R3G280-AN32-01

EC centrifugal fan

forward curved, single inlet

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Nominal data

Type	**R3G280-AN32-01**
Motor	**M3G112-GA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min^{-1}	1300
Power input	W	1100
Current draw	A	2.5
Min. back pressure	Pa	100
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

		Actual	Request 2015
01 Overall efficiency η_{es}	%	46.4	35.9
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		54.5	44
05 Variable speed drive		Yes	

09 Power input P_{ed}	kW	0.53
09 Air flow q_v	m^3/h	1345
09 Pressure increase p_{fs}	Pa	600
10 Speed (rpm) n	min^{-1}	1535
11 Specific ratio*		1.01

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-74509

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Technical features

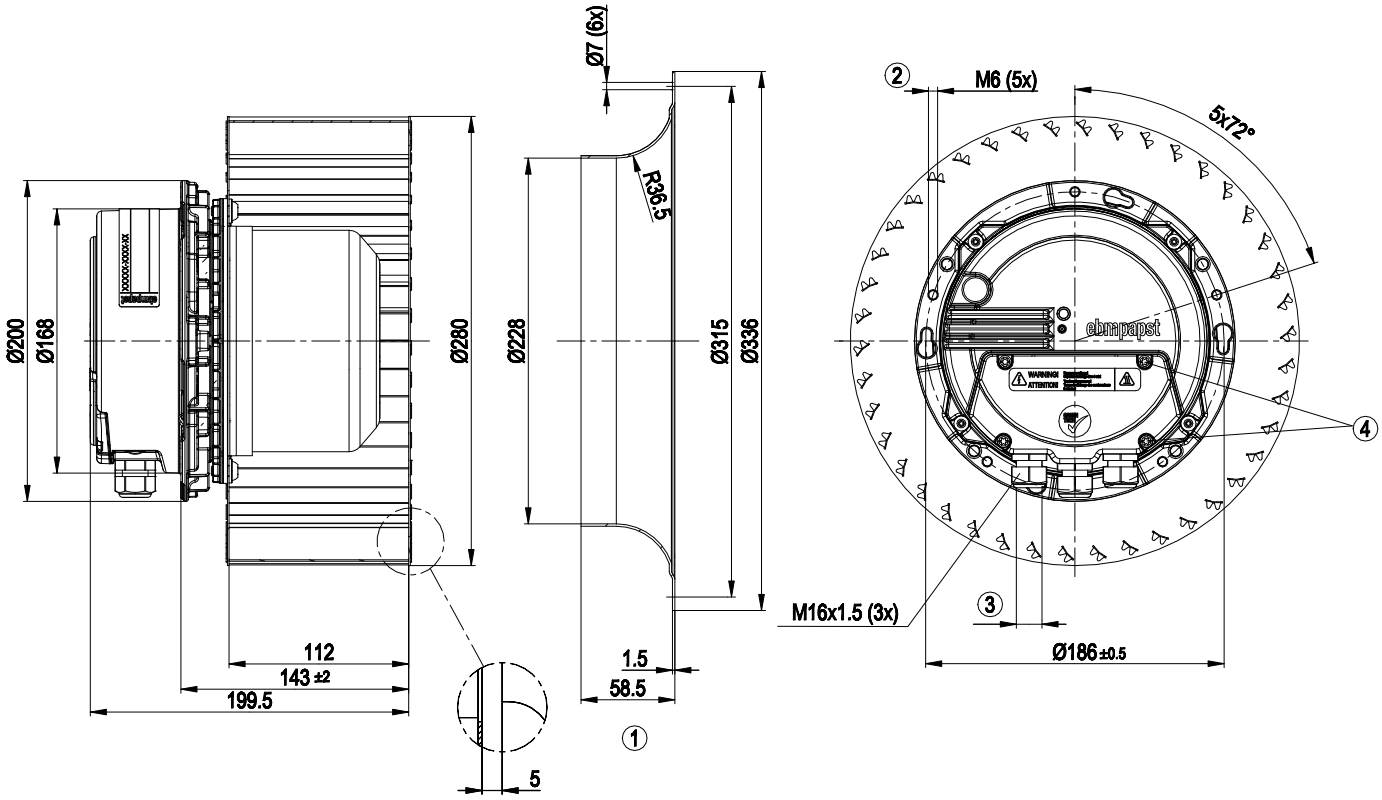
Mass	9.9 kg
Size	280 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Sheet steel, galvanised
Number of blades	42
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity (F)/environmental protection class (H)	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	Continuous operation (S1)
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC

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Product drawing



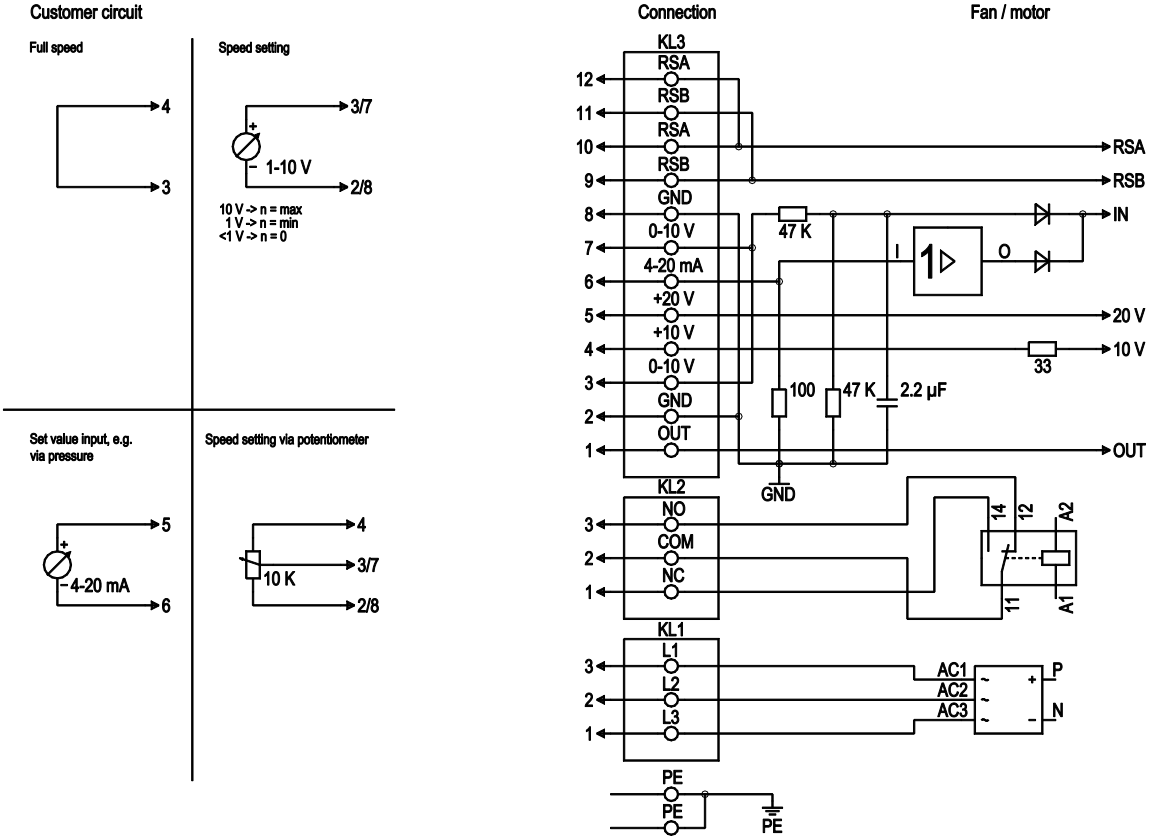
1	Accessory part: Inlet nozzle 28010-2-4013, not included in the standard scope of delivery
2	Depth of screw max. 16 mm
3	Cable diameter: min. 4 mm; max. 10 mm; tightening torque: 2.5±0.4 Nm
4	Tightening torque 3.5±0.5 Nm

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Connection screen



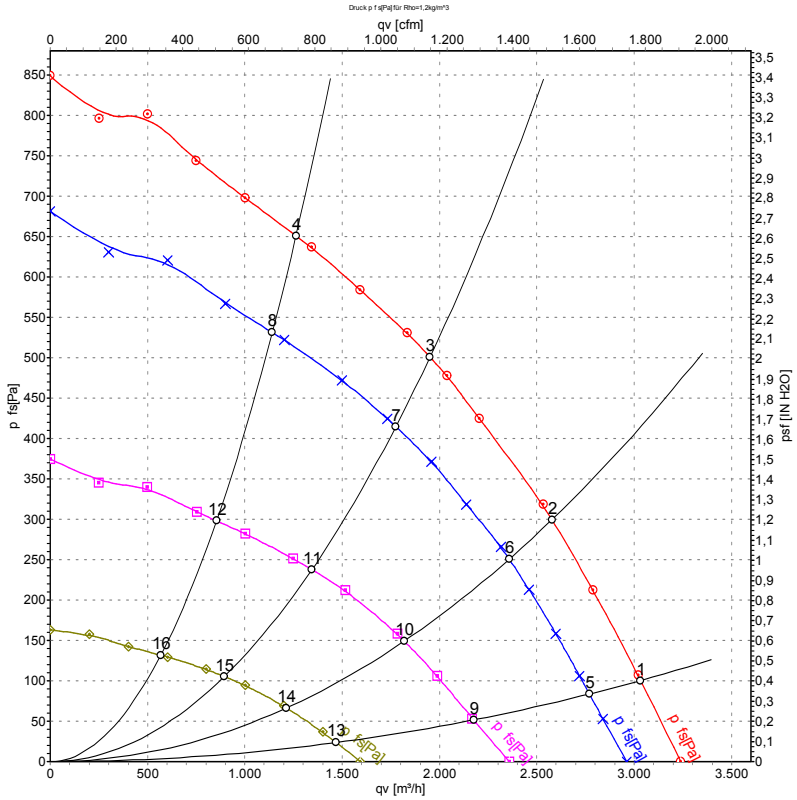
No.	Conn.	Designation	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, 50/60 Hz
KL2	1	NC	Floating status message contact, normally closed connection; break for failure
KL2	2	COM	Floating status message contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status message contact, normally open connection; make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of the current level control coefficient: 1 V equates to 10% level control coefficient. 10 V equate to 100% level control coefficient.
KL3	2, 8	GND	Reference mass for control interface, SELV
KL3	3, 7	0-10 V	Use control / actual value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3%), max. 10 mA, supply voltage for external devices (e.g. potentiometers), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, supply voltage for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / actual value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBus, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBus, RSA, SELV

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Charts: Air flow 50 Hz



Measurement: LU-74509-1
Measurement: LU-74510-1
Measurement: LU-74511-1
Measurement: LU-74512-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	m^3/h	Pa	cfm	inH2O
1	400	50	1300	1100	2.00	3030	100	1785	0.40
2	400	50	1395	894	1.68	2575	300	1515	1.20
3	400	50	1470	695	1.34	1950	500	1150	2.01
4	400	50	1545	514	1.00	1265	650	745	2.61
5	400	50	1230	819	1.56	2770	84	1630	0.34
6	400	50	1280	696	1.34	2360	251	1390	1.01
7	400	50	1340	534	1.06	1775	415	1045	1.67
8	400	50	1400	394	0.83	1140	532	670	2.14
9	400	50	970	406	0.83	2175	51	1280	0.20
10	400	50	995	334	0.72	1820	150	1070	0.60
11	400	50	1025	251	0.56	1345	238	790	0.96
12	400	50	1055	184	0.44	855	298	505	1.20
13	400	50	665	147	0.37	1470	24	865	0.10
14	400	50	680	124	0.32	1215	67	715	0.27
15	400	50	695	97	0.27	895	105	525	0.42
16	400	50	710	76	0.24	570	132	335	0.53

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · q_V = Air flow · p_{fs} = Pressure increase

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