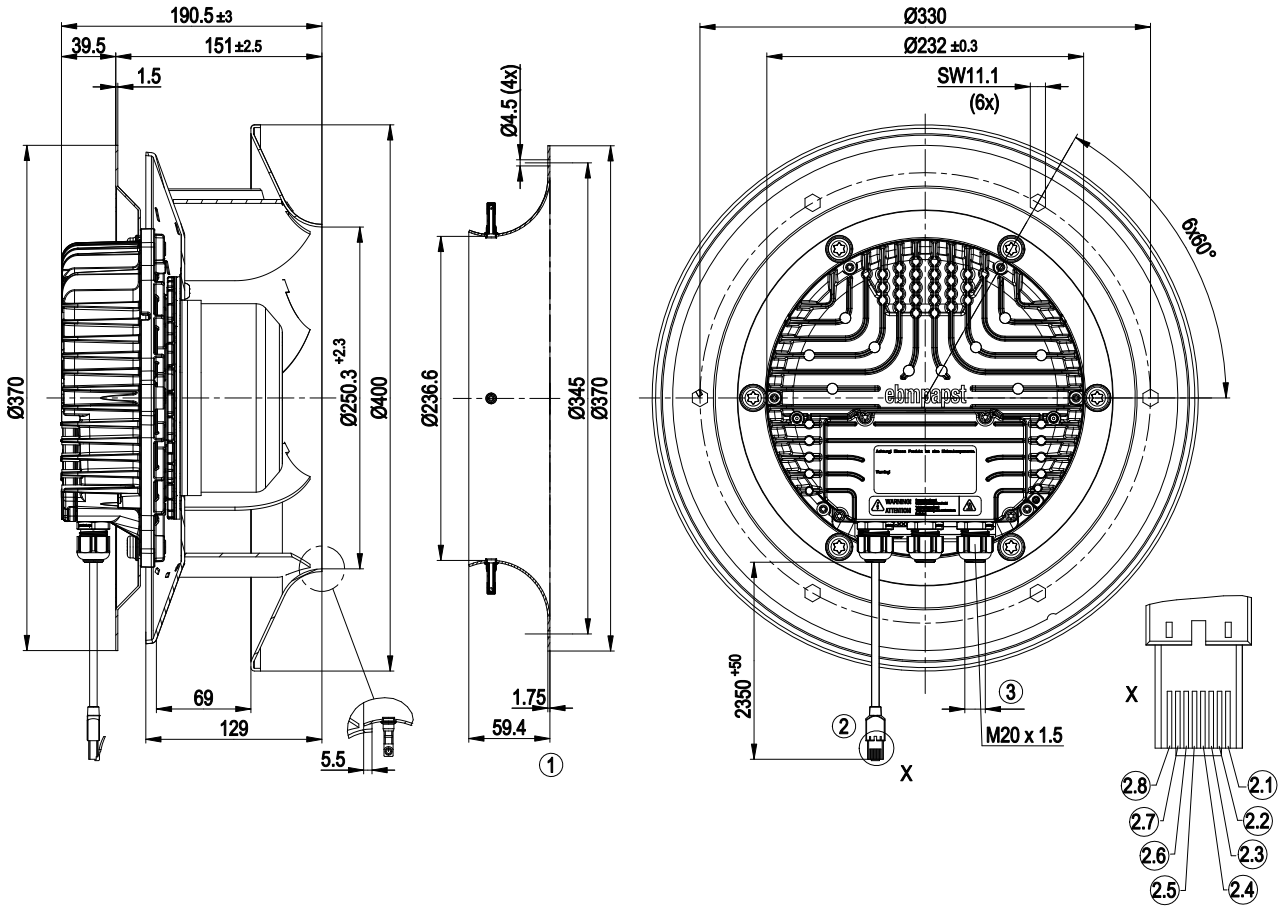
Mass	11.3 kg
Size	355 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU, 8-bit version - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	With plug; Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Cable exit	Variable
Protection class	I (if protective earth is connected by customer)
Approval	UL 1004-1; CSA C22.2 Nr.100

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Product drawing



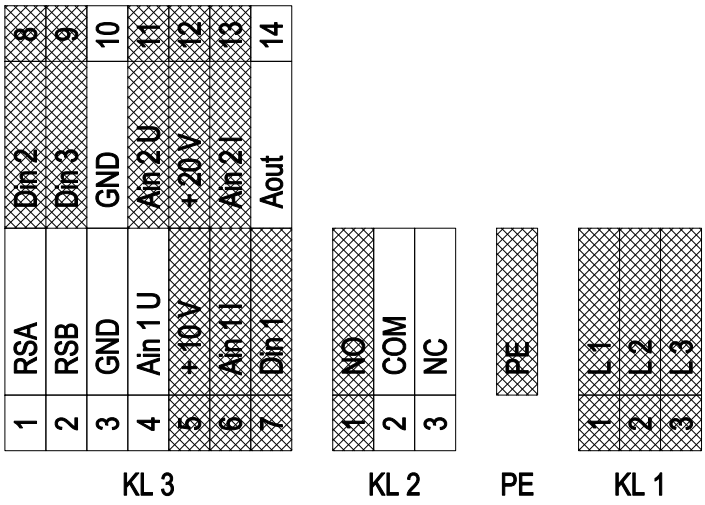
1	Accessory parts: Inlet nozzle with piezometer ring 35530-6-4013 and inlet nozzle 35550-2-4013 not included in the standard scope of delivery
2	Control line PVC with RJ-45 jack (8 contacts)
2.1	Ain1 U
2.2	GND
2.3	Aout
2.4	GND
2.5	COM
2.6	NC
2.7	RSA
2.8	RSB
3	Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 4±0.6 Nm

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Connection screen



grey shaded => not brought out via leads

No.	Pin	Signal	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; make for failure
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break for failure
KL 3	1	RSA	Bus connection RS485; RSA; MODBUS RTU
KL 3	2	RSB	Bus connection RS485; RSB; MODBUS RTU
KL 3	3 / 10	GND	Signal ground for control interface
KL 3	4	Ain1 U	Analogue input 1 (set value); 0-10 V; Ri= 100 kΩ; parametrisable curves; only usable as alternative to input Ain1 I
KL 3	5	+ 10 V	Fixed voltage output 10 VDC; + 10 V +/-3%; max. 10 mA; short circuit proof; power supply for ext. devices (e.g. potentiometer)
KL 3	6	Ain1 I	Analogue input 1 (set value); 4-20 mA; Ri= 100 Ω; parametrisable curves; only usable as alternative to input Ain1 U
KL 3	7	Din1	Digital input 1: enabling of electronics; enabling: open pin or applied voltage 5 to 50 VDC; disabling: bridge to GND or applied voltage < 1 VDC; reset function: triggers software reset after a level change to <1 V
KL 3	8	Din2	Digital input 2: parameter set switch 1/2; according to EEPROM setting, the valid/used parameter set is selectable per BUS or per digital input DIN2. Parameter set 1: open pin or applied voltage 5 to 50 VDC; parameter set 2: bridge to GND or applied voltage < 1 VDC
KL 3	9	Din3	Digital input 3: Control characteristic of the integrated controller; according to EEPROM setting, the control characteristic of the integrated controller is normally/inversely selectable per BUS or per digital input; normal: open pin or applied voltage 5 to 50 VDC (control deviation = actual sensor value - set value) inverse: bridge to GND or applied voltage < 1 VDC (control deviation = set value - actual sensor value)
KL 3	11	Ain2 U	Analogue input 2; actual sensor value 0-10 V; Ri= 100 kΩ; parametrisable curve; only usable as alternative to input Ain2 I
KL 3	12	+ 20 V	Fixed voltage output 20 VDC; + 20V +25/-10%; max. 50 mA; short circuit proof; power supply for ext. devices (e.g. sensors)
KL 3	13	Ain2 I	Analogue input 2; actual sensor value 4-20 mA; Ri= 100 Ω; parametrisable curve; only usable as alternative to input Ain2 U

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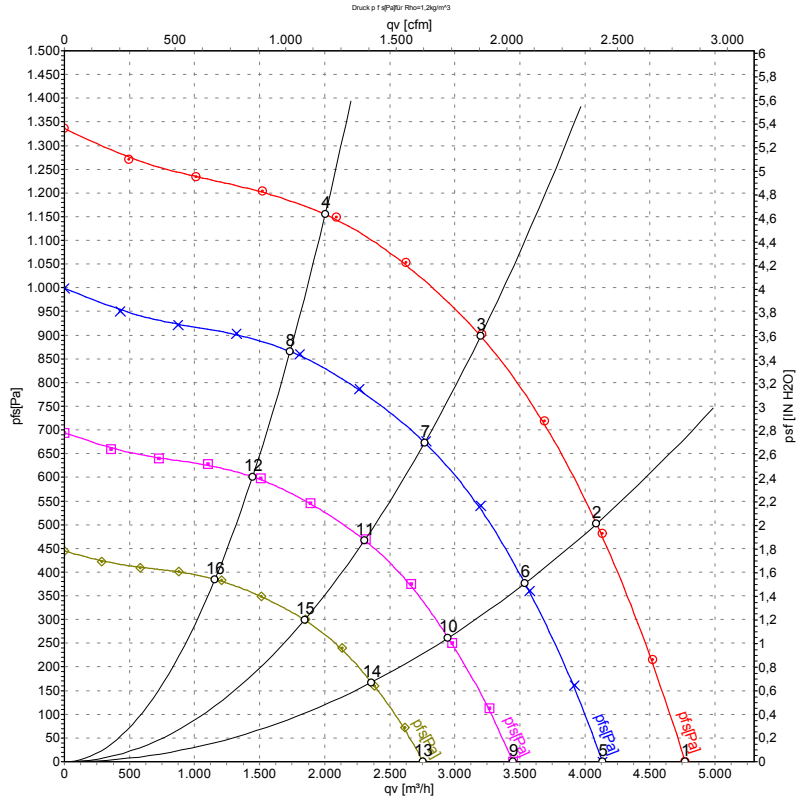
No.	Pin	Signal	Function / assignment
KL 3	14	Aout	Analogue output 0-10 V; max. 5 mA; output of the actual motor control factor (output voltage of electronics)/ of the actual motor speed.

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Charts: Air flow 50 Hz



Measurement: LU-129227

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	qv	p_{fs}
	V	Hz	min^{-1}	W	A	m^3/h	Pa
1	400	50	2800	888	1.44	4770	0
2	400	50	2800	1234	1.95	4085	500
3	400	50	2800	1500	2.40	3200	900
4	400	50	2800	1270	2.02	2005	1150
5	400	50	2400	578	0.94	4135	0
6	400	50	2400	799	1.26	3540	379
7	400	50	2400	895	1.41	2770	679
8	400	50	2400	824	1.31	1735	867
9	400	50	2000	335	0.54	3445	0
10	400	50	2000	462	0.73	2950	263
11	400	50	2000	518	0.82	2305	471
12	400	50	2000	477	0.76	1445	602
13	400	50	1600	171	0.28	2755	0
14	400	50	1600	237	0.37	2360	168
15	400	50	1600	265	0.42	1845	302
16	400	50	1600	244	0.39	1155	386

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · qv = Air flow · p_{fs} = Pressure increase

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