K3G450-PA23-B2

EC centrifugal module

backward-curved, single-intake

with support bracket

ebm-papst Mulfingen GmbH & Co. KG
Bachmühle 2 · D-74673 Mulfingen
Phone +49 7938 81-0
Fax +49 7938 81-110
info1@de.ebmpapst.com
www.ebmpapst.com

Limited partnership · Headquarters Mulfingen
Amtsgericht (court of registration) Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen
Amtsgericht (court of registration) Stuttgart · HRB 590142

Nominal data

Type	**K3G450-PA23-B2**
Motor	**M3G150-FF**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	2140
Power consumption	W	2900
Current draw	A	4.5
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	55

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	70.1	56.3
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		75.7	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	2.89
09 Air flow q_v	m^3/h	6655
09 Pressure increase p_{fs}	Pa	1050
10 Speed (rpm) n	min^{-1}	2155
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-175860

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Technical description

Weight	37.5 kg
Size	450 mm
Motor size	150
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Impeller material	Sheet aluminum, painted black
Support plate material	Sheet steel, galvanized and painted black
Support bracket material	Steel, galvanized and painted black
Inlet nozzle material	Sheet steel, galvanized and painted black
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H2+S
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	See product drawing
Condensation drainage holes	On stator side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used equipment with a total rated power greater than 1 kW
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC

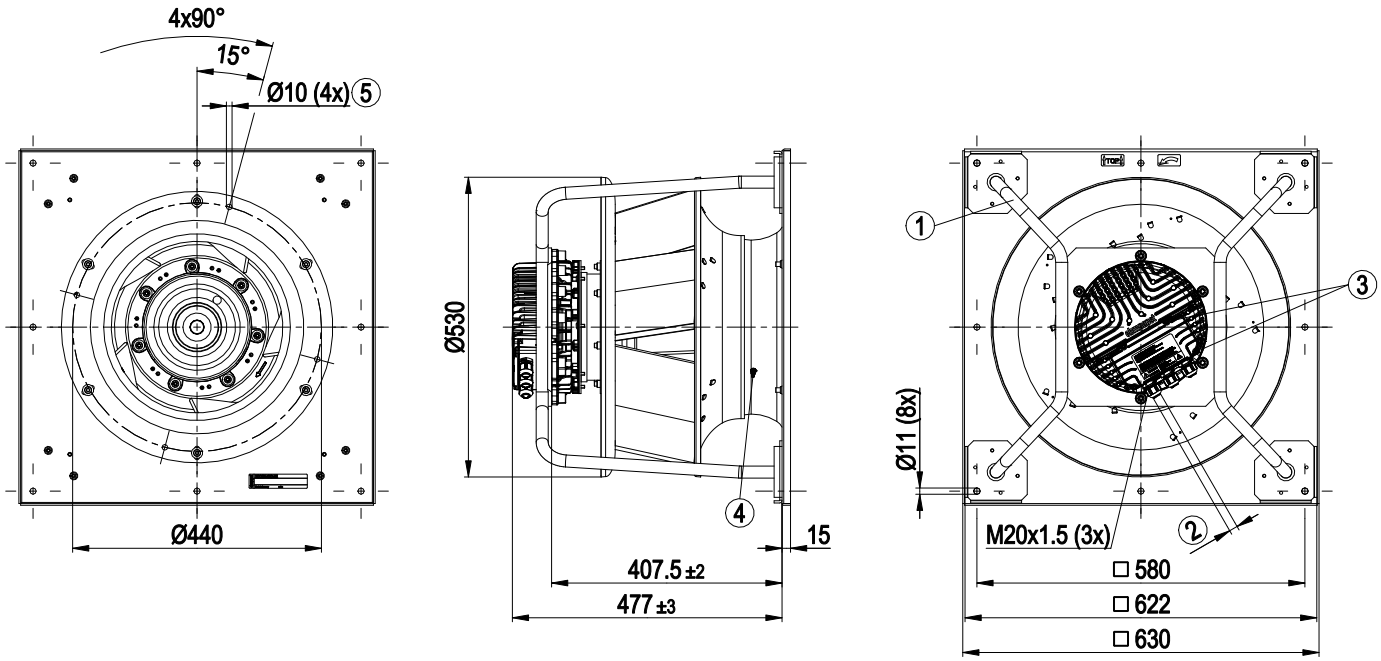
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Product drawing



1	Installation position: Shaft horizontal (only install support struts vertically as illustrated) or rotor on top, rotor on bottom on request
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
3	Tightening torque 3.5 ± 0.5 Nm
4	Inlet ring with pressure tap (k-factor: 240)
5	Mounting holes for FlowGrid

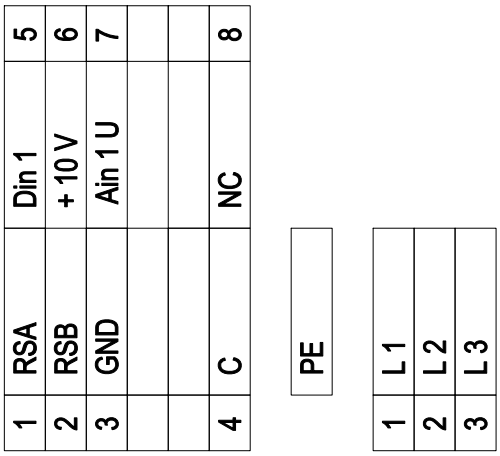
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Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 2	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 2	3	GND	Reference ground for control interface; SELV
KL2	4	C	Status relay, floating status contact, break for failure; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL 2	5	Din1	Digital input 1 enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 V; SELV
KL 2	6	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); SELV Or: +24 VDC input for parameter setting via MODBUS without line voltage
KL 2	7	Ain1 U	Analog input 1 (set value) 0-10 V, Ri = 100 kΩ, adjustable curve; SELV
KL2	8	NC	Status relay, floating status contact, break for failure

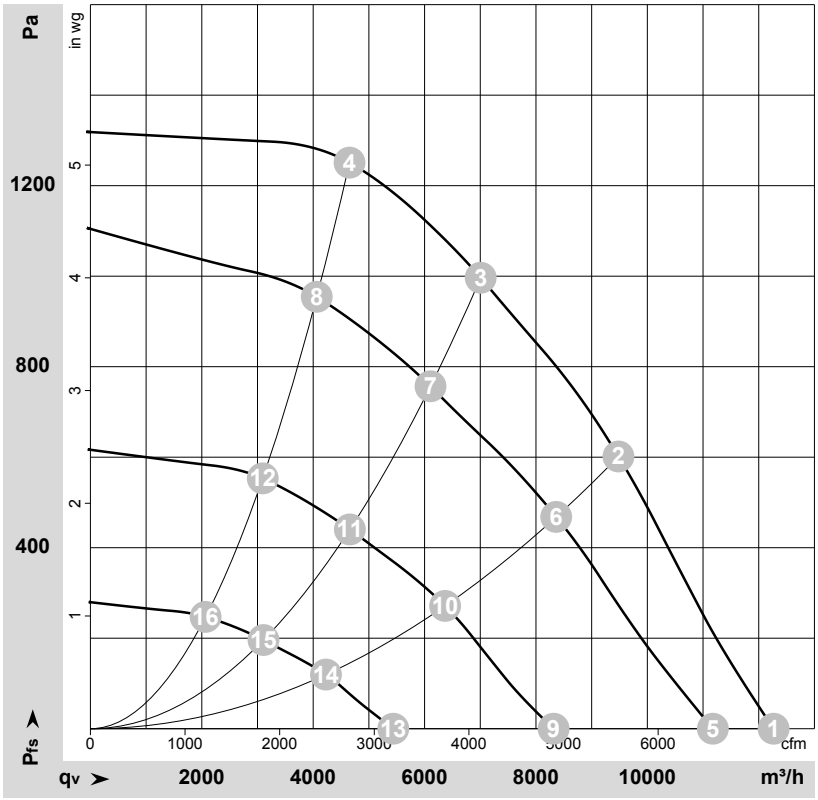
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Curves: Air performance 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-175860-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	400	50	2140	1709	2.69	89	96	95	12265	0	7220	0.00
2	400	50	2140	2655	4.09	78	85	88	9480	600	5580	2.41
3	400	50	2140	2900	4.50	74	81	87	7010	1000	4125	4.01
4	400	50	2140	2763	4.25	79	86	90	4655	1250	2740	5.02
5	400	50	1960	1302	2.11	86	93	93	11175	0	6580	0.00
6	400	50	1890	1825	2.87	74	82	85	8365	469	4925	1.88
7	400	50	1875	1938	3.03	71	78	83	6105	757	3595	3.04
8	400	50	1885	1851	2.90	75	82	87	4065	954	2390	3.83
9	400	50	1470	580	1.14	79	87	87	8315	0	4895	0.00
10	400	50	1435	827	1.45	68	75	79	6370	272	3750	1.09
11	400	50	1430	879	1.52	65	72	77	4660	440	2740	1.77
12	400	50	1435	840	1.47	68	75	80	3095	553	1820	2.22
13	400	50	980	208	0.57	66	75	76	5440	0	3200	0.00
14	400	50	960	277	0.69	57	65	69	4230	121	2490	0.49
15	400	50	955	295	0.72	56	63	68	3110	196	1830	0.79
16	400	50	960	283	0.70	58	65	70	2070	247	1215	0.99

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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