W3GZ50-CK12-45

EC axial fan

sickled blades (S series)

with full round nozzle, for agricultural ventilation

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Nominal data

Type	**W3GZ50-CK12-45**
Motor	**M3G150-NA**

Phase		3~
Nominal voltage	VAC	200
Nominal voltage range	VAC	200 .. 240
Frequency	Hz	50/60
Type of data definition		ml
State		prelim.
Speed (rpm)	min^{-1}	565-600
Power input	W	1825
Current draw	A	5.5
Max. back pressure	Pa	75
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data in accordance with ecodesign regulation EU 327/2011

		Actual	Request 2015
01 Overall efficiency η_{es}	%	40.4	35.3
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		45.1	40
05 Variable speed drive		Yes	

09 Power input P_{ed}	kW	1.82
09 Air flow q_v	m^3/h	30415
09 Pressure increase p_{fs}	Pa	82
10 Speed (rpm) n	min^{-1}	560
11 Specific ratio*		1.00

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-169010

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Technical features

Mass	60 kg
Size	1250 mm
Motor size	150
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Die-cast aluminium, coated in black
Material of mounting ring	Steel, coated in black plastic (RAL 9005)
Material of wall ring	Sheet steel, galvanised and coated in black plastic (RAL 9005)
Number of blades	3
Blade angle	0°
Direction of air flow	A
Direction of rotation	Counter-clockwise, seen on rotor
Type of protection	IP55
Insulation class	"F"
Humidity (F) / environmental protection class (H)	H2+A
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on top; rotor on bottom on request
Condensation drainage holes	On the stator side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical connection	Terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	CSA C22.2 no. 77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730-1

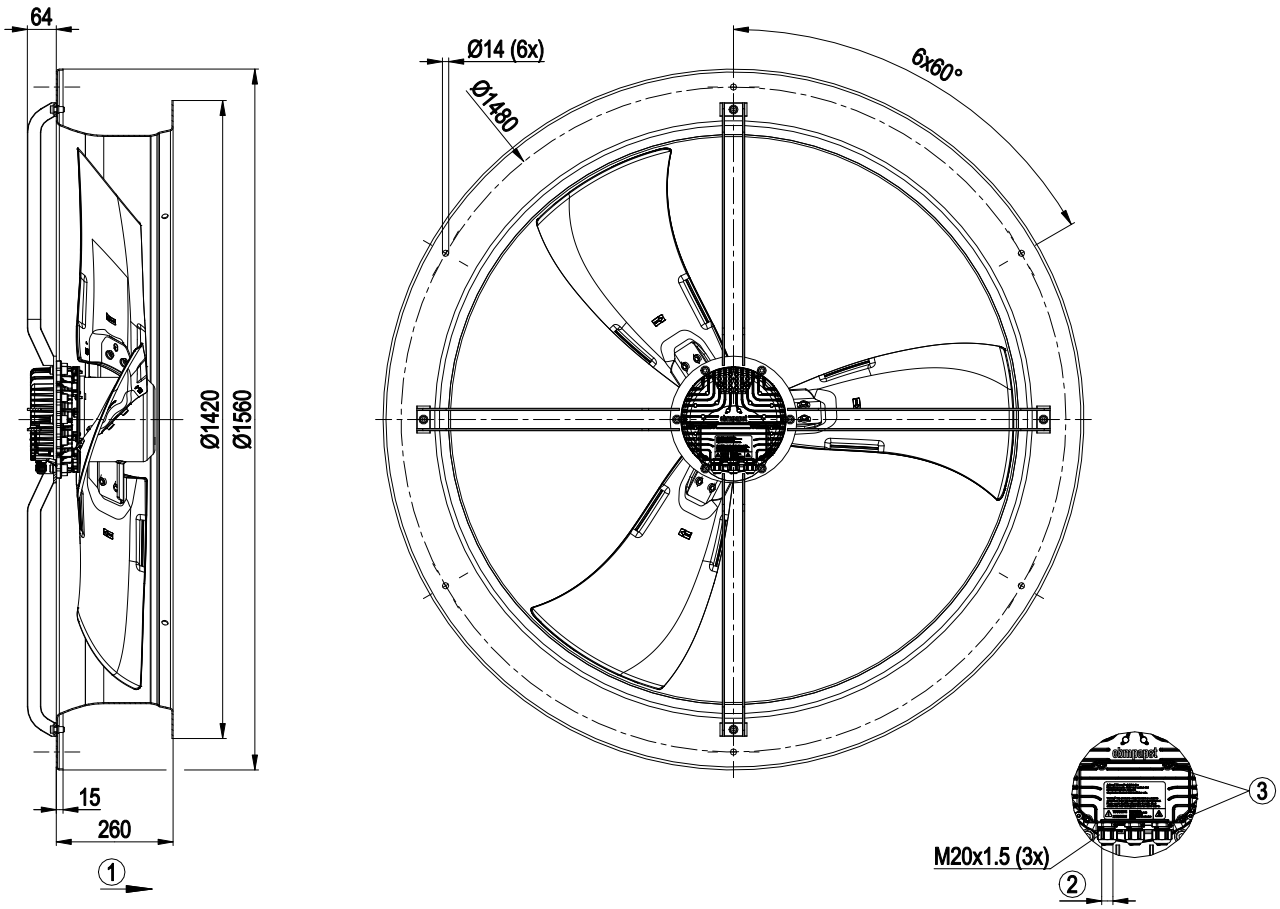
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Product drawing



1	Direction of air flow "A"
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4±0.6 Nm
3	Tightening torque 3.5±0.5 Nm

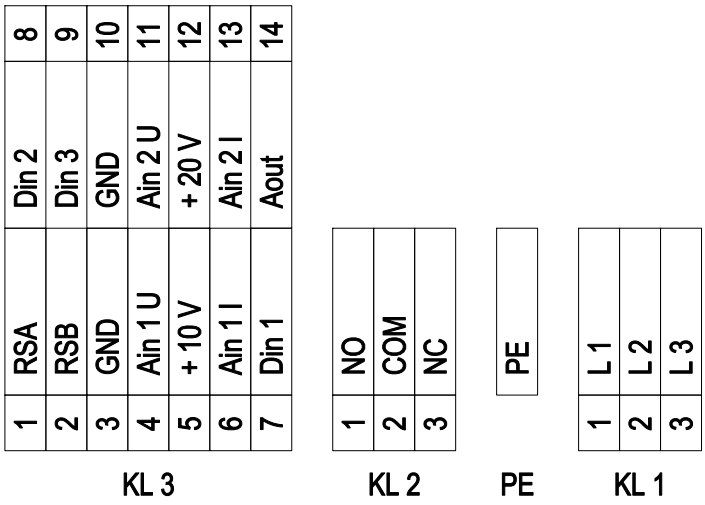
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Connection screen



No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~200-240 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~200-240 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~200-240 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Signal ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain1; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer), SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: parameter set switch 1/2, according to EEPROM setting, the valid/used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: open pin or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: controller function of integrated controller, according to EEPROM setting, the controller function of the integrated controller is normally/inversely selectable per bus or per digital input normal: open pin or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV

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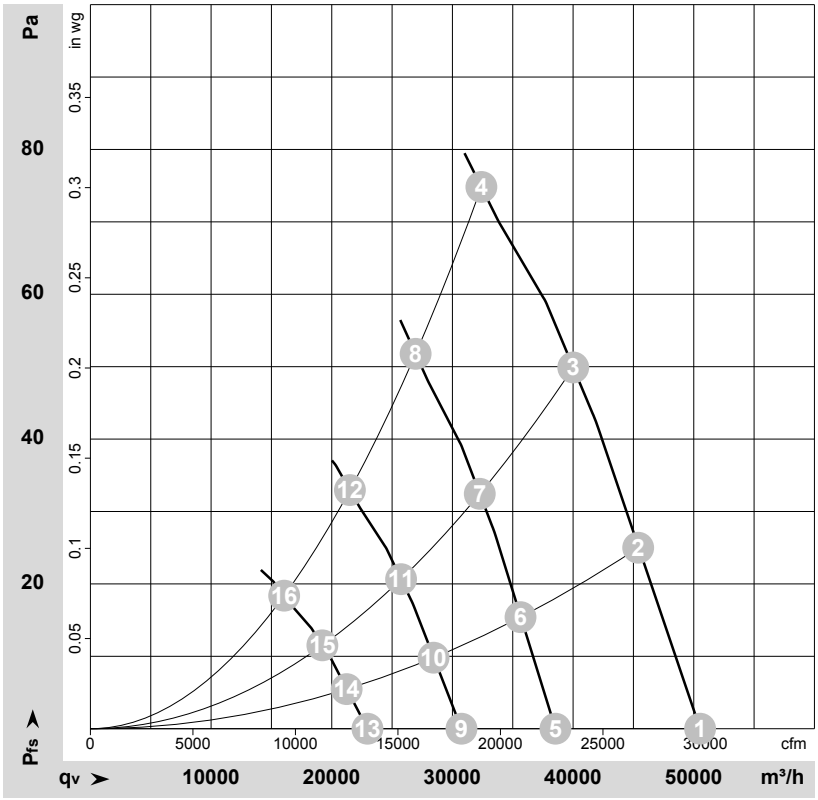
No.	Conn.	Designation	Function / assignment
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV

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Charts: Air flow 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-169010-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	Conn.	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
		V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	3~	200	50	615	1812	5.50	65	73	74	50525	0	29740	0.00
2	3~	200	50	600	1821	5.54	65	73	73	45395	25	26720	0.10
3	3~	200	50	585	1826	5.56	65	73	73	40015	50	23550	0.20
4	3~	200	50	565	1825	5.50	67	75	74	32400	75	19070	0.30
5	3~	200	50	470	804	2.44	58	66	67	38540	0	22685	0.00
6	3~	200	50	470	878	2.67	59	67	67	35645	16	20980	0.06
7	3~	200	50	470	957	2.91	60	68	67	32265	32	18990	0.13
8	3~	200	50	470	1049	3.18	63	71	70	26950	52	15865	0.21
9	3~	200	50	375	408	1.24	53	61	62	30750	0	18100	0.00
10	3~	200	50	375	446	1.36	53	61	61	28440	10	16740	0.04
11	3~	200	50	375	486	1.48	54	62	61	25745	21	15150	0.08
12	3~	200	50	375	533	1.62	57	65	64	21505	33	12655	0.13
13	3~	200	50	280	170	0.52	45	53	54	22960	0	13515	0.00
14	3~	200	50	280	186	0.56	46	54	54	21235	6	12500	0.02
15	3~	200	50	280	202	0.62	47	55	54	19220	12	11315	0.05
16	3~	200	50	280	222	0.67	50	58	57	16055	18	9450	0.07

Conn. = Connection · U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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