**K3G500-AF34-01**

# EC centrifugal module

backward-curved, single-intake

with support plate

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ErP2015 EXCEEDS THE NORM

## Nominal data

| | |
|---|---|
| **Type** | **K3G500-AF34-01** |
| **Motor** | **M3G112-GA** |

| | | |
|---|---|---|
| Phase | | 3~ |
| Nominal voltage | VAC | 400 |
| Nominal voltage range | VAC | 380 .. 480 |
| Frequency | Hz | 50/60 |
| Speed (rpm) | $min^{-1}$ | 1160 |
| Power consumption | W | 810 |
| Current draw | A | 1.55 |
| Max. ambient temperature | °C | 60 |

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

## Data according to ErP Directive

| | | Actual | Req. 2015 |
|---|---|---|---|
| 01 Overall efficiency $\eta_{es}$ | % | 61.7 | 50.4 |
| 02 Measurement category | | A | |
| 03 Efficiency category | | Static | |
| 04 Efficiency grade N | | 73.3 | 62 |
| 05 Variable speed drive | | Yes | |

| | | |
|---|---|---|
| 09 Power consumption $P_{ed}$ | kW | 0.79 |
| 09 Air flow $q_v$ | $m^3/h$ | 5405 |
| 09 Pressure increase $p_{fs}$ | Pa | 300 |
| 10 Speed (rpm) n | $min^{-1}$ | 1160 |
| 11 Specific ratio* | | 1.00 |

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + $p_{fs}$ / 100 000 Pa

LU-74028

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## Technical description

| | |
|---|---|
| **Weight** | 28.0 kg |
| **Fan size** | 500 mm |
| **Electronics housing material** | Die-cast aluminum, painted black |
| **Impeller material** | Sheet aluminum |
| **Support plate material** | Sheet steel, galvanized |
| **Spacer material** | Aluminum |
| **Inlet nozzle material** | Sheet steel, galvanized |
| **Number of blades** | 9 |
| **Direction of rotation** | Clockwise, viewed toward rotor |
| **Degree of protection** | IP54 |
| **Insulation class** | "B" |
| **Moisture (F) / Environmental (H) protection class** | F4-1 |
| **Max. permitted ambient temp. for motor (transport/storage)** | +80 °C |
| **Min. permitted ambient temp. for motor (transport/storage)** | -40 °C |
| **Installation position** | Shaft horizontal or rotor on bottom; rotor on top on request |
| **Mode** | S1 |
| **Motor bearing** | Ball bearing |
| **Technical features** | - Output 10 VDC, max. 10 mA<br>- Output 20 VDC, max. 50 mA<br>- Output for slave 0-10 V<br>- Input for sensor 0-10 V or 4-20 mA<br>- Alarm relay<br>- Integrated PID controller<br>- Motor current limitation<br>- PFC, passive<br>- RS-485 ebmBUS<br>- Soft start<br>- Control input 0-10 VDC / PWM<br>- Control interface with SELV potential safely disconnected from the mains<br>- Thermal overload protection for electronics/motor<br>- Line undervoltage / phase failure detection |
| **EMC immunity to interference** | According to EN 61000-6-2 (industrial environment) |
| **EMC circuit feedback** | According to EN 61000-3-2/3 |
| **EMC interference emission** | According to EN 61000-6-3 (household environment) |
| **Electrical hookup** | Via terminal box |
| **Motor protection** | Thermal overload protector (TOP) internally connected |
| **Protection class** | I (with customer connection of protective earth) |
| **Conformity with standards** | EN 61800-5-1; CE |
| **Approval** | EAC |



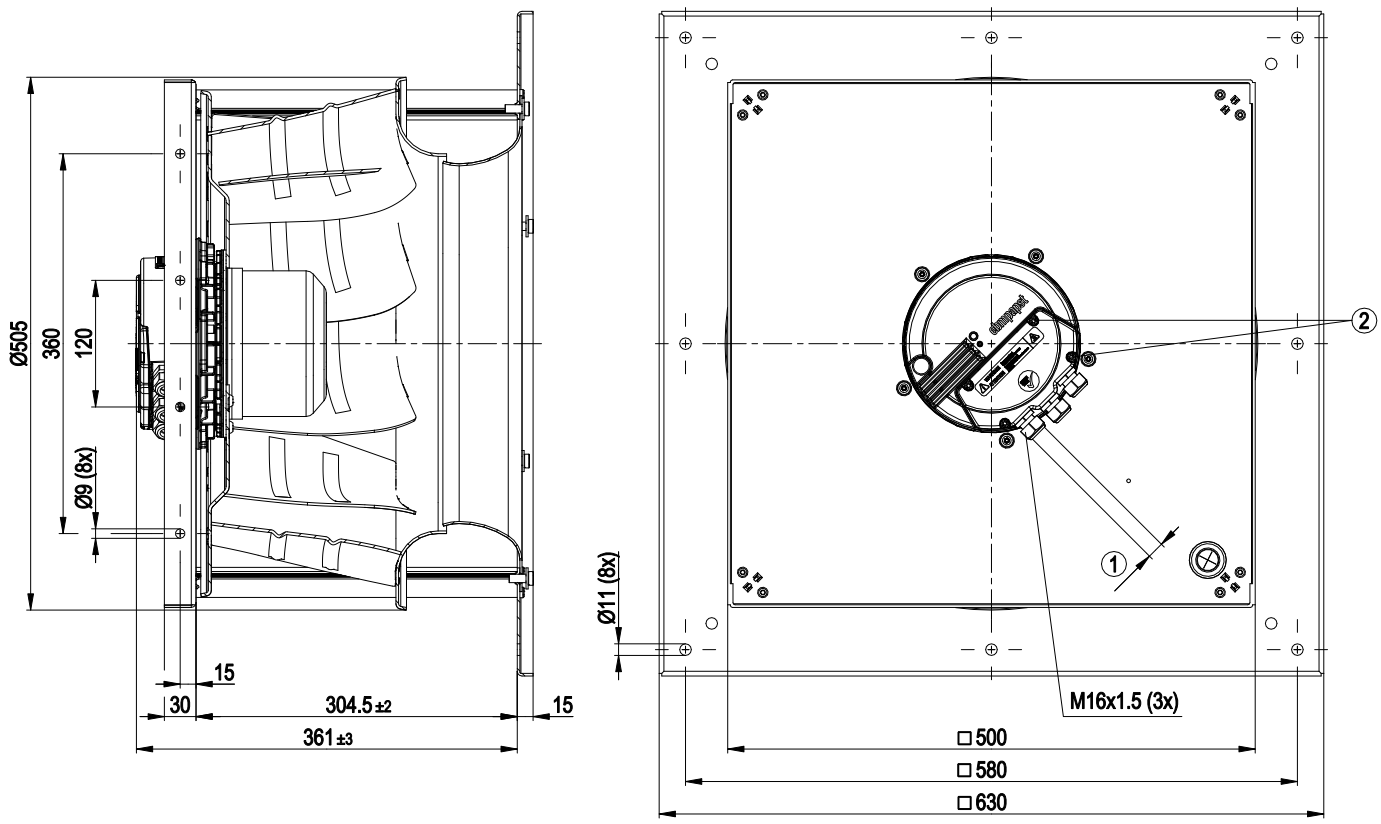
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## Product drawing




| | |
|---|---|
| 1 | Cable diameter min. 4 mm, max. 10 mm, tightening torque 2.5 ± 0.4 Nm |
| 2 | Tightening torque 3.5 ± 0.5 Nm |



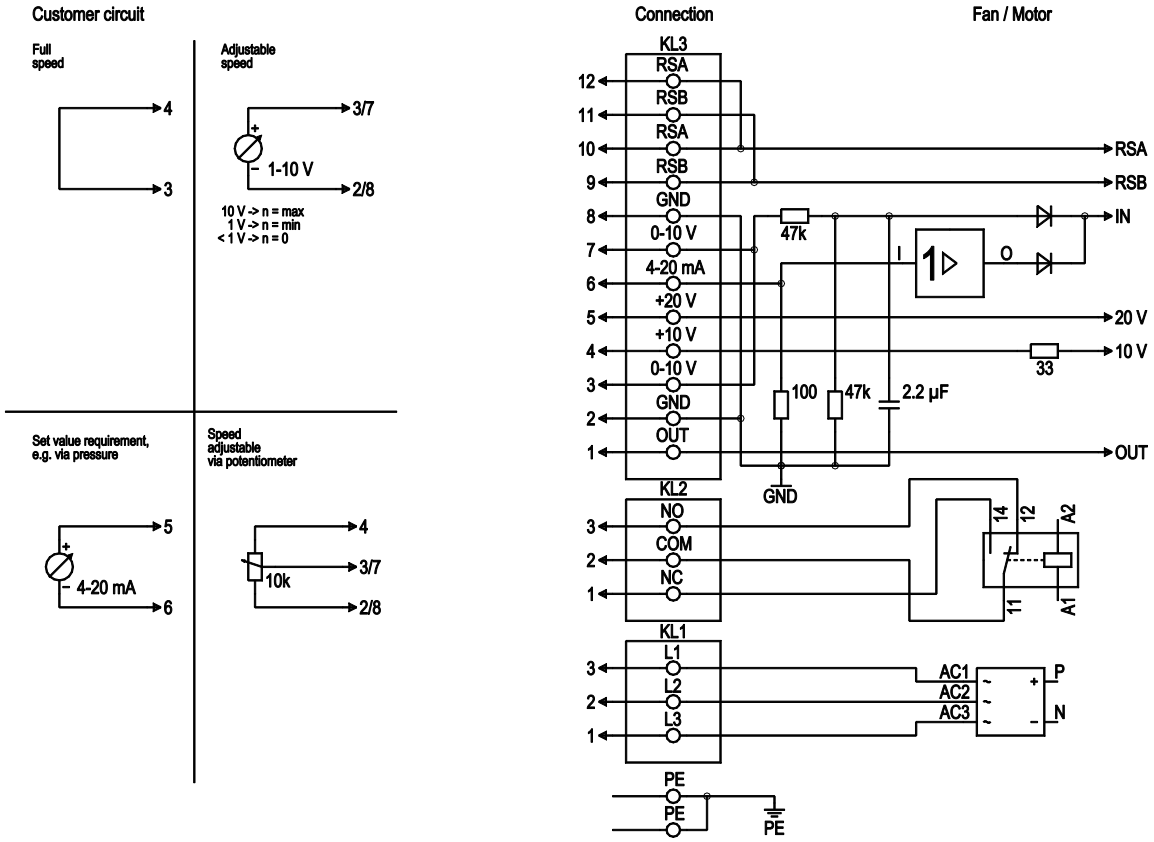
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## Connection diagram




| No. | Conn. | Designation | Function/assignment |
|---|---|---|---|
| PE | | PE | Protective earth terminal |
| KL1 | 1, 2, 3 | L1, L2, L3 | Power supply 50/60 Hz |
| KL2 | 1 | NC | Floating status contact, break for failure |
| KL2 | 2 | COM | floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1) |
| KL2 | 3 | NO | Floating status contact, make for failure |
| KL3 | 1 | OUT | Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level. |
| KL3 | 2, 8 | GND | Reference ground for control interface, SELV |
| KL3 | 3, 7 | 0-10 V | Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV |
| KL3 | 4 | +10 V | Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV |
| KL3 | 5 | +20 V | Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV |
| KL3 | 6 | 4-20 mA | Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV |
| KL3 | 9, 11 | RSB | RS485 interface for ebmBUS, RSB, SELV |
| KL3 | 10, 12 | RSA | RS485 interface for ebmBUS, RSA, SELV |



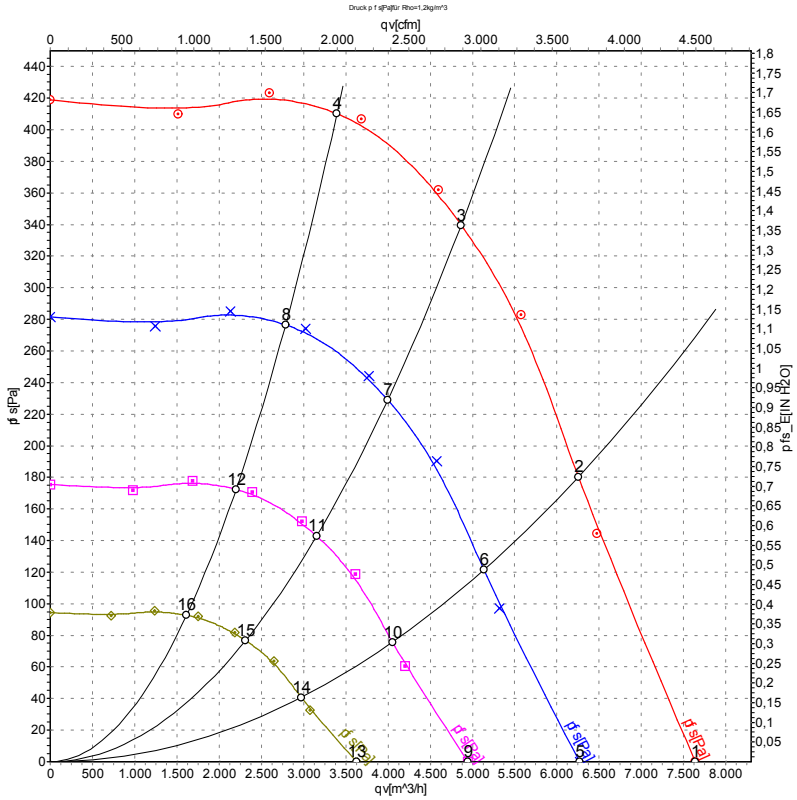
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## Curves: Air performance 50 Hz




Measurement: LU-105321-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

## Measured values

| | U | f | n | $P_{ed}$ | I | $LpA_{in}$ | $LwA_{in}$ | $LwA_{out}$ | qv | $p_{fs}$ | qv | $p_{fs}$ |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| | V | Hz | $min^{-1}$ | W | A | dB(A) | dB(A) | dB(A) | $m^3/h$ | Pa | CFM | inH2O |
| 1 | 400 | 50 | 1160 | 563 | 0.96 | 76 | 83 | 86 | 7640 | 0 | 4495 | 0.00 |
| 2 | 400 | 50 | 1160 | 721 | 1.22 | 69 | 76 | 80 | 6255 | 180 | 3680 | 0.72 |
| 3 | 400 | 50 | 1160 | 810 | 1.55 | 64 | 71 | 77 | 4865 | 340 | 2865 | 1.36 |
| 4 | 400 | 50 | 1160 | 726 | 1.22 | 64 | 72 | 77 | 3395 | 410 | 2000 | 1.65 |
| 5 | 400 | 50 | 950 | 311 | 0.53 | 72 | 79 | 81 | 6265 | 0 | 3690 | 0.00 |
| 6 | 400 | 50 | 950 | 399 | 0.67 | 65 | 72 | 76 | 5135 | 120 | 3020 | 0.48 |
| 7 | 400 | 50 | 950 | 445 | 0.73 | 60 | 67 | 73 | 3995 | 229 | 2350 | 0.92 |
| 8 | 400 | 50 | 950 | 402 | 0.68 | 60 | 67 | 73 | 2785 | 277 | 1640 | 1.11 |
| 9 | 400 | 50 | 750 | 153 | 0.26 | 67 | 74 | 76 | 4945 | 0 | 2910 | 0.00 |
| 10 | 400 | 50 | 750 | 196 | 0.33 | 60 | 67 | 71 | 4055 | 75 | 2385 | 0.30 |
| 11 | 400 | 50 | 750 | 219 | 0.36 | 55 | 62 | 68 | 3155 | 143 | 1855 | 0.57 |
| 12 | 400 | 50 | 750 | 198 | 0.33 | 55 | 62 | 68 | 2200 | 173 | 1295 | 0.69 |
| 13 | 400 | 50 | 550 | 60 | 0.10 | 60 | 67 | 69 | 3630 | 0 | 2135 | 0.00 |
| 14 | 400 | 50 | 550 | 77 | 0.13 | 53 | 60 | 64 | 2975 | 40 | 1750 | 0.16 |
| 15 | 400 | 50 | 550 | 86 | 0.14 | 48 | 55 | 61 | 2315 | 77 | 1360 | 0.31 |
| 16 | 400 | 50 | 550 | 78 | 0.13 | 48 | 55 | 61 | 1615 | 93 | 950 | 0.37 |

U = Power supply · f = Frequency · n = Speed (rpm) · $P_{ed}$ = Power consumption · I = Current draw · $LpA_{in}$ = Sound pressure level intake side · $LwA_{in}$ = Sound power level intake side
$LwA_{out}$ = Sound power level outlet side · qv = Air flow · $p_{fs}$ = Pressure increase



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