W3G710-GO87-92

EC axial fan - HyBlade

sickle-shaped blades (S series)

with square full nozzle

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Nominal data

Type	**W3G710-GO87-92**
Motor	**M3G112-IA**

Phase		3~
Nominal voltage	VAC	200
Nominal voltage range	VAC	200 .. 240
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min^{-1}	900
Power consumption	W	930
Current draw	A	3.0
Max. back pressure	Pa	125
Max. back pressure	inH2O	0.5
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

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Technical description

Weight	33.5 kg
Fan size	710 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Sheet aluminum insert, sprayed with PP plastic
Fan housing material	Sheet steel, pre-galvanized and coated with black plastic (RAL 9005)
Guard grille material	Steel, coated with black plastic (RAL 9005)
Number of blades	5
Blade pitch	0°
Airflow direction	"V"
Direction of rotation	Counterclockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1
Approval	UL 1004-7 + 60730

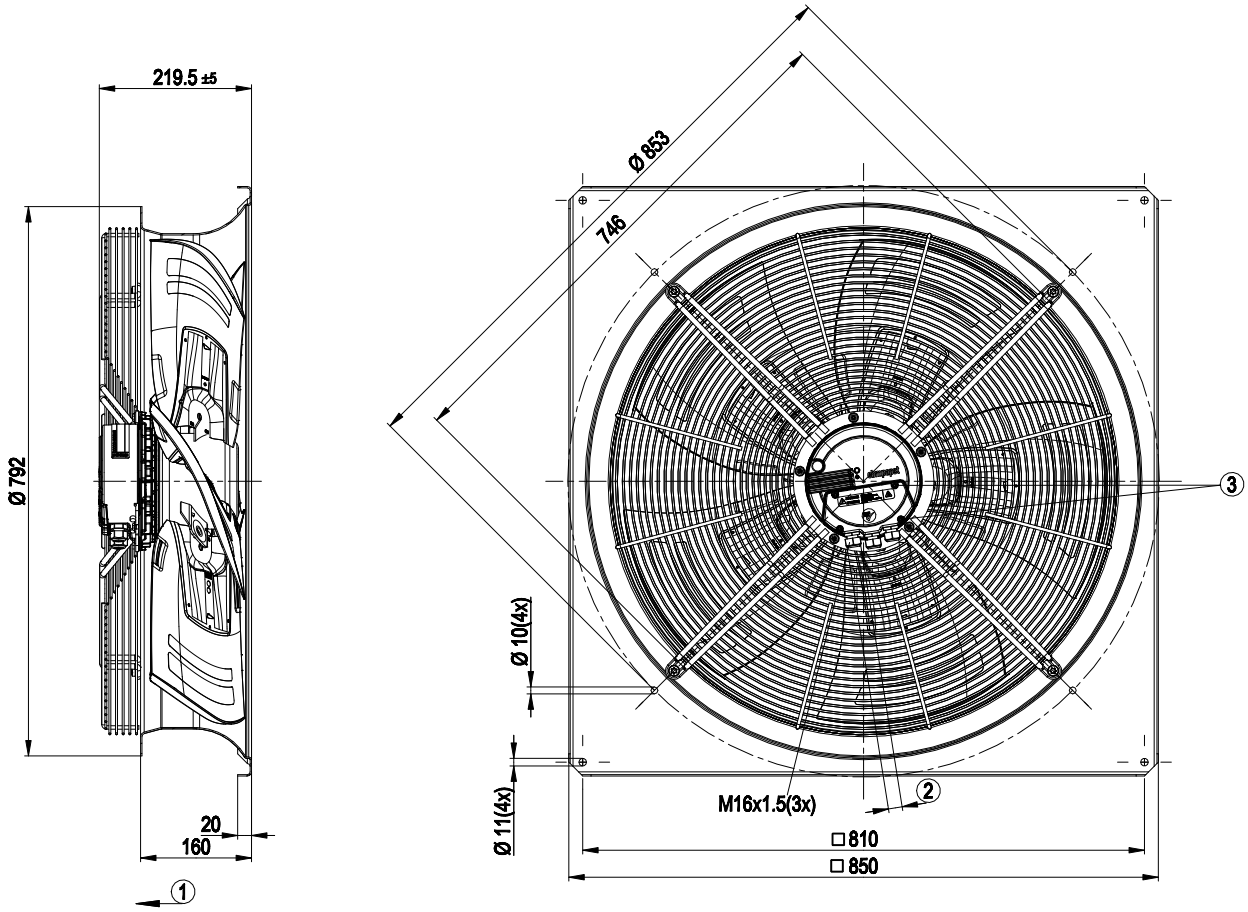
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Product drawing



1	Direction of air flow "V"
2	Cable diameter min. 4 mm, max. 10 mm; tightening torque 2±0.3 Nm
3	Tightening torque 3.5±0.5 Nm

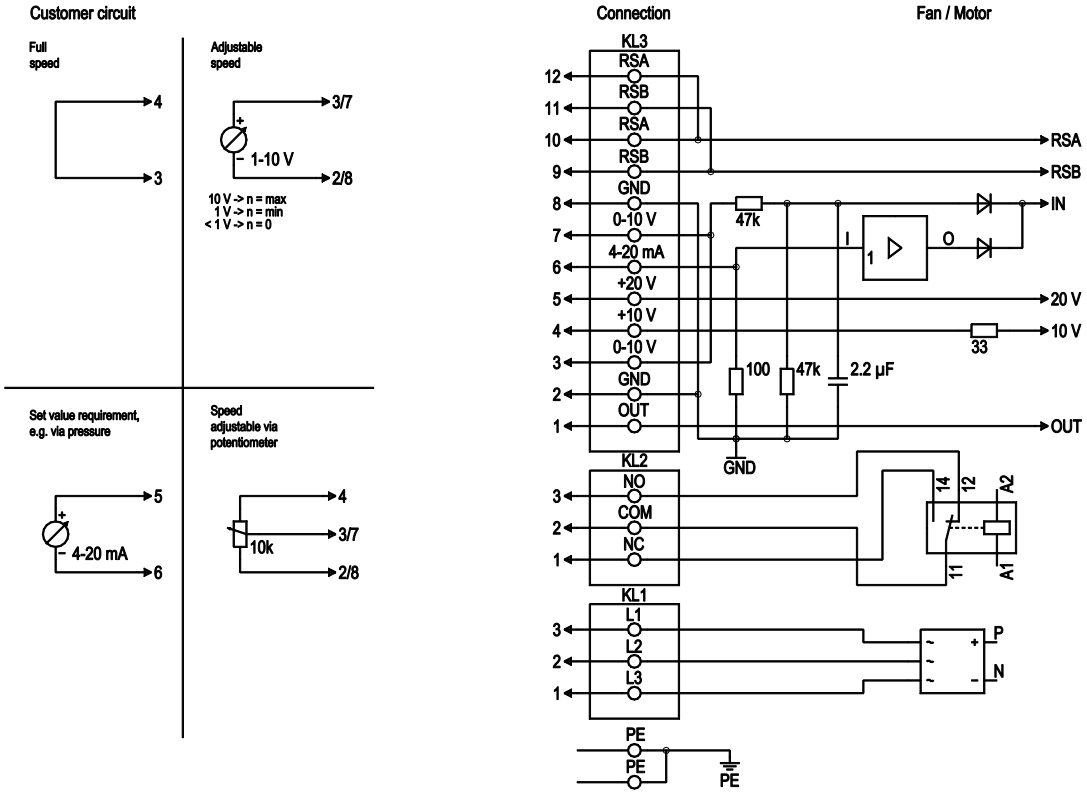
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Connection diagram



No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply, voltage range (see nameplate), 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

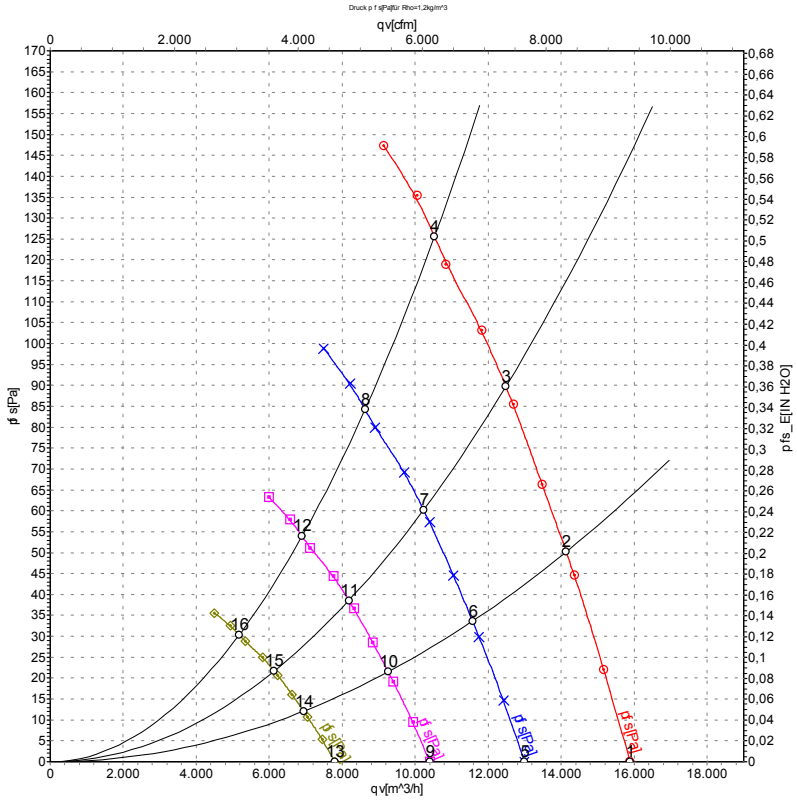
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Curves: Air performance 50 Hz



Measurement: LU-126878-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	200	50	900	583	1.81	63	70	70	15890	0	9355	0.00
2	200	50	900	719	2.22	62	69	69	14140	50	8320	0.20
3	200	50	900	822	2.55	65	71	72	12480	90	7345	0.36
4	200	50	900	930	3.00	72	79	79	10530	125	6200	0.50
5	200	50	750	319	0.99	59	65	65	12990	0	7645	0.00
6	200	50	750	394	1.22	58	64	65	11570	34	6810	0.14
7	200	50	750	452	1.40	61	67	67	10230	60	6020	0.24
8	200	50	750	506	1.56	68	74	75	8625	84	5075	0.34
9	200	50	600	163	0.51	54	60	61	10390	0	6115	0.00
10	200	50	600	202	0.62	53	60	60	9255	22	5450	0.09
11	200	50	600	231	0.72	56	62	62	8185	39	4815	0.16
12	200	50	600	259	0.80	63	69	70	6900	54	4060	0.22
13	200	50	450	69	0.21	48	54	54	7795	0	4590	0.00
14	200	50	450	85	0.26	47	53	54	6945	12	4085	0.05
15	200	50	450	98	0.30	50	56	56	6135	22	3610	0.09
16	200	50	450	109	0.34	57	63	64	5175	30	3045	0.12

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase

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