S3G630-AQ48-09

EC axial fan - HyBlade

sickle-shaped blades (S series)

with guard grille for short nozzle

ebm-papst Mulfingen GmbH & Co. KG
Bachmühle 2 · D-74673 Mulfingen
Phone +49 7938 81-0
Fax +49 7938 81-110
info1@de.ebmpapst.com
www.ebmpapst.com

Limited partnership · Headquarters Mulfingen
Amtsgericht (court of registration) Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen
Amtsgericht (court of registration) Stuttgart · HRB 590142

ErP2015 EXCEEDS THE NORM

Nominal data

Type	**S3G630-AQ48-09**
Motor	**M3G112-GA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min^{-1}	940
Power consumption	W	530
Current draw	A	0.95
Max. back pressure	Pa	110
Max. back pressure	inH2O	0.44
Min. ambient temperature	°C	-40
Max. ambient temperature	°C	65

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	46.2	31.8
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		54.4	40
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	0.51
09 Air flow q_v	m^3/h	7465
09 Pressure increase p_{fs}	Pa	105
10 Speed (rpm) n	min^{-1}	935
11 Specific ratio*		1.00

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-126010

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Technical description

Weight	15.4 kg
Fan size	630 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Press-fitted sheet steel blank, sprayed with PP plastic
Guard grille material	Steel, coated with black plastic (RAL 9005)
Number of blades	5
Airflow direction	"V"
Direction of rotation	Counterclockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H2
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - Cable break detection with control line - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC; UL 1004-7 + 60730

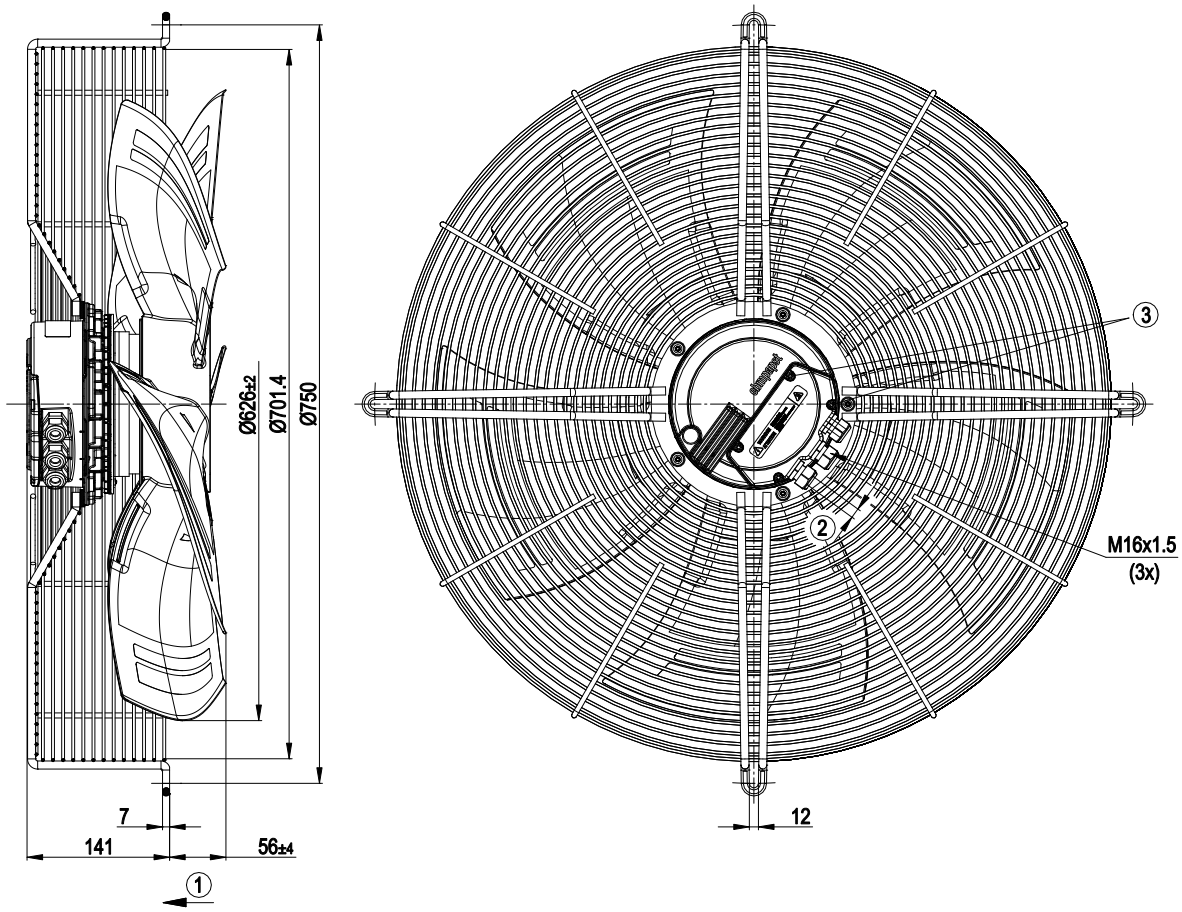
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Product drawing



1	Direction of air flow "V"
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 2.5 ± 0.4 Nm
3	Tightening torque 3.5 ± 0.5 Nm

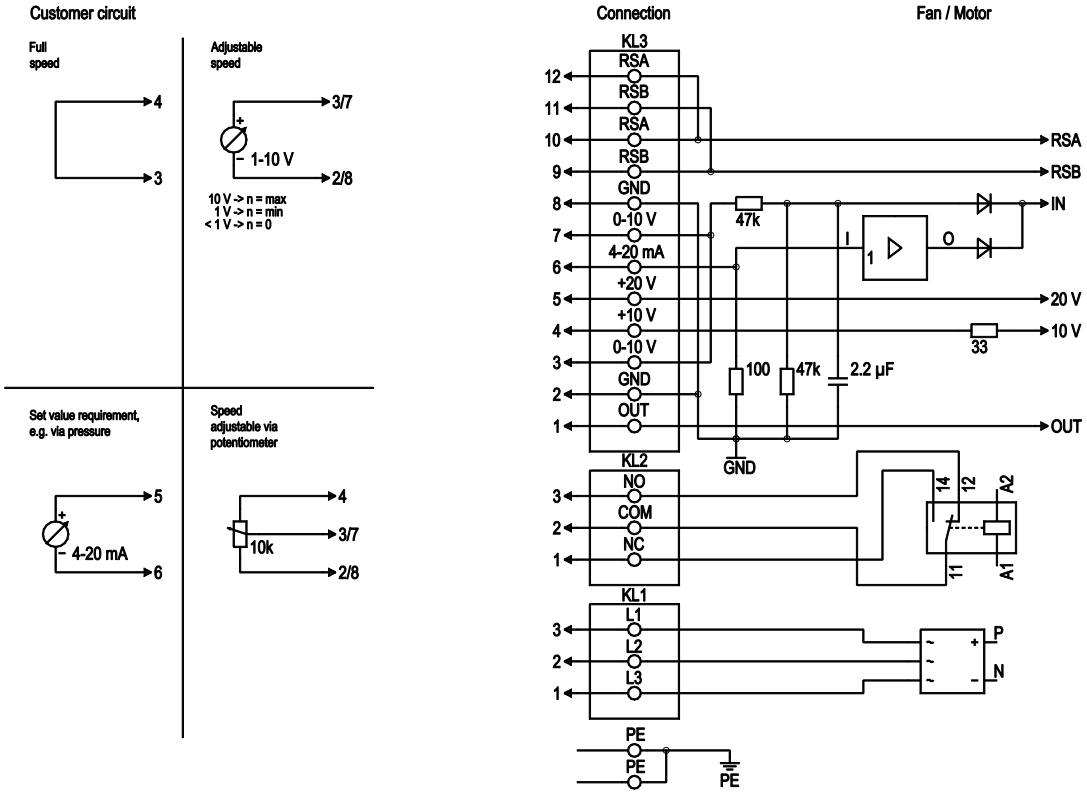
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Connection diagram



No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply, voltage range (see nameplate), 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

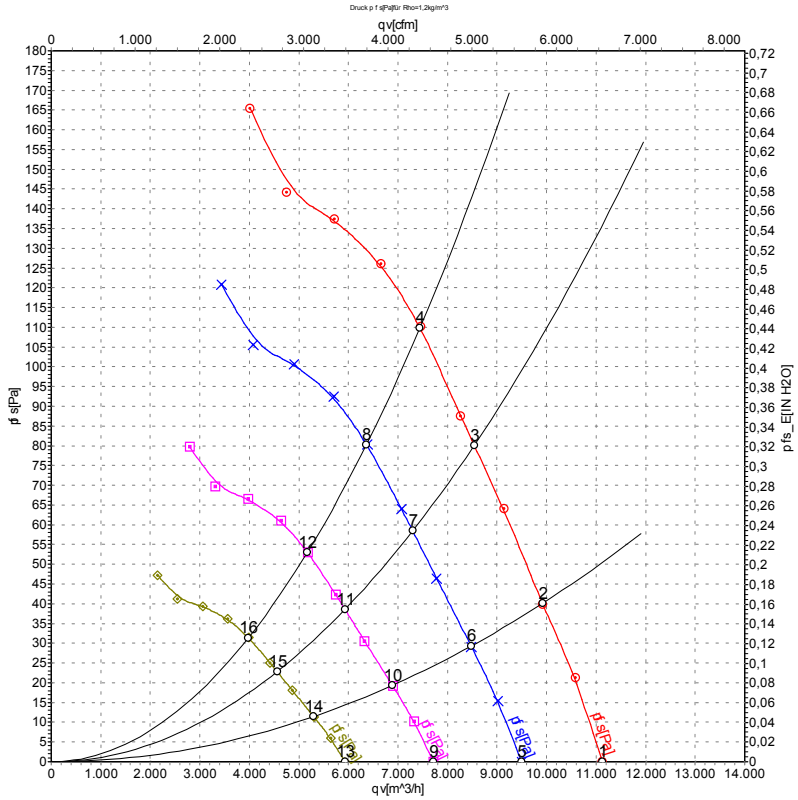
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Curves: Air performance 50 Hz



Measurement: LU-126010-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	400	50	940	351	0.68	67	74	74	11130	0	6550	0.00
2	400	50	940	405	0.75	67	73	73	9920	40	5840	0.16
3	400	50	940	472	0.83	64	71	71	8540	80	5025	0.32
4	400	50	940	530	0.95	63	70	70	7445	110	4380	0.44
5	400	50	800	217	0.42	64	71	71	9490	0	5585	0.00
6	400	50	800	254	0.47	63	70	70	8475	29	4990	0.12
7	400	50	800	294	0.52	60	68	67	7295	58	4295	0.23
8	400	50	800	325	0.57	59	67	66	6365	81	3745	0.33
9	400	50	650	117	0.23	59	66	66	7710	0	4540	0.00
10	400	50	650	136	0.25	59	66	65	6885	19	4055	0.08
11	400	50	650	158	0.28	56	63	63	5930	39	3490	0.16
12	400	50	650	174	0.30	55	62	62	5170	53	3045	0.21
13	400	50	500	53	0.10	54	61	60	5930	0	3490	0.00
14	400	50	500	62	0.11	53	60	60	5300	12	3120	0.05
15	400	50	500	72	0.13	50	57	57	4560	23	2685	0.09
16	400	50	500	79	0.14	49	56	56	3975	32	2340	0.13

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase

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