K3G280-RP54-B2

EC centrifugal module - RadiCal

backward-curved, single-intake

with support bracket

ebm-papst Mulfingen GmbH & Co. KG
Bachmühle 2 · D-74673 Mulfingen
Phone +49 7938 81-0
Fax +49 7938 81-110
info1@de.ebmpapst.com
www.ebmpapst.com

Limited partnership · Headquarters Mulfingen
Amtsgericht (court of registration) Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen
Amtsgericht (court of registration) Stuttgart · HRB 590142

ErP2015 EXCEEDS THE NORM

Nominal data

Type	**K3G280-RP54-B2**
Motor	**M3G084-FA**

Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	2880
Power consumption	W	705
Current draw	A	3.1
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	61.8	49.9
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		73.9	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	0.7
09 Air flow q_v	m^3/h	2250
09 Pressure increase p_{fs}	Pa	634
10 Speed (rpm) n	min^{-1}	2875
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-140333

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Technical description

Weight	9.6 kg
Fan size	280 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	PP plastic
Support plate material	Sheet steel, galvanized
Support bracket material	Steel, painted black
Inlet nozzle material	Sheet steel, galvanized
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F3-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on top; rotor on bottom on request
Condensation drainage holes	None
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Motor current limitation - PFC, active - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 55022 (Class B, household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (if protective earth is connected by customer to the housing's connection point)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC

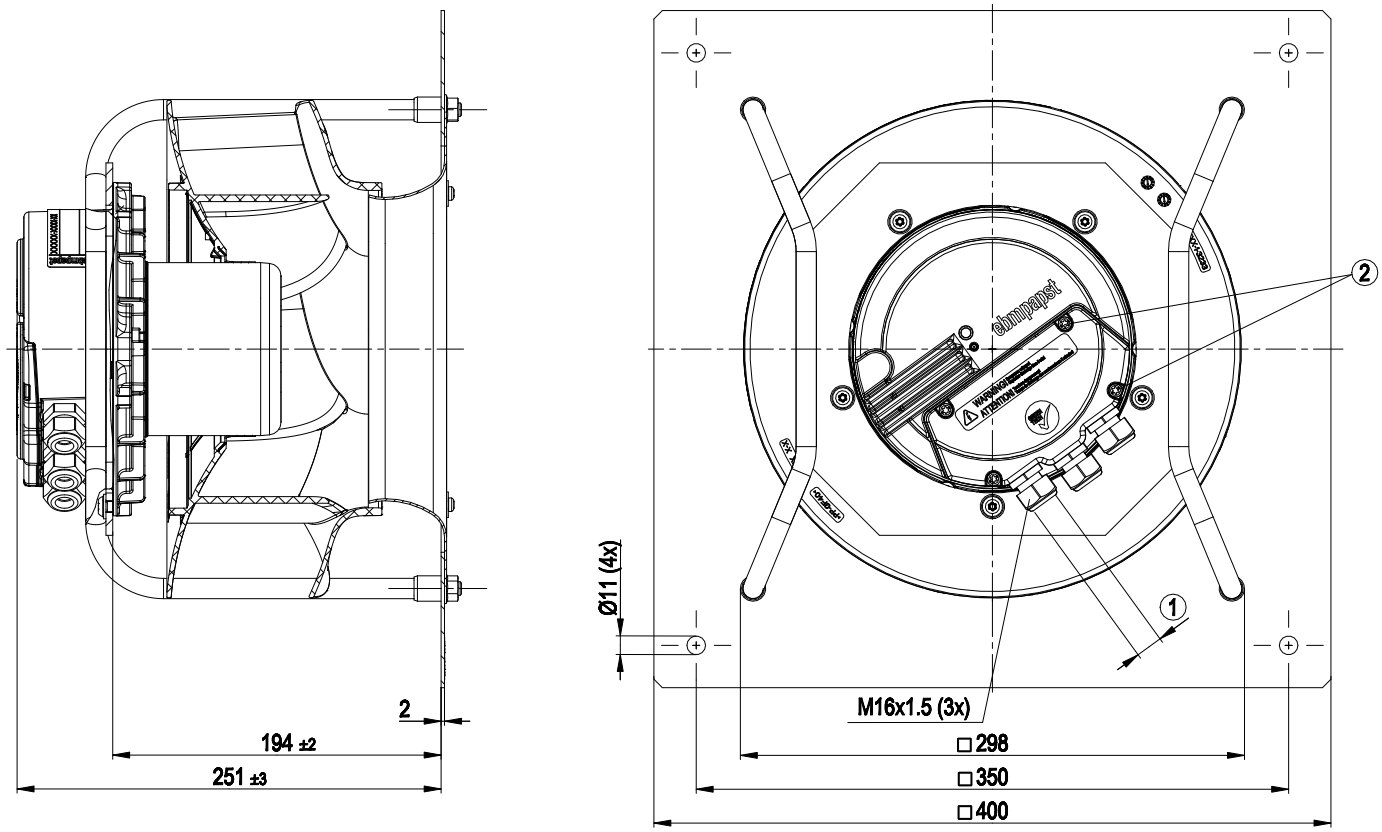
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Product drawing



1	Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5±0.4 Nm
2	Tightening torque 3.5 ± 0.5 Nm

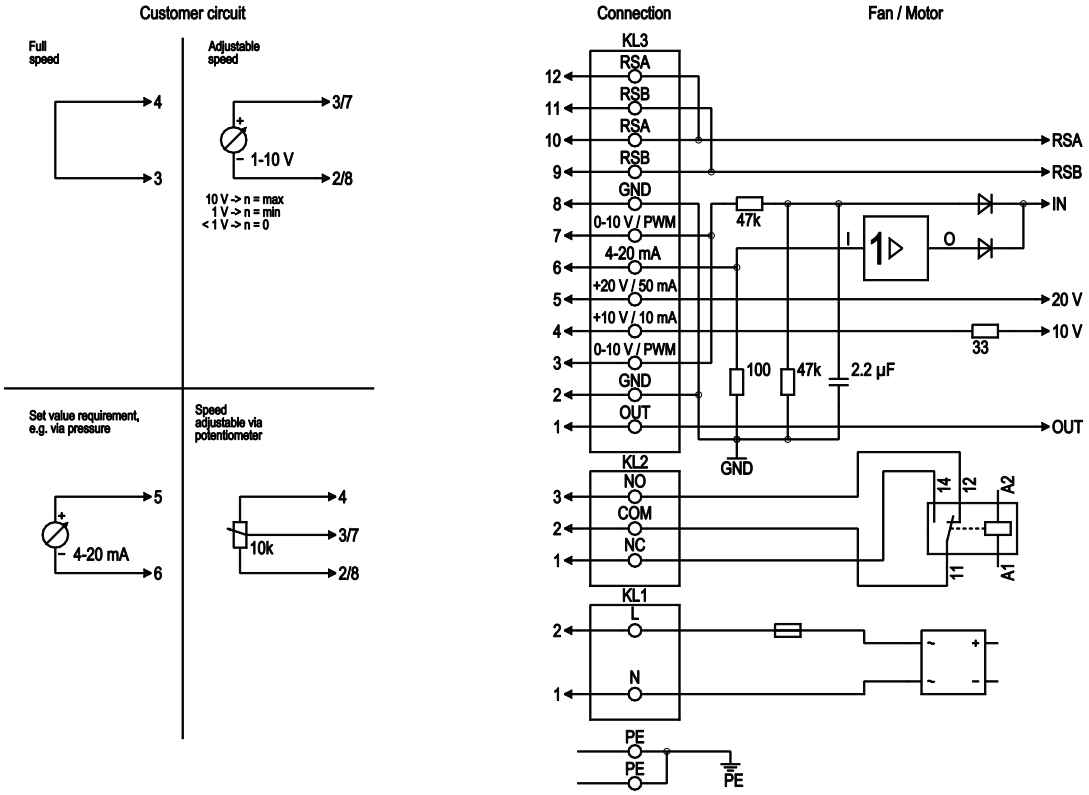
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Connection diagram



No.	Conn.	Designation	Function/assignment
PE	-	PE	Protective earth terminal
KL1	1, 2	N, L	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Control/current sensor value input 0-10 VDC, impedance 100 kΩ, use only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/- 3%), max. 10 mA, power supply for ext. devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA power supply for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Control/current sensor value input 4-20 mA, impedance 100 Ω, use only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

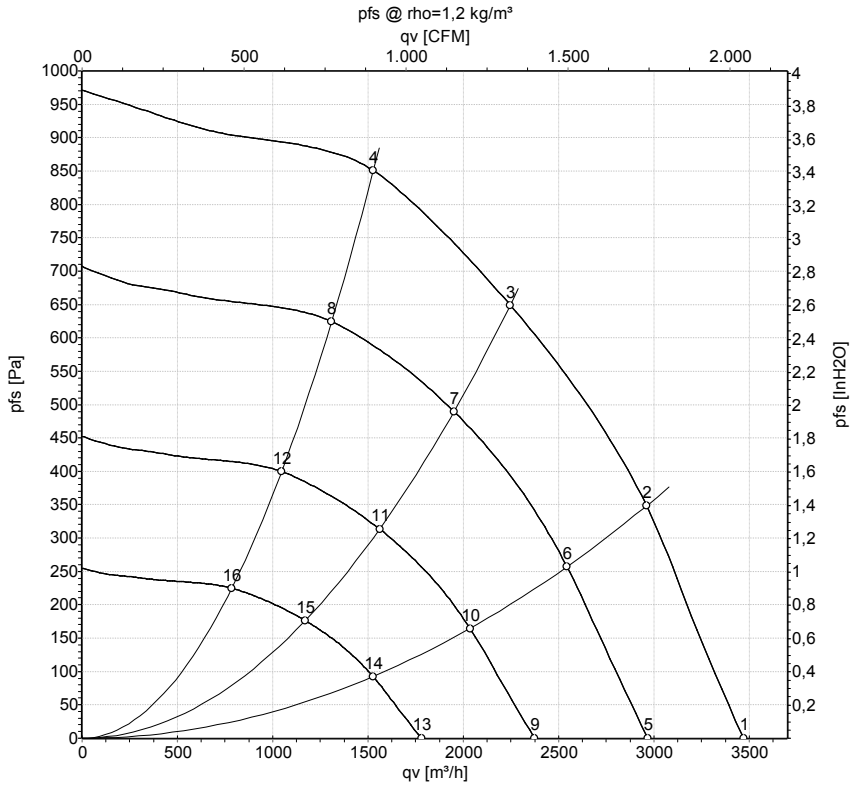
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Curves: Air performance 50 Hz



Measurement: LU-140333-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	230	50	2900	509	2.28	78	86	3470	0	2040	0.00
2	230	50	2900	648	2.86	74	81	2960	350	1745	1.41
3	230	50	2880	705	3.10	68	75	2245	650	1320	2.61
4	230	50	2900	668	2.95	69	77	1530	850	900	3.41
5	230	50	2500	319	1.42	74	82	2970	0	1745	0.00
6	230	50	2500	409	1.81	70	77	2545	259	1495	1.04
7	230	50	2500	462	2.04	64	72	1950	491	1150	1.97
8	230	50	2500	420	1.85	65	73	1310	626	770	2.51
9	230	50	2000	163	0.73	69	76	2375	0	1395	0.00
10	230	50	2000	210	0.93	64	72	2035	166	1200	0.67
11	230	50	2000	236	1.05	59	66	1560	314	920	1.26
12	230	50	2000	215	0.95	60	67	1045	400	615	1.61
13	230	50	1500	69	0.31	61	69	1780	0	1050	0.00
14	230	50	1500	88	0.39	57	64	1525	93	900	0.37
15	230	50	1500	100	0.44	52	59	1170	177	690	0.71
16	230	50	1500	91	0.40	53	60	785	225	460	0.90

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
qv = Air flow · p_{fs} = Pressure increase

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