A3G630-AQ31-90

EC axial fan - HyBlade

sickle-shaped blades (S series)

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**A3G630-AQ31-90**
Motor	**M3G112-GA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	1080
Power consumption	W	825
Current draw	A	1.4
Max. back pressure	Pa	150
Max. back pressure	inH2O	0.6
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	45.6	33.1
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		52.5	40
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	0.8
09 Air flow q_v	m^3/h	8735
09 Pressure increase p_{fs}	Pa	140
10 Speed (rpm) n	min^{-1}	1080
11 Specific ratio*		1.00

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-124642

ebmpapst

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Technical description

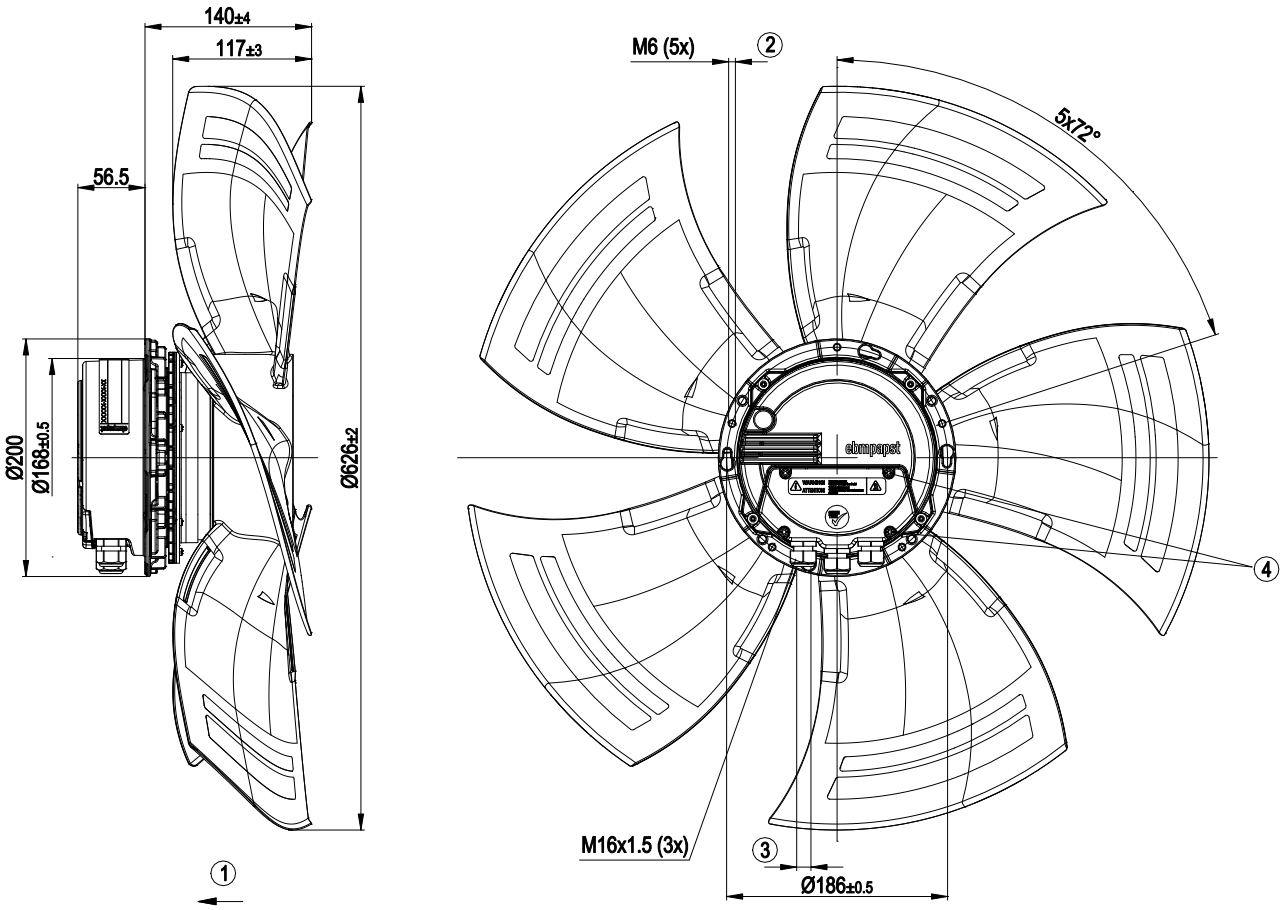
Weight	13 kg
Fan size	630 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Press-fitted sheet steel blank, sprayed with PP plastic
Number of blades	5
Airflow direction	"V"
Direction of rotation	Counterclockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+ 80 °C
Min. permitted ambient temp. for motor (transport/storage)	- 40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC; UL 1004-7 + 60730

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Product drawing



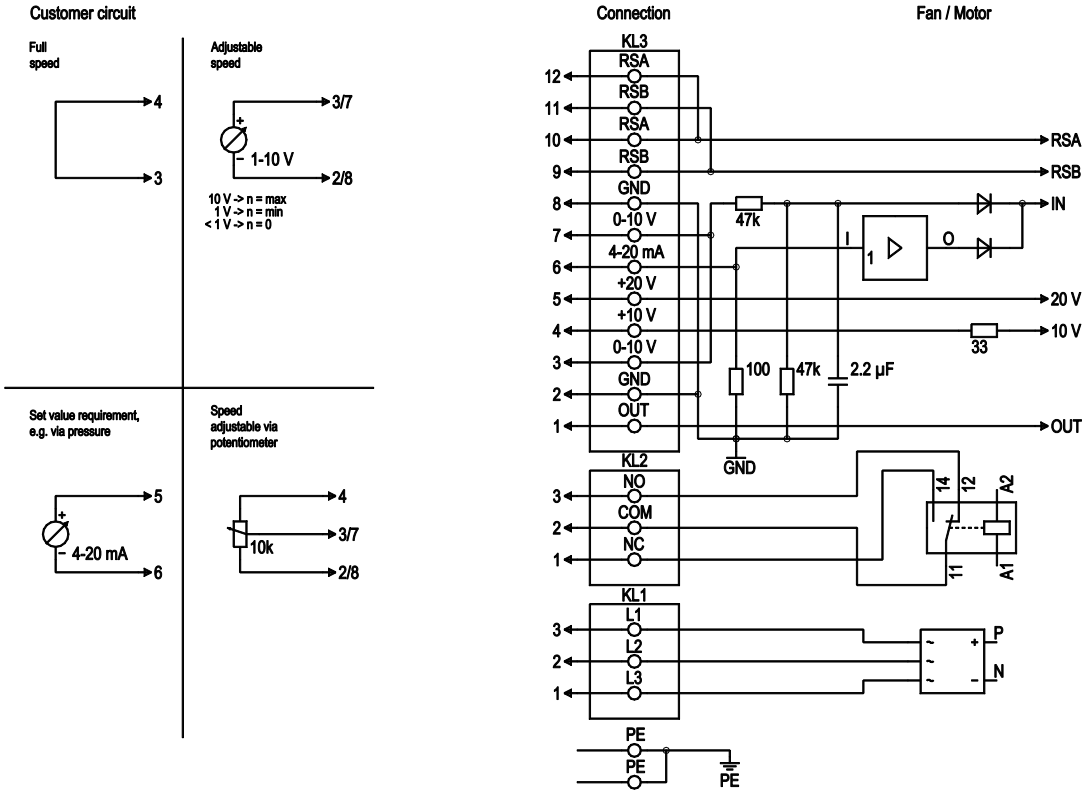
1	Direction of air flow "V"
2	Max. clearance for screw 16 mm
3	Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5±0.4 Nm
4	Tightening torque 3.5 ± 0.5 Nm

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Connection diagram



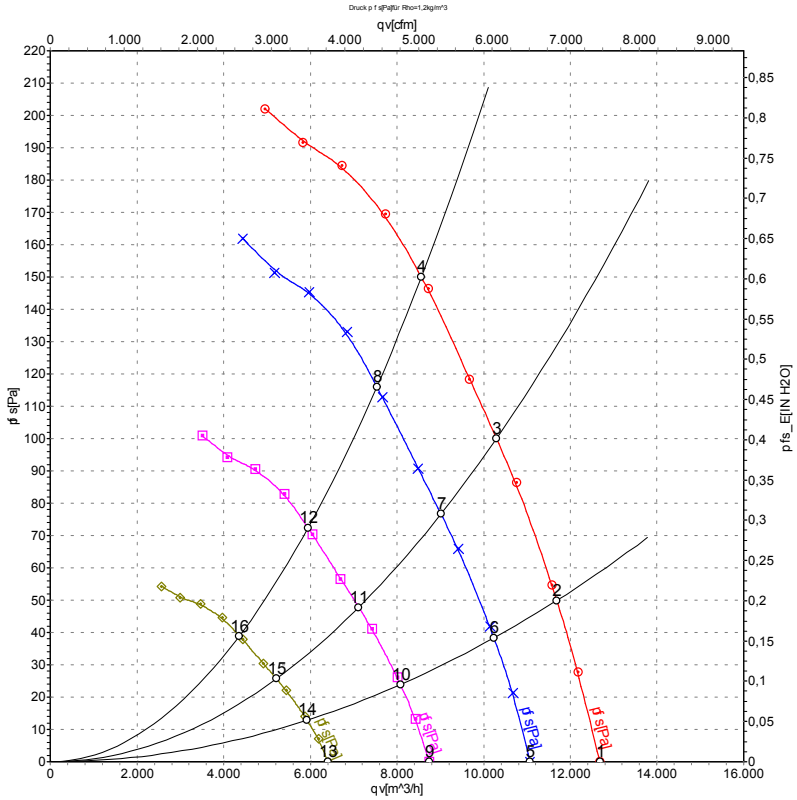
No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply, voltage range (see nameplate), 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

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Curves: Air performance 50 Hz



Measurement: LU-124642-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	m^3/h	Pa	CFM	inH2O
1	400	50	1090	548	0.91	12680	0	7465	0.00
2	400	50	1085	637	1.04	11690	50	6880	0.20
3	400	50	1085	732	1.18	10300	100	6060	0.40
4	400	50	1080	825	1.40	8565	150	5040	0.60
5	400	50	950	365	0.60	11070	0	6515	0.00
6	400	50	950	428	0.70	10240	38	6025	0.15
7	400	50	950	492	0.79	9015	77	5305	0.31
8	400	50	950	554	0.90	7535	116	4435	0.47
9	400	50	750	180	0.30	8740	0	5145	0.00
10	400	50	750	210	0.34	8080	24	4755	0.10
11	400	50	750	242	0.39	7120	48	4190	0.19
12	400	50	750	272	0.44	5950	72	3500	0.29
13	400	50	550	71	0.12	6410	0	3775	0.00
14	400	50	550	83	0.14	5925	13	3490	0.05
15	400	50	550	95	0.15	5220	26	3070	0.10
16	400	50	550	107	0.18	4360	39	2565	0.16

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · qv = Air flow · p_{fs} = Pressure increase

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