A3G710-AU32-71

EC axial fan - HyBlade

sickled blades (S series)

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Nominal data

Type	**A3G710-AU32-71**
Motor	**M3G150-IF**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min^{-1}	1250
Power input	W	2800
Current draw	A	4.3
Max. back pressure	Pa	240
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

		Actual	Request 2015
01 Overall efficiency η_{es}	%	42.9	36.5
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		46.4	40
05 Variable speed drive		Yes	

09 Power input P_{ed}	kW	2.83
09 Air flow q_v	m^3/h	14785
09 Pressure increase p_{fs}	Pa	281
10 Speed (rpm) n	min^{-1}	1250
11 Specific ratio*		1.00

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

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Technical features

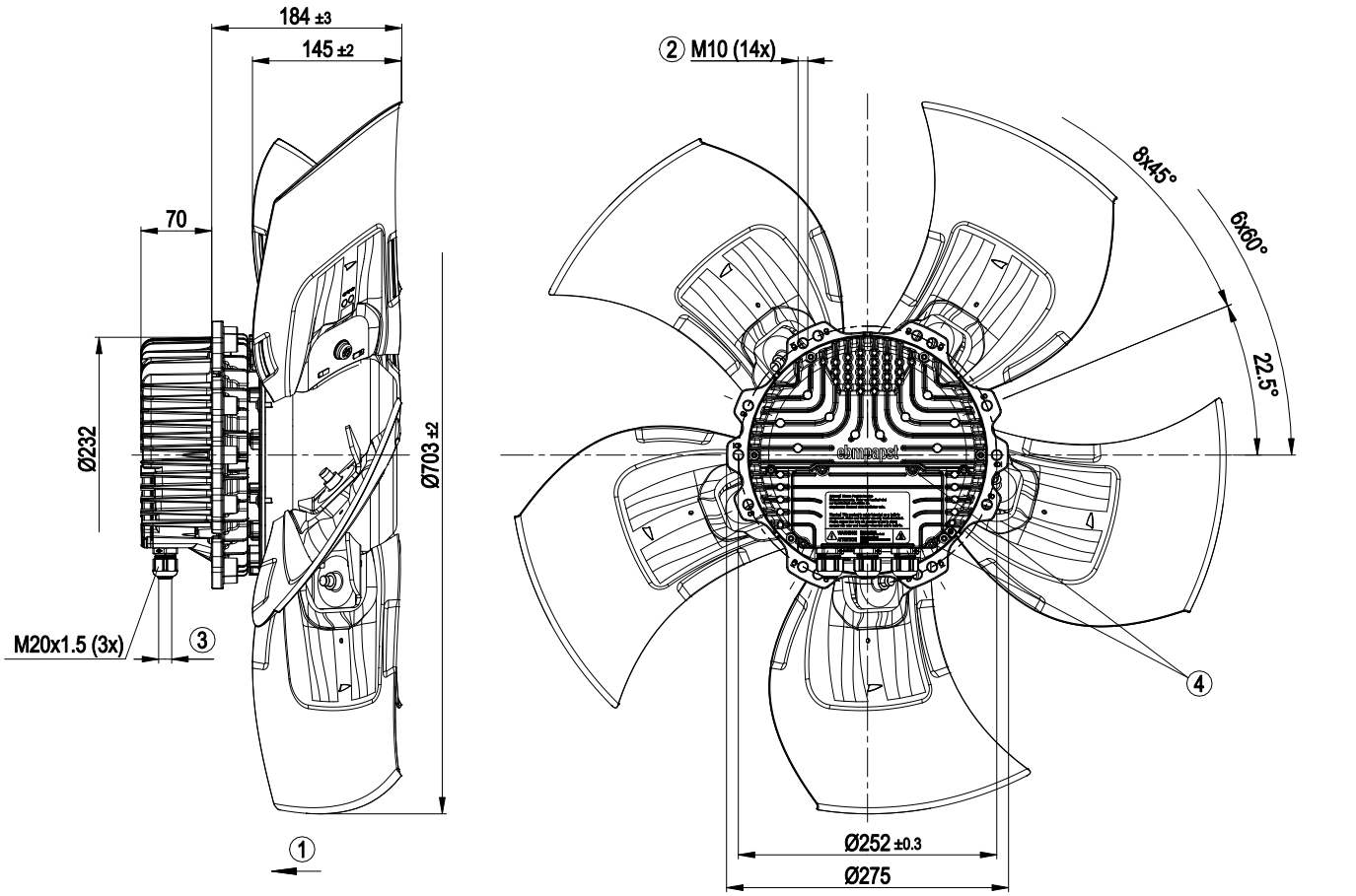
Mass	25.6 kg
Size	710 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Aluminium sheet insert, sprayed with PP plastic
Number of blades	5
Blade angle	0°
Direction of air flow	"V"
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 55
Insulation class	"F"
Humidity (F)/environmental protection class (H)	F4-1
Note ambient temperature	Occasional start-up between -40°C and -25°C is permissible. For continuous operation at ambient temperatures below -25°C (e.g. refrigeration applications) we recommend our fan version with special low-temperature bearings.
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used devices with a total rated power greater than 1 kW
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC

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Product drawing



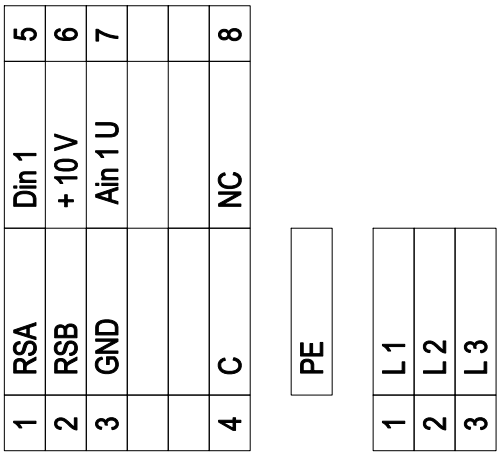
1	Direction of air flow "V"
2	Thread reach max. 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4±0.6 Nm
4	Tightening torque 3.5±0.5 Nm

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Connection screen



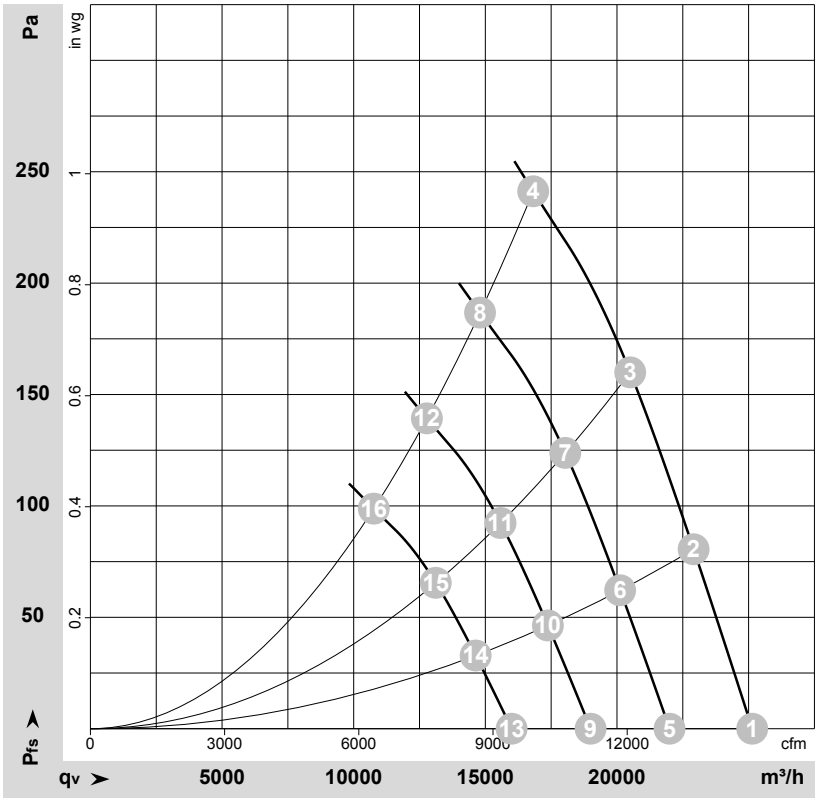
No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 2	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 2	3	GND	Signal ground for control interface; SELV
KL2	4	C	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / 2 A (AC1)
KL 2	5	Din1	Digital input 1 enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 V; SELV
KL 2	6	+ 10 V	Fixed voltage output 10 VDC; +10 V -3 %, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer); SELV Alternative: +24 VDC input for parametrisation via MODBUS without mains power
KL 2	7	Ain1 U	Analogue input 1 (set value) 0-10 V, Ri=100 kΩ, parametrisable curve; SELV
KL2	8	NC	Status relay, floating status contact; break for failure

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Charts: Air flow 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-179592-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	Conn.	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
		V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	inH2O
1	Y	400	50	1250	2226	3.46	71	79	80	25135	0	14795	0.00
2	Y	400	50	1250	2429	3.76	71	79	79	22910	80	13485	0.32
3	Y	400	50	1250	2617	4.04	72	79	79	20500	160	12065	0.64
4	Y	400	50	1250	2800	4.30	75	82	81	16820	240	9900	0.96
5	Y	400	50	1100	1492	2.32	68	76	76	22000	0	12950	0.00
6	Y	400	50	1100	1647	2.55	68	76	76	20120	64	11845	0.26
7	Y	400	50	1100	1782	2.75	69	76	76	18035	124	10615	0.50
8	Y	400	50	1100	1914	2.95	72	79	77	14800	187	8710	0.75
9	Y	400	50	950	961	1.49	64	72	73	19000	0	11180	0.00
10	Y	400	50	950	1061	1.64	64	72	72	17375	48	10230	0.19
11	Y	400	50	950	1148	1.77	65	72	72	15575	92	9170	0.37
12	Y	400	50	950	1233	1.90	68	75	74	12780	139	7525	0.56
13	Y	400	50	800	574	0.89	60	68	68	16000	0	9415	0.00
14	Y	400	50	800	634	0.98	60	67	68	14635	34	8615	0.14
15	Y	400	50	800	685	1.06	61	68	68	13120	66	7720	0.26
16	Y	400	50	800	736	1.13	64	71	69	10765	99	6335	0.40

Conn. = Connection · U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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