W3G650-DK23-05

EC axial fan

sickle-shaped blades (S series)

with square full nozzle

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**W3G650-DK23-05**	
Motor	**M3G150-IF**	
Phase		3~
Nominal voltage	V	400
Nominal voltage range	V	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min^{-1}	1500
Power consumption	W	2800
Current draw	A	4.3
Max. back pressure	Pa	300
Max. back pressure	inH2O	1.2
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	44.4	36.3
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		48.1	40
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	2.6
09 Air flow q_v	m^3/h	14260
09 Pressure increase p_{fs}	Pa	276
10 Speed (rpm) n	min^{-1}	1510
11 Specific ratio*		1.00

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-127870

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Technical description

Weight	41.9 kg
Fan size	650 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Sheet aluminum insert, sprayed with PP plastic
Fan housing material	Sheet steel, galvanized and coated with black plastic (RAL 9005)
Guard grille material	Steel, coated with black plastic (RAL 9005)
Number of blades	5
Blade pitch	-5°
Airflow direction	"A"
Direction of rotation	Counterclockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	H2
Max. permitted ambient temp. for motor (transport/storage)	+ 80 °C
Min. permitted ambient temp. for motor (transport/storage)	- 40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - External release input - Alarm relay - Integrated PID controller - Power limiter - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - EEPROM write cycles: 100,000 maximum - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	C22.2 No.77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730

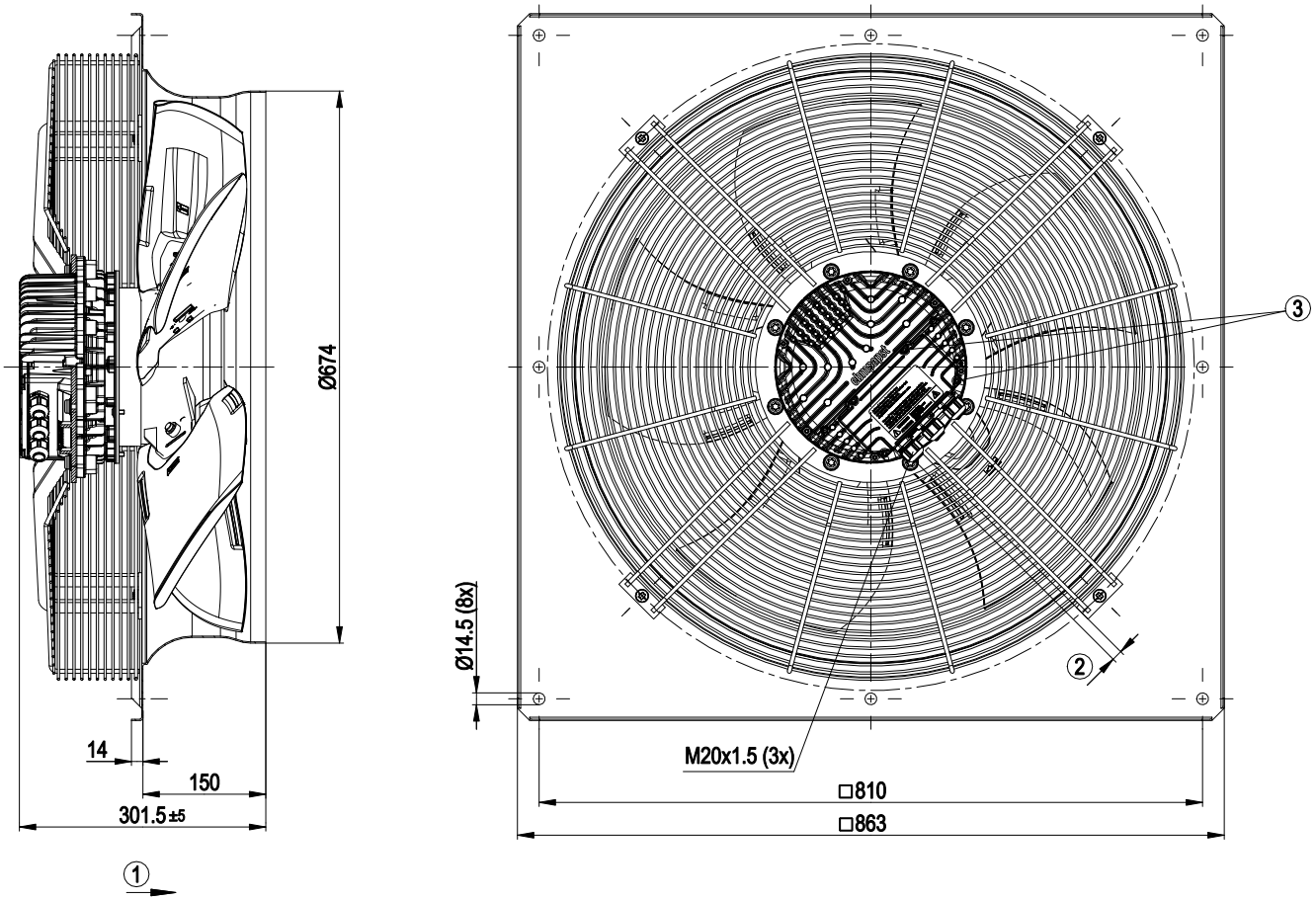
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Product drawing



1	Direction of air flow "A"
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
3	Tightening torque 3.5 ± 0.5 Nm

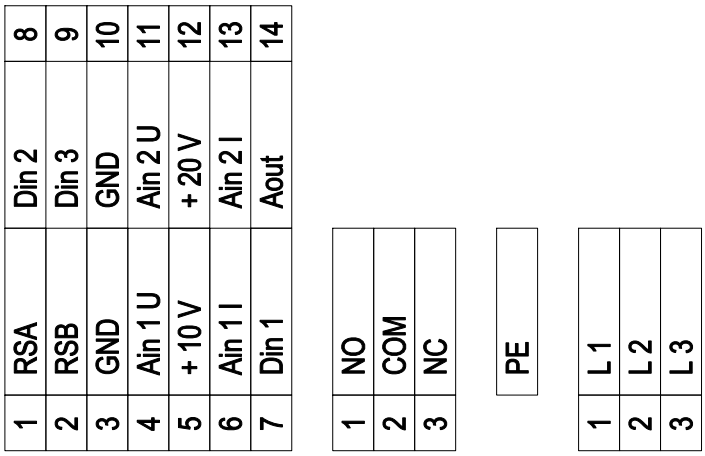
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Connection diagram



No.	Conn.	Designation	Function/assignment
KL 1	1	L1	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	2	L2	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
KL 1	3	L3	Supply connection, power supply 3-phase 380-480 VAC, 50/60 Hz
PE		PE	Ground connection, PE connection
KL 2	1	NO	Status relay, floating status contact; make for failure
KL2	2	COM	Status relay, floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break for failure
KL 3	1	RSA	Bus connection RS485, RSA, MODBUS-RTU; SELV
KL 3	2	RSB	Bus connection RS485, RSB, MODBUS-RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analog input 1, set value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain1 I; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof power supply for external devices (e.g. pot); SELV
KL 3	6	Ain1 I	Analog input 1, set value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain1U; SELV
KL 3	7	Din1	Digital input 1: enable electronics, enable: pin open or applied voltage 5-50 VDC disable: bridge to GND or applied voltage < 1 VDC reset function: triggers software reset after a level change to < 1 VDC; SELV
KL 3	8	Din2	Digital input 2: Switching parameter sets 1/2, according to EEPROM setting, the valid or used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	9	Din3	Digital input 3: according to EEPROM setting, the integrated controller's direction of action can be selected as normal/inverse via bus or digital input normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage < 1 VDC; SELV
KL 3	11	Ain2 U	Analog input 2, measured value: 0-10 V, Ri = 100 kΩ, adjustable curve, only usable as alternative to input Ain2I; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof power supply for external devices (e.g. sensors); SELV

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No.	Conn.	Designation	Function/assignment
KL 3	13	Ain2 I	Analog input 2, measured value: 4-20 mA, Ri = 100 Ω, adjustable curve, only usable as alternative to input Ain2U; SELV
KL 3	14	Aout	Analog output 0-10 VDC, max. 5 mA, output of current motor modulation level / motor speed adjustable curve; SELV

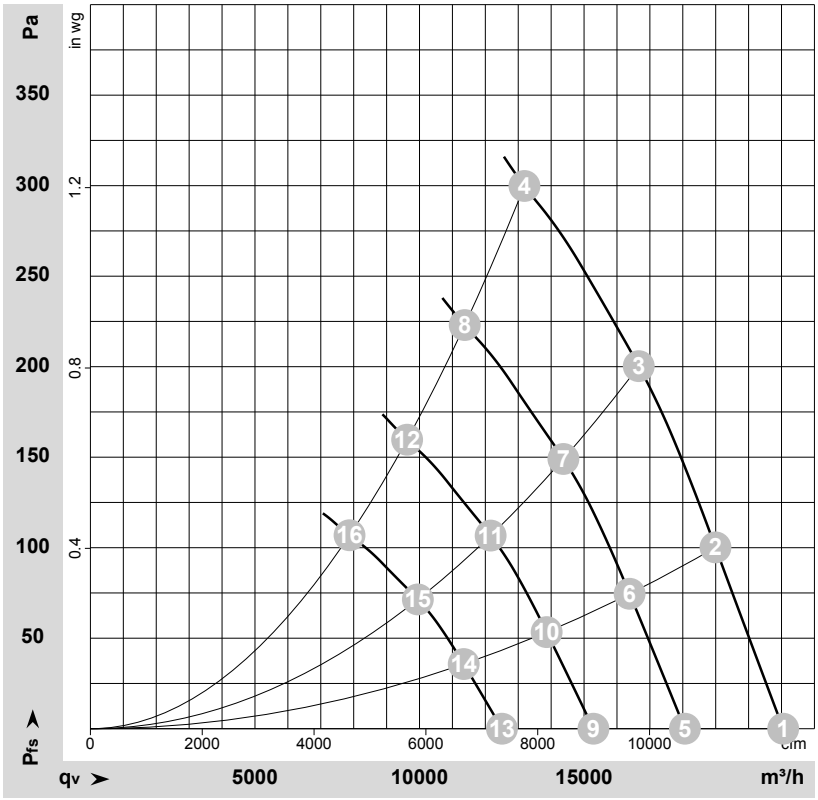
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Curves: Air performance 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-127870-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	400	50	1500	1747	2.69	75	86	87	21050	0	12390	0.00
2	400	50	1500	2045	3.14	72	84	84	18995	100	11180	0.40
3	400	50	1500	2346	3.59	75	86	86	16660	200	9805	0.80
4	400	50	1500	2800	4.30	76	88	88	13190	300	7760	1.20
5	400	50	1300	1104	1.70	71	83	83	18065	0	10630	0.00
6	400	50	1300	1313	2.02	69	80	81	16385	75	9645	0.30
7	400	50	1300	1506	2.30	71	82	82	14370	149	8460	0.60
8	400	50	1300	1748	2.68	72	84	84	11375	223	6695	0.90
9	400	50	1100	669	1.03	66	78	79	15285	0	8995	0.00
10	400	50	1100	795	1.22	64	76	76	13865	53	8160	0.21
11	400	50	1100	912	1.40	67	78	78	12160	107	7160	0.43
12	400	50	1100	1059	1.62	68	80	80	9625	159	5665	0.64
13	400	50	900	366	0.56	61	73	74	12505	0	7360	0.00
14	400	50	900	436	0.67	59	71	71	11345	36	6675	0.14
15	400	50	900	500	0.76	62	73	73	9950	72	5855	0.29
16	400	50	900	580	0.89	63	75	75	7875	107	4635	0.43

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase

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