K3G400-HB41-01

EC centrifugal module - RadiPac

backward-curved, single-intake

with support bracket

ebm-papst Mulfingen GmbH & Co. KG
Bachmühle 2 · D-74673 Mulfingen
Phone +49 7938 81-0
Fax +49 7938 81-110
info1@de.ebmpapst.com
www.ebmpapst.com

Limited partnership · Headquarters Mulfingen
Amtsgericht (court of registration) Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen
Amtsgericht (court of registration) Stuttgart · HRB 590142

Nominal data

Type	**K3G400-HB41-01**
Motor	**M3G150-IF**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min^{-1}	3700
Power consumption	W	6000
Current draw	A	9.1
Min. ambient temperature	°C	-40
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	62	59.6
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		64.4	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	5.9
09 Air flow q_v	m^3/h	6810
09 Pressure increase p_{fs}	Pa	1881
10 Speed (rpm) n	min^{-1}	3710
11 Specific ratio*		1.02

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

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Technical description

Weight	42 kg
Size	400 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Support bracket material	Steel, painted black
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H1
Ambient temperature note	Occasional start-up at temperatures between -40°C and -25°C is permitted. For continuous operation at ambient temperatures below -25°C (such as refrigeration applications), use must be made of a fan design with special low-temperature bearings.
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	See product drawing
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output for slave 0-10 V - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Power limiter - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	CSA C22.2 No. 77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730-1

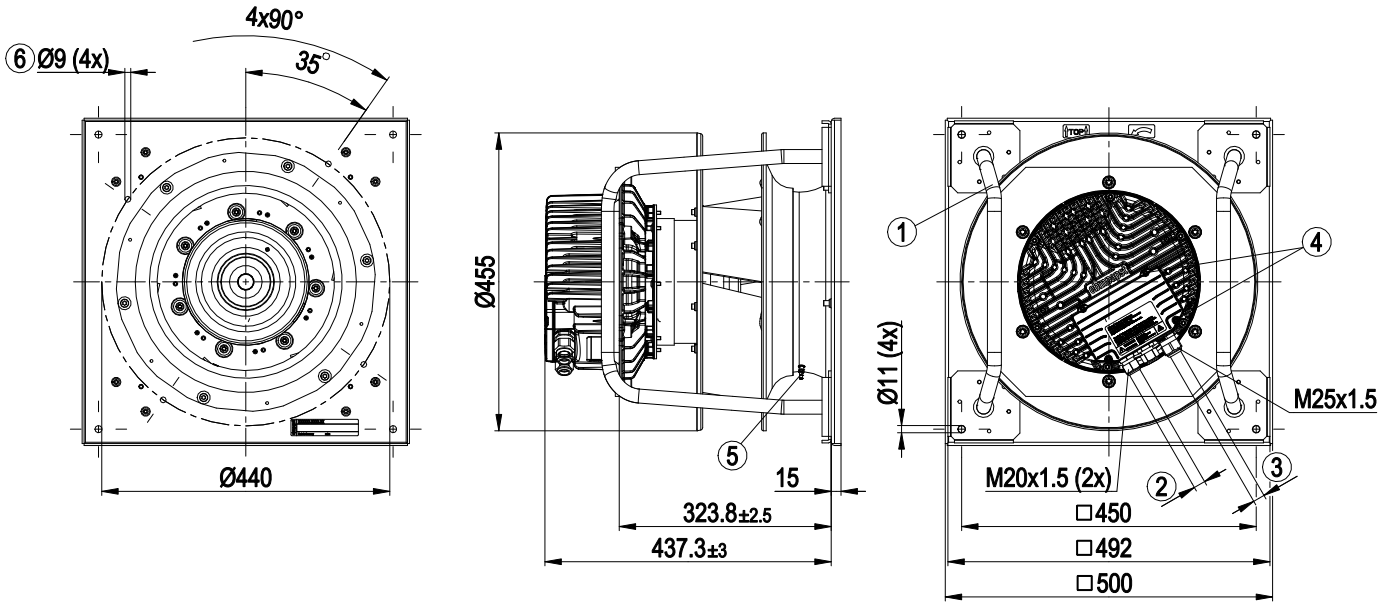
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Product drawing



1	Installed position: shaft horizontal (install support struts only vertically as illustrated) or rotor on bottom; rotor on top on request
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
3	Cable diameter min. 9 mm, max. 16 mm, tightening torque 6 ± 0.9 Nm
4	Tightening torque 3.5 ± 0.5 Nm
5	Inlet ring with pressure tap (k-factor: 188)
6	Mounting holes for FlowGrid

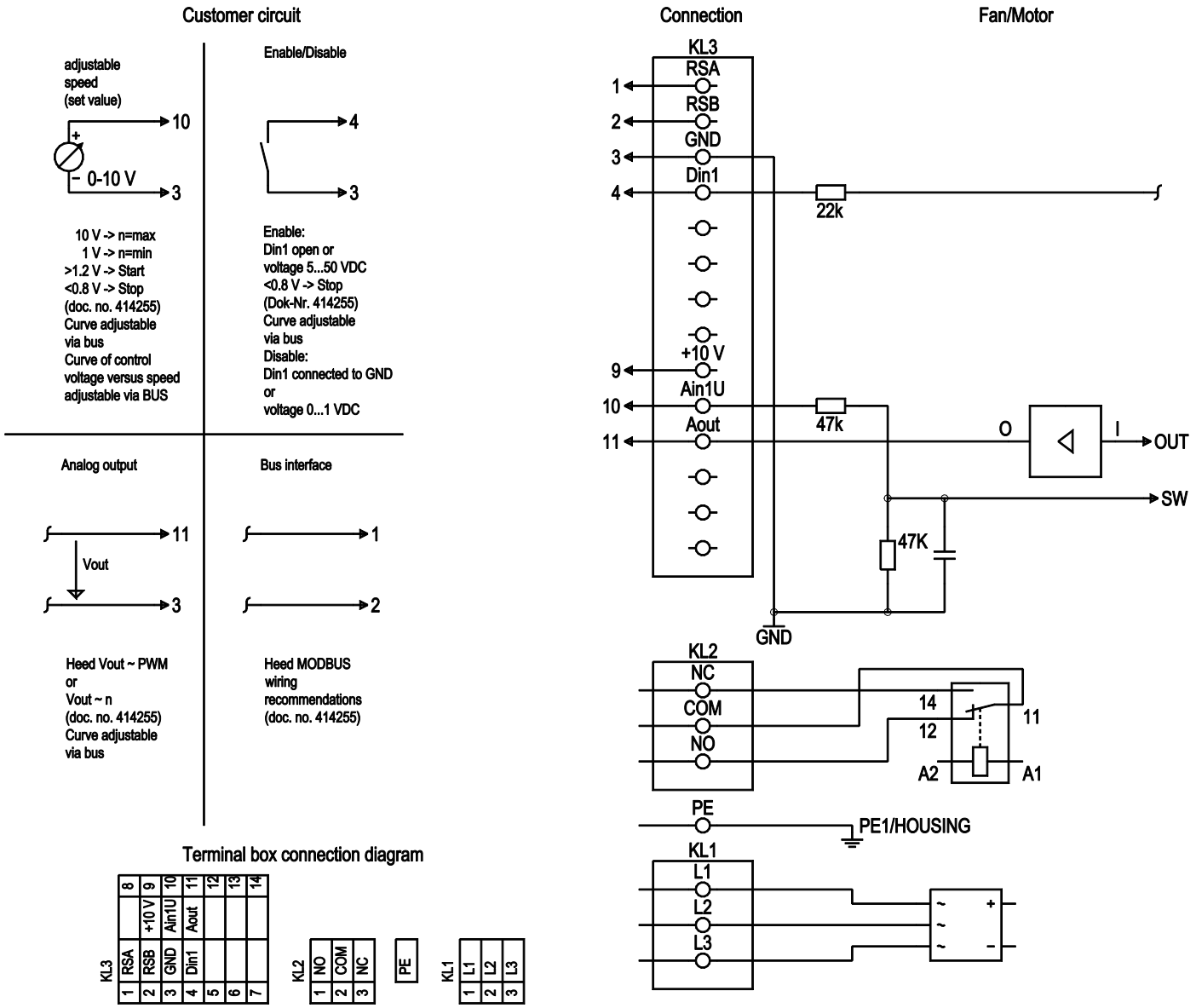
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Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1, 2, 3	L1, L2, L3	Power supply, phase, see nameplate for voltage range
PE	PE	PE	Protective earth
KL2	1	NO	Status relay, floating status contact, option 1: make for failure, option 2: make for error for run monitor
KL2	2	COM	Status relay, floating status contact, common connection, contact rating 250 VAC / 2 A (AC1) / min. 10 mA; basic insulation on supply side and reinforced insulation on control interface side
KL2	3	NC	Status relay, floating status contact, option 1: break for failure, option 2: break for error message for run monitor
KL 3	1	RSA	RS485 interface for MODBUS, RSA; SELV
KL 3	2	RSB	RS485 interface for MODBUS, RSB; SELV
KL 3	3	GND	Reference ground for control interface; SELV
KL 3	4	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV

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No.	Conn.	Designation	Function/assignment
KL 3	-	-	-
KL 3	-	-	-
KL3	-	-	-
KL3	-	-	-
KL 3	9	10 V / max. 10 mA	Voltage output, power supply for external devices (e.g. potentiometers), SELV
KL 3	10	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve; SELV
KL 3	11	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV
KL 3	-	-	-
KL 3	-	-	-
KL 3	-	-	-

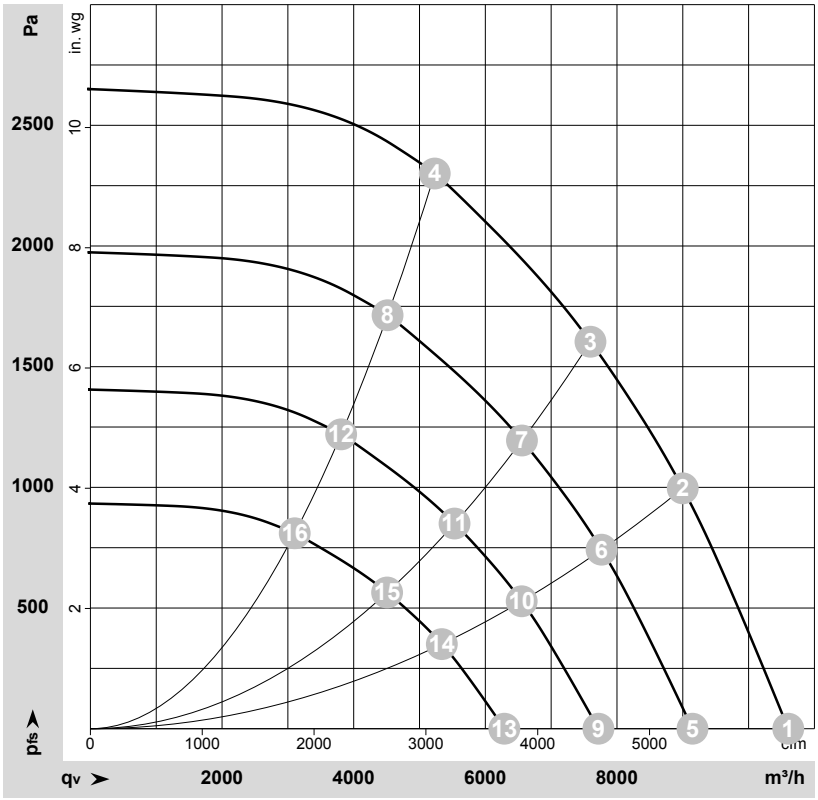
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Curves: Air performance 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-193984-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
		V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	3~	400	50	3700	3459	5.35	93	102	107	10600	0	6240	0.00
2	3~	400	50	3700	4915	7.50	88	97	103	9000	1000	5295	4.01
3	3~	400	50	3700	5657	8.62	87	94	101	7595	1600	4470	6.42
4	3~	400	50	3700	6000	9.10	88	95	101	5230	2300	3080	9.23
5	3~	400	50	3200	2221	3.43	90	98	103	9145	0	5385	0.00
6	3~	400	50	3200	3159	4.82	85	93	99	7765	757	4570	3.04
7	3~	400	50	3200	3636	5.54	83	91	97	6555	1198	3860	4.81
8	3~	400	50	3200	3845	5.85	84	92	98	4515	1713	2655	6.88
9	3~	400	50	2700	1334	2.06	85	94	99	7720	0	4545	0.00
10	3~	400	50	2700	1898	2.90	80	89	95	6555	539	3855	2.16
11	3~	400	50	2700	2184	3.33	79	86	93	5530	853	3255	3.42
12	3~	400	50	2700	2309	3.52	80	87	93	3810	1220	2240	4.90
13	3~	400	50	2200	722	1.12	80	89	94	6290	0	3700	0.00
14	3~	400	50	2200	1027	1.57	75	83	89	5340	358	3140	1.44
15	3~	400	50	2200	1181	1.80	74	81	88	4510	566	2655	2.27
16	3~	400	50	2200	1249	1.90	75	82	88	3105	810	1825	3.25

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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