K3G355-PG60-27

EC centrifugal module - RadiPac

backward-curved, single-intake

with support bracket

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Nominal data

Type	**K3G355-PG60-27**
Motor	**M3G112-EA**

Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	2480
Power consumption	W	1300
Current draw	A	5.8
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	64.9	52.8
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		74.1	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	1.31
09 Air flow q_v	m^3/h	3730
09 Pressure increase p_{fs}	Pa	761
10 Speed (rpm) n	min^{-1}	2490
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-174534

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Technical description

Size	355 mm
Motor size	112
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Support bracket material	Steel, painted black
Inlet nozzle material	Sheet steel, galvanized
Number of blades	5
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	See legend on product drawing
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Tach output - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Power limiter - Motor current limitation - PFC, active - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-4 (industrial environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (with customer connection of protective earth)

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Conformity with standards	EN 61800-5-1; CE
Approval	UL 1004-7 + 60730-1; EAC; CSA C22.2 No. 77 + CAN/CSA-E60730-1

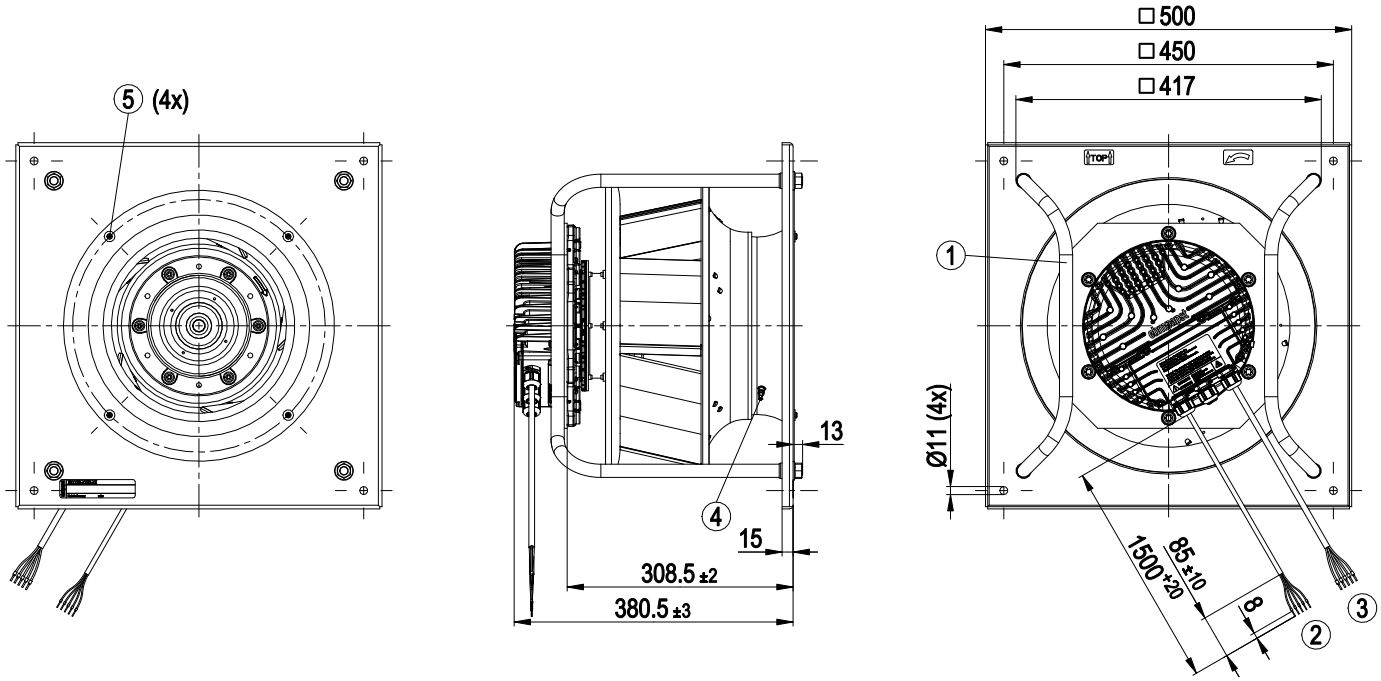
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Product drawing



1	Installed position: shaft horizontal (install support struts only vertically as illustrated) or rotor on bottom; rotor on top on request
2	Cable PVC AWG22
	5x wire-end ferrule
3	Cable PVC AWG18
	5x wire-end ferrule
4	Inlet ring with pressure tap (k-factor: 148)
5	Attachment holes for inlet ring and FlowGrid (00400-2-2957 not included in scope of delivery)

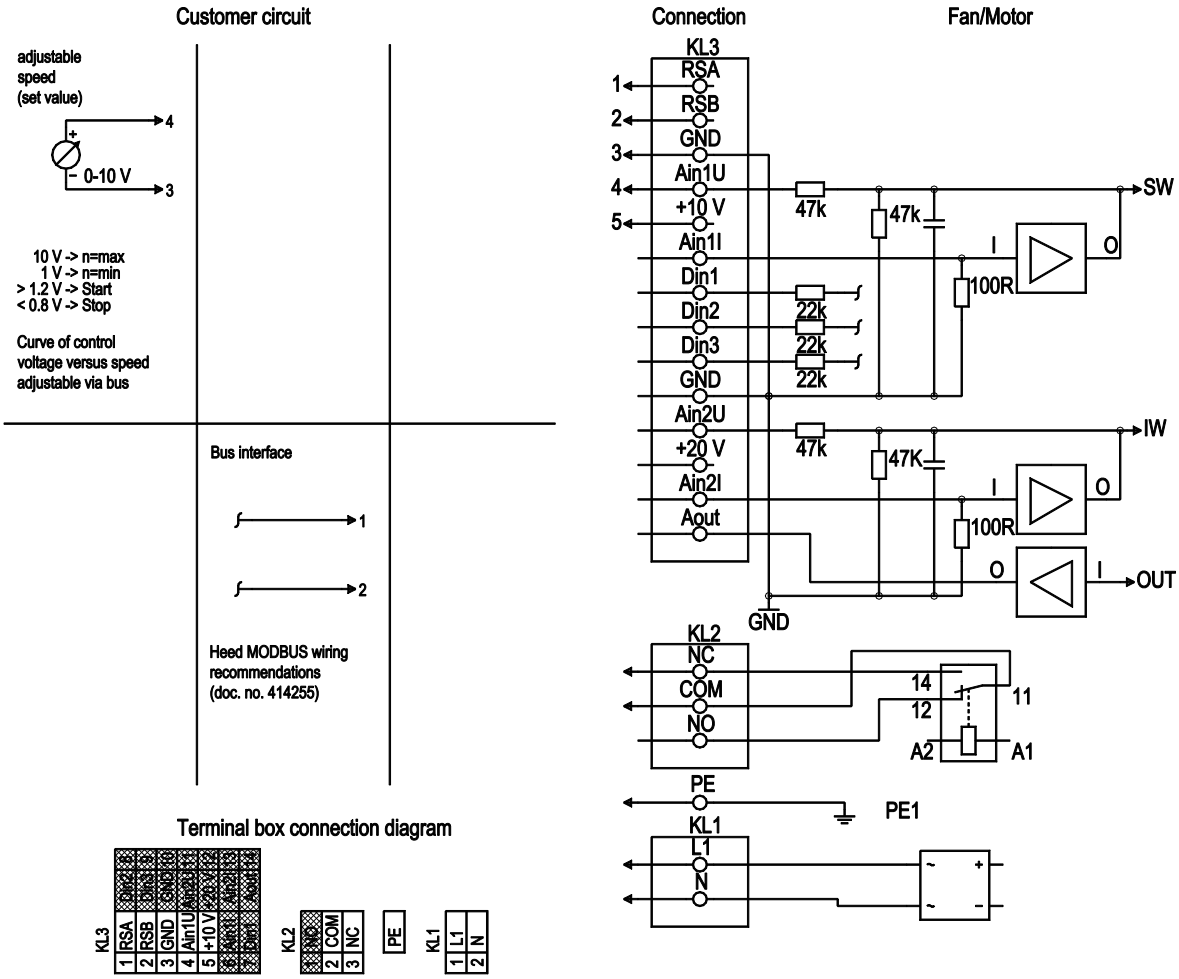
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Connection diagram



Terminal box connection diagram

No.	Conn.	Designation	Color	Function/assignment
KL1	1	L1	black	Supply connection, power supply; for nominal voltage range see technical data
KL1	2	N	blue	Supply connection, power supply; for nominal voltage range see technical data
PE	PE	PE	green/yellow	Ground connection, PE connection
KL2	1	NO	-	Status relay, floating status contact, make for failure
KL2	2	COM	white 2	Status relay, floating status contact, changeover contact, common connection, contact rating, max. 250 VAC/2 A (AC1)/min. 10 mA
KL2	3	NC	white 1	Status relay, floating status contact, break for failure
KL3	1	RSA	white	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL3	2	RSB	brown	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL3	3	GND	blue	Reference ground for control interface, SELV
KL3	4	Ain1 U	yellow	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL3	5	+10 V	red	Fixed voltage output 10 VDC, +10 V ± 3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. pot); SELV
KL3	6	Ain1 I	-	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1 U; SELV
KL3	7	Din1	-	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV

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No.	Conn.	Designation	Color	Function/assignment
KL3	8	Din2	-	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL3	9	Din3	-	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected via bus or digital input Din3; normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL3	10	GND	-	Reference ground for control interface, SELV
KL3	11	Ain2 U	-	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2 I; SELV
KL3	12	+20 V	-	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV Alternatively: +24 VDC input for parameterization without line voltage
KL3	13	Ain2 I	-	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2 U; SELV
KL3	14	Aout	-	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV

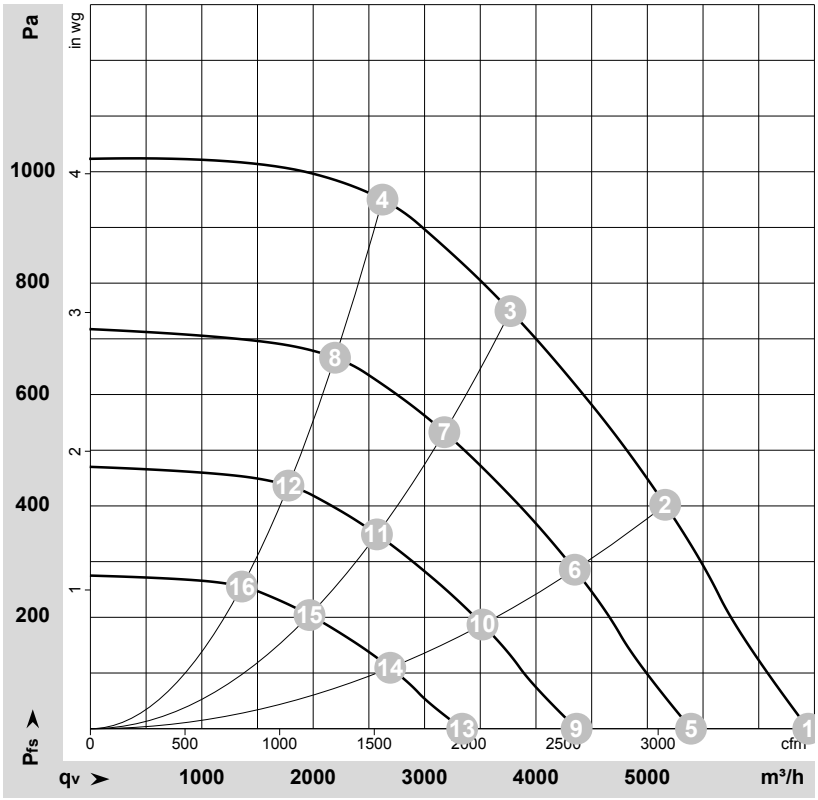
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Curves: Air performance 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-174534-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	230	50	2480	725	3.19	79	86	89	6445	0	3795	0.00
2	230	50	2480	1101	4.80	72	80	84	5160	400	3035	1.61
3	230	50	2480	1300	5.80	70	77	82	3770	750	2220	3.01
4	230	50	2480	1277	5.57	74	81	86	2620	950	1545	3.81
5	230	50	2100	425	1.87	75	82	85	5390	0	3175	0.00
6	230	50	2100	659	2.87	68	76	80	4350	285	2560	1.14
7	230	50	2100	786	3.43	66	73	78	3180	533	1870	2.14
8	230	50	2100	750	3.27	70	76	81	2195	675	1295	2.71
9	230	50	1700	225	0.99	69	76	79	4365	0	2570	0.00
10	230	50	1700	350	1.52	63	70	75	3520	187	2070	0.75
11	230	50	1700	417	1.82	61	68	72	2570	349	1515	1.40
12	230	50	1700	398	1.74	64	71	76	1780	442	1045	1.77
13	230	50	1300	101	0.44	62	70	73	3340	0	1965	0.00
14	230	50	1300	156	0.68	56	64	68	2690	109	1585	0.44
15	230	50	1300	187	0.81	54	61	66	1965	204	1160	0.82
16	230	50	1300	178	0.78	57	64	69	1360	259	800	1.04

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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