W3G710-DU21-02

EC axial fan - HyBlade

sickle-shaped blades (S series)

with square full nozzle

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**W3G710-DU21-02**
Motor	**M3G150-IF**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	1250
Power consumption	W	2830
Current draw	A	4.3
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	39.3	36.5
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		42.8	40
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	2.86
09 Air flow q_v	m^3/h	14380
09 Pressure increase p_{fs}	Pa	267
10 Speed (rpm) n	min^{-1}	1260
11 Specific ratio*		1.00

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-120948

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Technical description

Weight	45 kg
Fan size	710 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Sheet aluminum insert, sprayed with PP plastic
Fan housing material	Sheet steel, pre-galvanized and coated with black plastic
Guard grille material	Steel, phosphated and coated with black plastic
Number of blades	5
Blade pitch	0°
Airflow direction	"A"
Direction of rotation	Counterclockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+ 80 °C
Min. permitted ambient temp. for motor (transport/storage)	- 40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- RS-485 MODBUS-RTU - PFC, passive - Control input 0-10 VDC / PWM - Thermal overload protection for electronics/motor - Alarm relay - Integrated PID controller - Input for sensor 0-10 V or 4-20 mA - Output for slave 0-10 V - Motor current limitation - Soft start - Line undervoltage / phase failure detection - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - External 24 V input (parameter setting)
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	C22.2 No.77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730

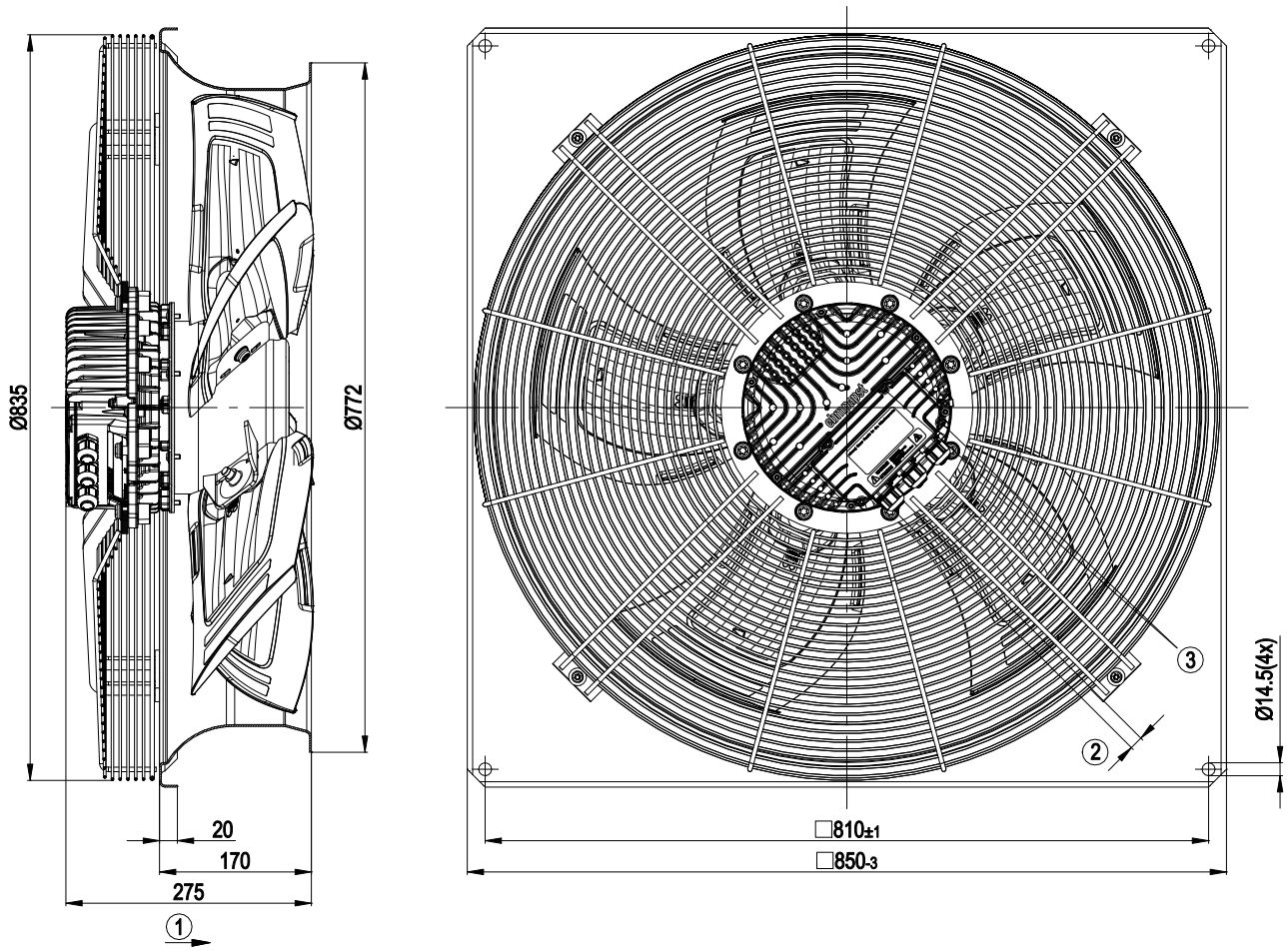
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Product drawing



1	Direction of air flow "A"
2	Cable diameter min. 4 mm, max. 10 mm; tightening torque 4±0.6 Nm
3	Tightening torque 3.5±0.5 Nm

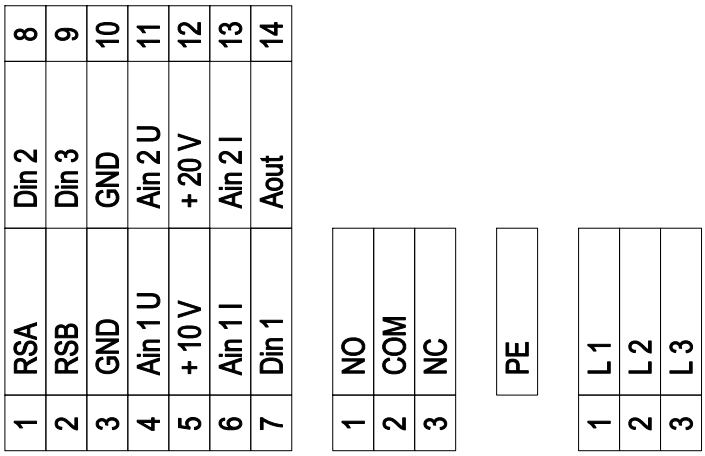
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Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact; make for failure
KL2	2	COM	Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV

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No.	Conn.	Designation	Function/assignment
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV

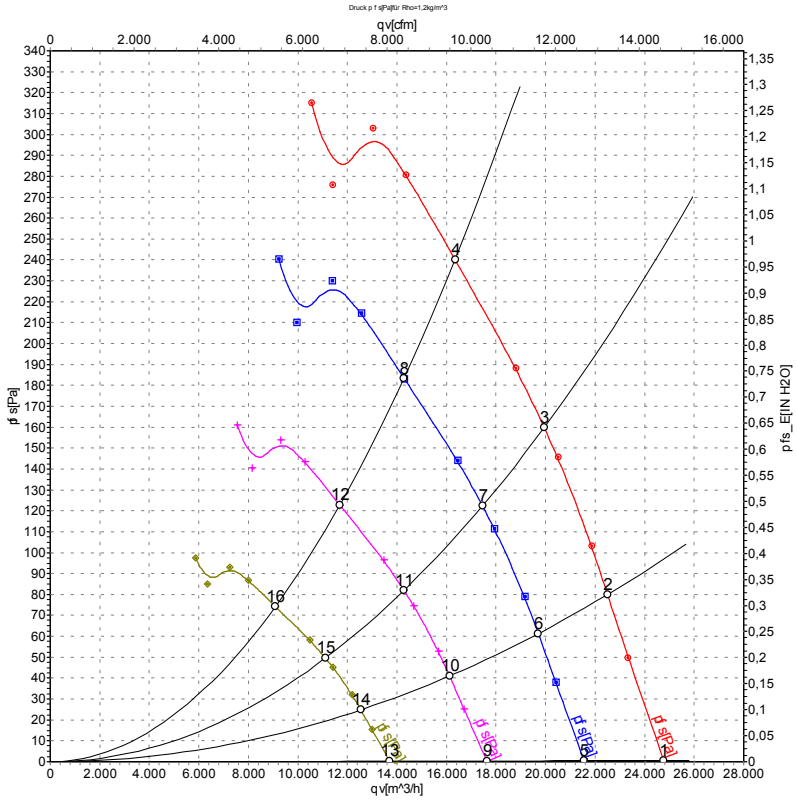
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Curves: Air performance 50 Hz



Measurement: LU-120948-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	400	50	1250	2227	3.40	71	79	81	24770	0	14580	0.00
2	400	50	1250	2420	3.70	71	79	80	22500	80	13245	0.32
3	400	50	1250	2649	4.02	72	79	80	19940	160	11735	0.64
4	400	50	1250	2830	4.30	75	83	82	16350	240	9625	0.96
5	400	50	1100	1465	2.24	68	76	78	21540	0	12680	0.00
6	400	50	1100	1624	2.48	68	76	77	19700	61	11595	0.24
7	400	50	1100	1775	2.69	69	76	77	17450	122	10270	0.49
8	400	50	1100	1884	2.87	73	80	79	14290	183	8410	0.73
9	400	50	900	802	1.23	64	72	73	17630	0	10375	0.00
10	400	50	900	890	1.36	64	72	72	16120	41	9490	0.16
11	400	50	900	972	1.48	65	72	73	14280	82	8405	0.33
12	400	50	900	1032	1.57	68	75	74	11690	123	6880	0.49
13	400	50	700	378	0.58	59	66	68	13710	0	8070	0.00
14	400	50	700	418	0.64	59	66	67	12540	25	7380	0.10
15	400	50	700	457	0.69	59	67	67	11110	50	6540	0.20
16	400	50	700	486	0.74	63	70	69	9090	74	5350	0.30

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase

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