R3G560-AO38-21

EC centrifugal fan

backward curved, single inlet

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Nominal data

Type	**R3G560-AO38-21**
Motor	**M3G150-FF**

Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min^{-1}	1250
Power input	W	1500
Current draw	A	6.7
Min. back pressure	Pa	0
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

		Actual	Request 2015
01 Overall efficiency η_{es}	%	66.7	53.3
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		75.4	62
05 Variable speed drive		Yes	

09 Power input P_{ed}	kW	1.5
09 Air flow q_v	m^3/h	7580
09 Pressure increase p_{fs}	Pa	444
10 Speed (rpm) n	min^{-1}	1185
11 Specific ratio*		1.00

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-162357

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Technical features

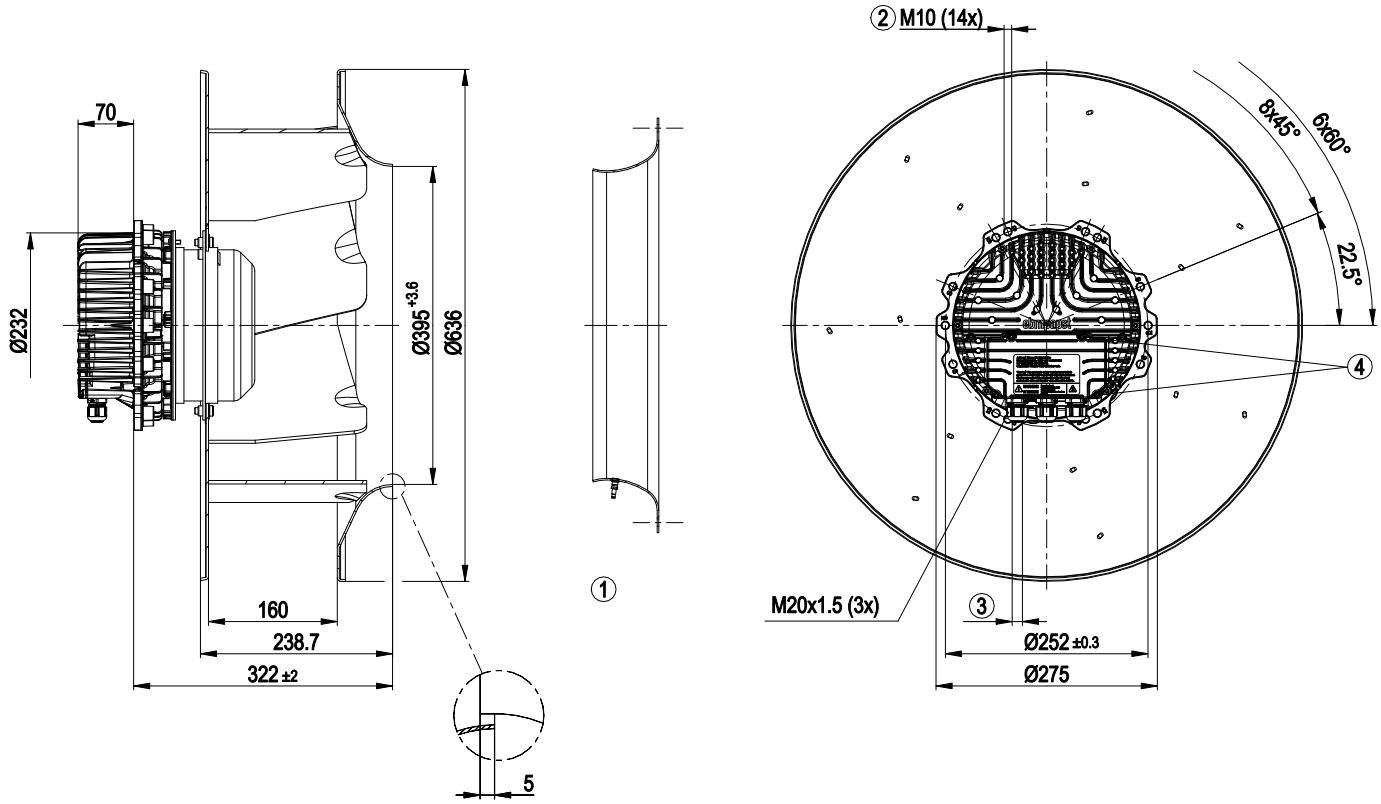
Mass	30.5 kg
Size	560 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 55
Insulation class	"F"
Humidity (F)/environmental protection class (H)	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Tach output - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Output limit - Motor current limit - PFC, active - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	C22.2 Nr.77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730

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Product drawing



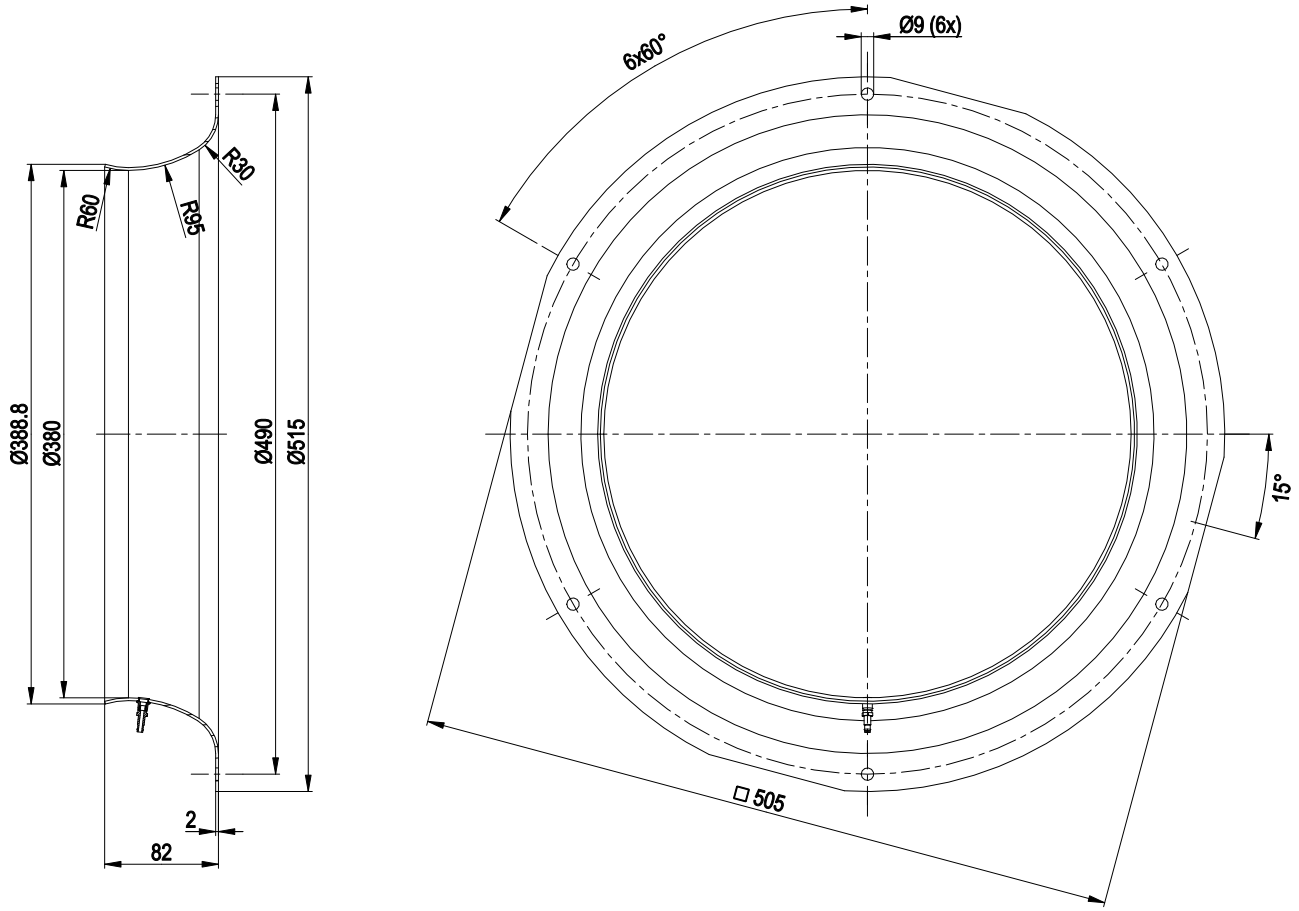
1	Accessory part: inlet nozzle 64030-2-4013 (k-factor 348) not included in scope of delivery
2	Thread reach max. 20 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4±0.6 Nm
4	Tightening torque 3.5±0.5 Nm

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Accessory part



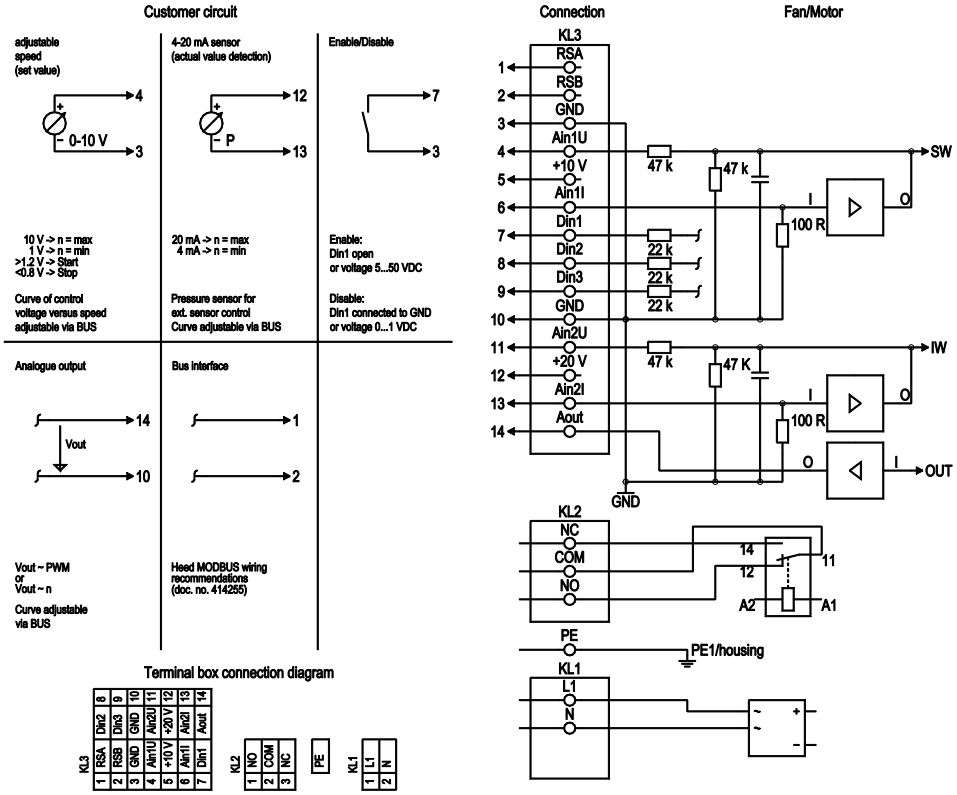
Inlet nozzle 64030-2-4013 with pressure tap not included in scope of delivery

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Connection screen



No.	Conn.	Designation	Function / assignment
KL1	1	L1	Mains connection, power supply; see technical data for nominal voltage range
KL1	2	N	Mains connection, power supply; see technical data for nominal voltage range
PE		PE	Earth connection, PE connection
KL2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating 250 VAC/ max. 2 A (AC1)/min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL3	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL3	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL3	3	GND	Reference earth for control interface; SELV
KL3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only for use as alternative to input Ain1; SELV
KL3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V +/-3%, max. 10 mA, short-circuit-proof, power supply for ext. devices (e.g. potentiometer); SELV
KL3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω, parametrisable curve, only for use as alternative to input Ain1 U; SELV
KL3	7	Din1	Digital input 1: Enabling of electronics, Enabling: Pin open or applied voltage 5-50 VDC Disabling: Bridge to GND or applied voltage <1 VDC Reset function: Triggers software reset after a level change to <1 VDC; SELV
KL3	8	Din2	Digital input 2: Parameter set 1/2 switching, depending on EEPROM setting, the valid/used parameter set can be selected via the bus or via the digital input DIN2. Parameter set 1: Pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV

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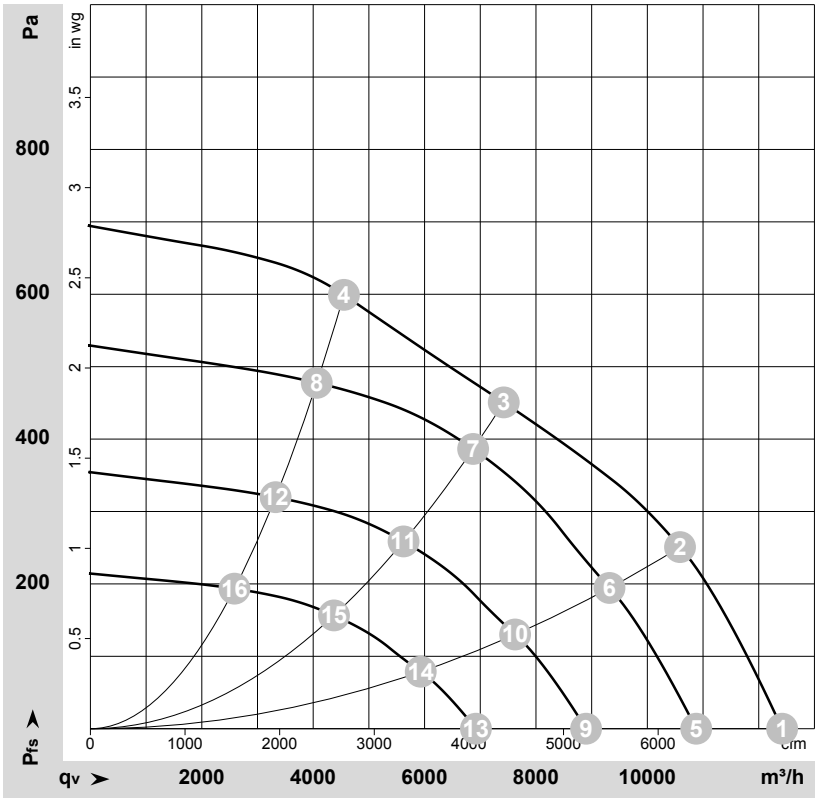
No.	Conn.	Designation	Function / assignment
KL3	9	Din3	Digital input 3: Controller function of integrated controller, depending on EEPROM setting, the controller function of the integrated controller can be selected via the bus or the digital input Din 3 normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL3	10	GND	Signal ground for control interface, SELV
KL3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain2; SELV
KL3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof, power supply for ext. devices (e.g. sensors); SELV Alternatively: +24 VDC input for parametrisation without mains power
KL3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, Ri = 100 Ω, parametrisable curve, only for use as alternative to input Ain2 U; SELV
KL3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV

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Charts: Air flow 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-162357-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	inH2O
1	230	50	1250	1128	5.01	79	86	90	12420	0	7310	0.00
2	230	50	1250	1469	6.70	71	80	84	10585	250	6230	1.00
3	230	50	1200	1500	6.70	68	76	81	7420	450	4370	1.81
4	230	50	1250	1500	6.70	71	78	84	4550	600	2680	2.41
5	230	50	1100	758	3.37	76	83	87	10880	0	6405	0.00
6	230	50	1100	1002	4.61	68	76	81	9320	194	5485	0.78
7	230	50	1100	1200	5.52	66	74	79	6870	388	4045	1.56
8	230	50	1100	1075	4.93	68	76	81	4065	478	2390	1.92
9	230	50	900	415	1.84	71	78	82	8900	0	5240	0.00
10	230	50	900	549	2.52	63	71	76	7625	130	4490	0.52
11	230	50	900	657	3.02	61	69	74	5625	260	3310	1.04
12	230	50	900	589	2.70	63	71	76	3325	320	1955	1.28
13	230	50	700	195	0.87	64	72	76	6920	0	4075	0.00
14	230	50	700	258	1.19	57	65	69	5930	79	3490	0.32
15	230	50	700	309	1.42	55	62	67	4375	157	2575	0.63
16	230	50	700	277	1.27	57	64	69	2585	193	1520	0.77

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
q_V = Air flow · p_{fs} = Pressure increase

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