K3G355-AX56-90

EC centrifugal module - RadiPac

backward curved, single inlet

with support bracket



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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**K3G355-AX56-90**	
Motor	**M3G112-EA**	
Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min^{-1}	2140
Power input	W	1000
Current draw	A	1.65
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}	%	65.5	47.3	51.3
Efficiency grade N		76.2	58	62
Power input P_{ed}	kW	0.95		
Air flow q_v	m^3/h	3905		
Pressure increase p_{fs}	Pa	530		
Speed n	min^{-1}	2150		

Data definition with optimum efficiency. LU-106551
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

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Technical features

Mass	17.4 kg
Size	355 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Material of mounting plate	Sheet steel, galvanised
Material of support bracket	Steel, coated in black
Material of inlet nozzle	Sheet steel, galvanised
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Refer to product drawing
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC; UL 1004-7 + 60730

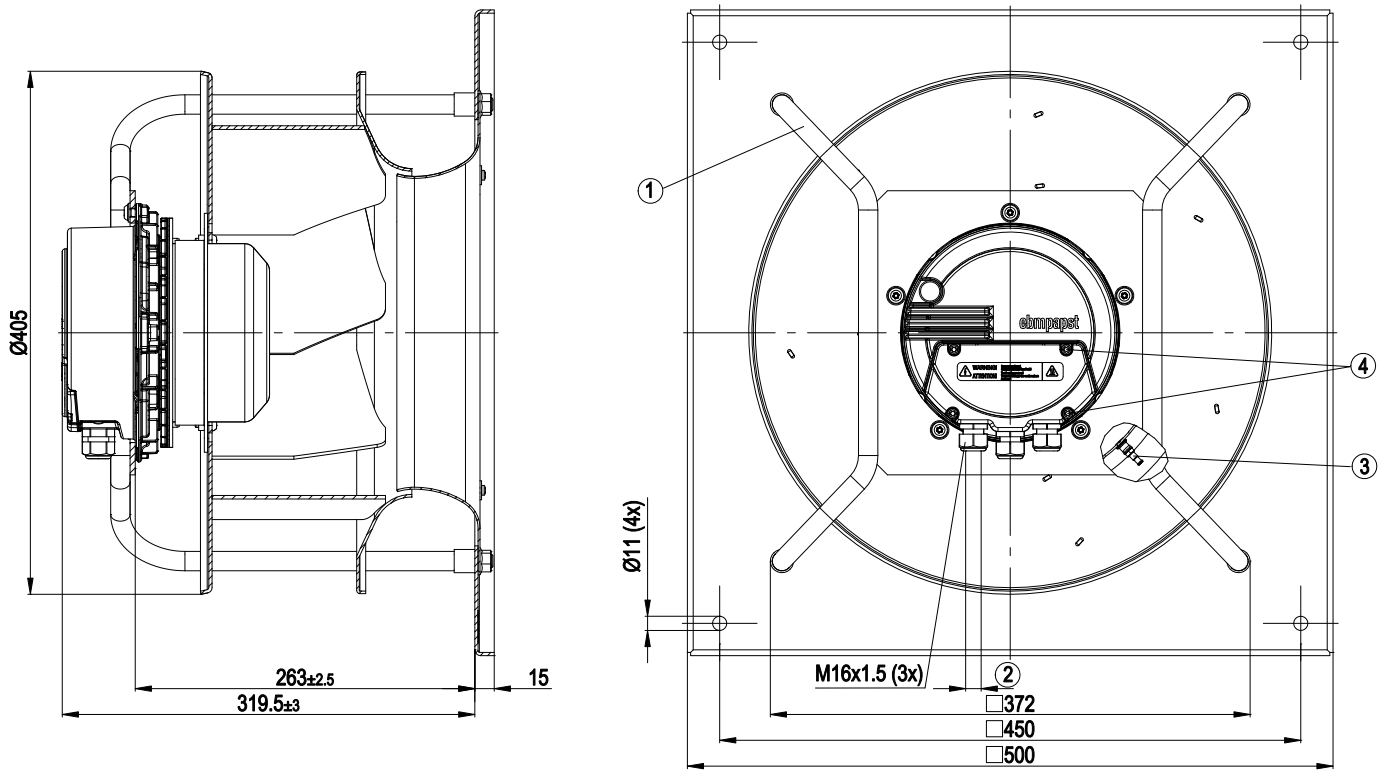
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Product drawing



1	Mounting position: shaft horizontal (install the support struts only vertically as shown in the view!) or rotor on bottom; rotor on top on request
2	Cable diameter: min. 4 mm, max. 10 mm; tightening torque: 2.5±0.4 Nm
3	Inlet nozzle with bleeder connection for pressure relief (k-factor: 148)
4	Tightening torque 3.5±0.5 Nm

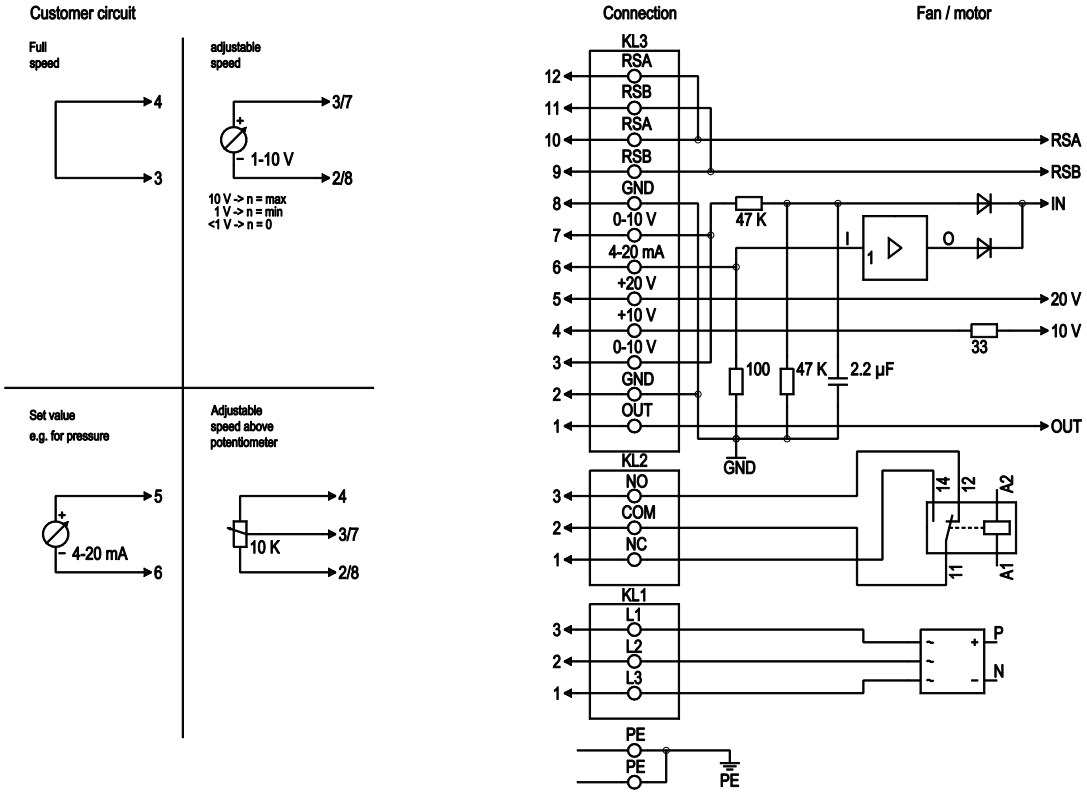
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Connection screen



No.	Conn.	Designation	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, voltage range (see type plate), 50/60 Hz
KL2	1	NC	Floating status contact, break with error
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, close with error
KL3	1	OUT	Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the actual motor duty cycle (PWM): 1 V corresponds to 10% PWM, 10 V correspond to 100% PWM.
KL3	2, 8	GND	Signal ground for control interface, SELV
KL3	3, 7	0-10 V	Set value / actual sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, supply voltage for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Set value / actual sensor value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

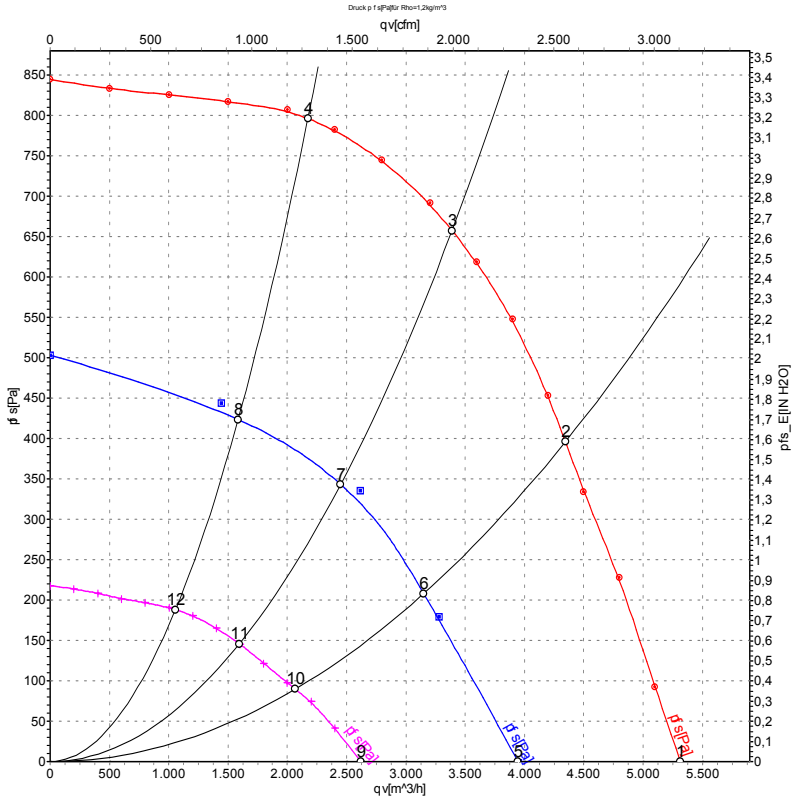
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Charts: Air flow 50 Hz



Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa
1	400	50	2140	656	1.14	81	87	91	5315	0
2	400	50	2140	893	1.50	71	77	83	4345	400
3	400	50	2140	1000	1.65	68	75	81	3390	650
4	400	50	2140	918	1.54	71	78	84	2175	800
5	400	50	1610	286	0.57	72	79	84	3945	0
6	400	50	1595	350	0.68	64	70	76	3150	210
7	400	50	1580	387	0.74	62	69	75	2450	350
8	400	50	1585	366	0.70	64	70	76	1585	431
9	400	50	1080	113	0.28	63	71	76	2620	0
10	400	50	1065	133	0.31	57	64	69	2070	90
11	400	50	1065	143	0.33	53	60	66	1595	146
12	400	50	1060	135	0.32	54	61	68	1055	188

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
qv = Air flow · p_{fs} = Pressure increase

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