A3G630-AU31-71

EC axial fan - HyBlade

sickled blades (S series)

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Nominal data

Type	**A3G630-AU31-71**
Motor	**M3G150-IF**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min^{-1}	1510
Power input	W	3250
Current draw	A	5.0
Max. back pressure	Pa	320
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	65

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

		Actual	Request 2015
01 Overall efficiency η_{es}	%	40.7	36.8
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		43.9	40
05 Variable speed drive		Yes	

09 Power input P_{ed}	kW	3.17
09 Air flow q_v	m^3/h	15415
09 Pressure increase p_{fs}	Pa	287
10 Speed (rpm) n	min^{-1}	1505
11 Specific ratio*		1.00

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-176699

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Technical features

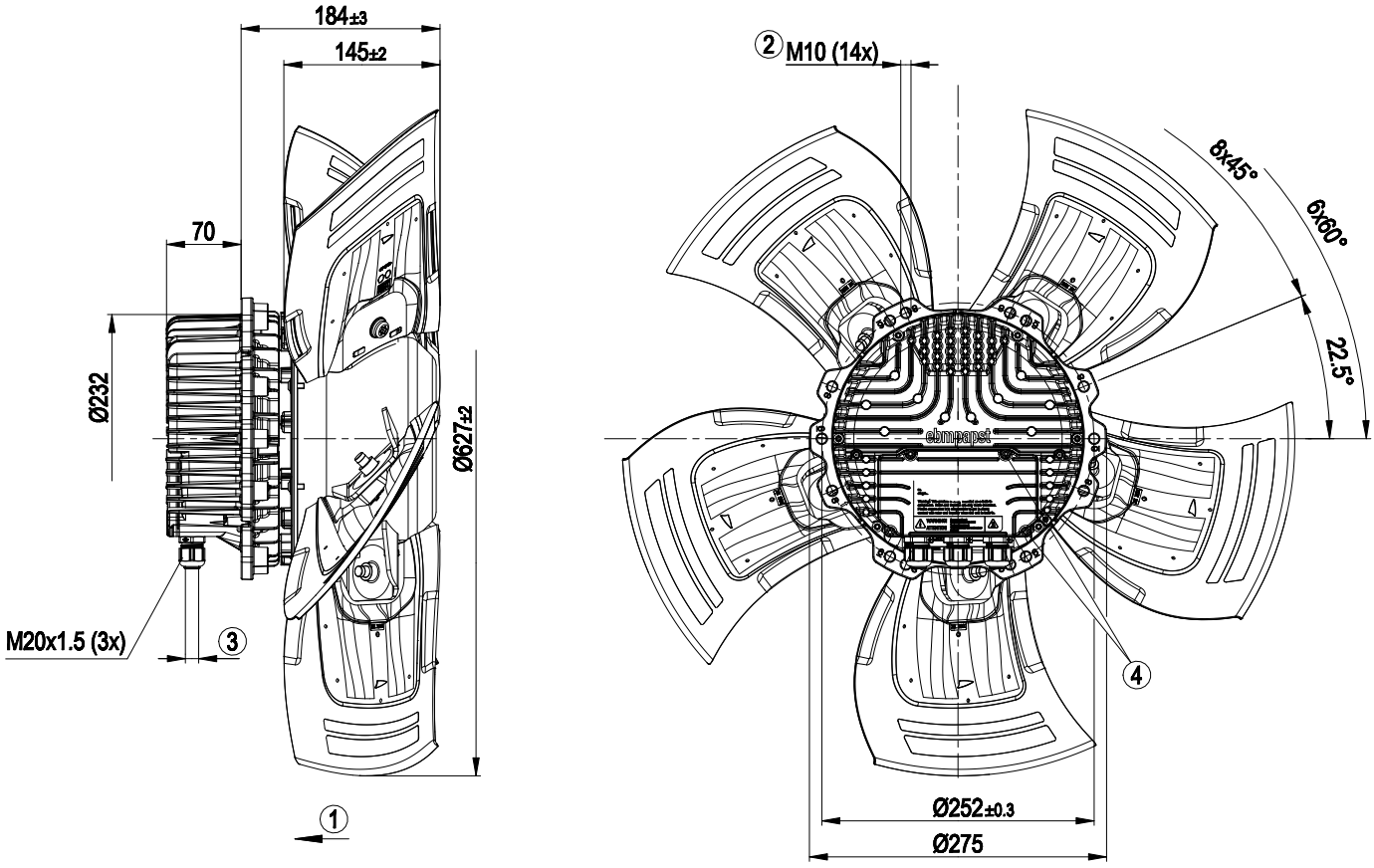
Mass	25.4 kg
Size	630 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Aluminium sheet insert, sprayed with PP plastic
Number of blades	5
Blade angle	0°
Direction of air flow	"V"
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 55
Insulation class	"F"
Humidity (F)/environmental protection class (H)	F4-1
Note ambient temperature	Occasional start-up between -40°C and -25°C is permissible. For continuous operation at ambient temperatures below -25°C (e.g. refrigeration applications) we recommend our fan version with special low-temperature bearings.
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used devices with a total rated power greater than 1 kW
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC

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Product drawing



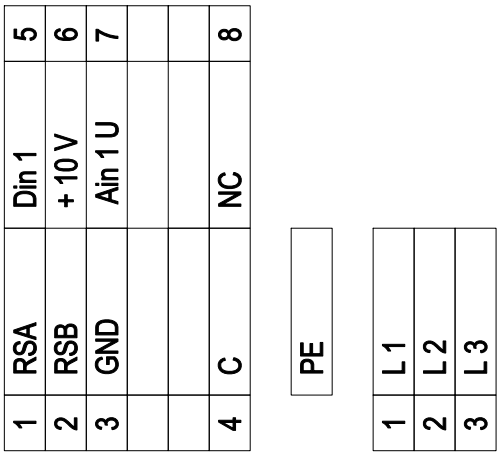
1	Direction of air flow "V"
2	Thread reach max. 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4±0.6 Nm
4	Tightening torque 3.5±0.5 Nm

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Connection screen



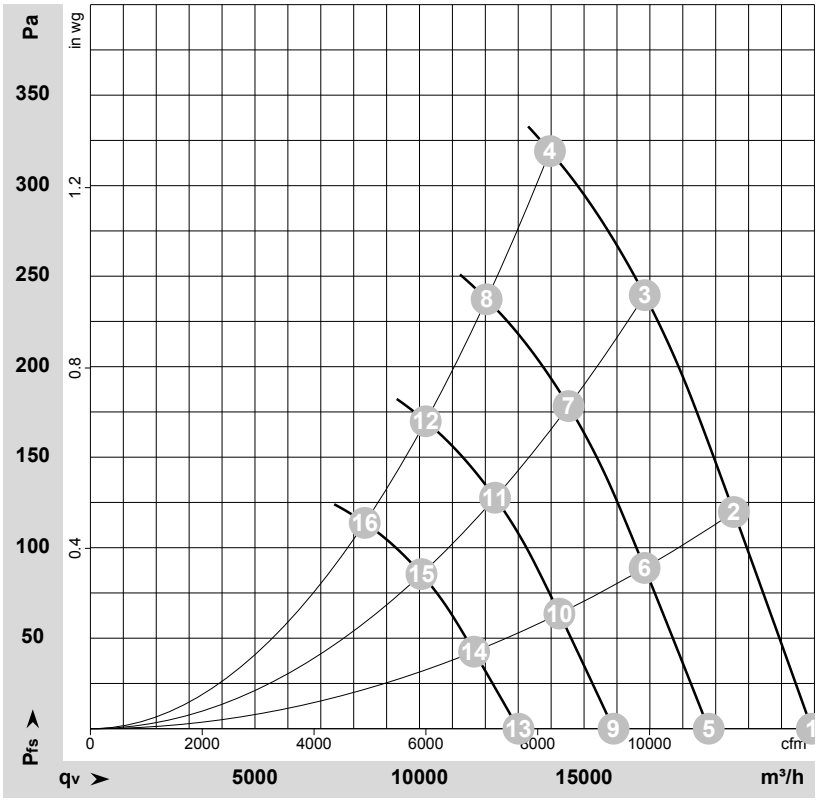
No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 2	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 2	3	GND	Signal ground for control interface; SELV
KL2	4	C	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / 2 A (AC1)
KL 2	5	Din1	Digital input 1 enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 V; SELV
KL 2	6	+ 10 V	Fixed voltage output 10 VDC; +10 V -3 %, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer); SELV Alternative: +24 VDC input for parametrisation via MODBUS without mains power
KL 2	7	Ain1 U	Analogue input 1 (set value) 0-10 V, Ri=100 kΩ, parametrisable curve; SELV
KL2	8	NC	Status relay, floating status contact; break for failure

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Charts: Air flow 50 Hz



ρ = 1.173 kg/m³ ± 2 %

Measurement: LU-176699-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	Conn.	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
		V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	inH2O
1	Y	400	50	1510	2589	4.00	74	82	83	21925	0	12905	0.00
2	Y	400	50	1510	2821	4.34	73	81	81	19550	120	11510	0.48
3	Y	400	50	1510	3071	4.71	74	81	81	16845	240	9915	0.96
4	Y	400	50	1510	3250	5.00	77	84	83	13965	320	8220	1.28
5	Y	400	50	1300	1630	2.52	70	78	79	18790	0	11060	0.00
6	Y	400	50	1300	1805	2.78	70	77	78	16840	90	9910	0.36
7	Y	400	50	1300	1971	3.03	70	77	77	14530	179	8550	0.72
8	Y	400	50	1300	2082	3.19	73	81	79	12040	237	7085	0.95
9	Y	400	50	1100	987	1.52	66	74	75	15895	0	9355	0.00
10	Y	400	50	1100	1094	1.68	65	73	73	14250	64	8385	0.26
11	Y	400	50	1100	1194	1.83	66	73	73	12295	128	7235	0.51
12	Y	400	50	1100	1261	1.93	69	76	75	10190	170	5995	0.68
13	Y	400	50	900	541	0.83	61	69	70	13005	0	7655	0.00
14	Y	400	50	900	599	0.92	60	68	68	11660	43	6860	0.17
15	Y	400	50	900	654	1.00	61	68	68	10060	86	5920	0.35
16	Y	400	50	900	691	1.06	64	71	70	8335	114	4905	0.46

Conn. = Connection · U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side
LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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