K3G355-RT01-J3

EC centrifugal module - RadiCal

backward curved, single inlet

with support bracket

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Nominal data

Type	**K3G355-RT01-J3**
Motor	**M3G084-GF**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min^{-1}	2100
Power input	W	770
Current draw	A	1.2
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data in accordance with ecodesign regulation EU 327/2011 (EN 17166)

		Actual	Request 2015
01 Overall efficiency η_{es}	%	66	50.2
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		77.8	62
05 Variable speed drive		Yes	

09 Power input P_{ed}	kW	0.75
09 Air flow q_v	m^3/h	3205
09 Pressure increase p_{fs}	Pa	511
10 Speed (rpm) n	min^{-1}	2100
11 Specific ratio*		1.01

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

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Technical features

Mass	15.1 kg
Size	355 mm
Motor size	84
Surface of rotor	Coated in black
Material of terminal box	PP plastic
Material of electronics housing	Die-cast aluminium
Material of impeller	PA plastic
Material of mounting plate	Sheet steel, galvanised
Material of support bracket	Steel, coated in black
Material of inlet nozzle	Sheet steel, galvanised
Number of blades	6
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP55
Insulation class	"F"
Humidity (F) / environmental protection class (H)	H1
Note ambient temperature	Occasional start-up between -40 °C and -25 °C is permissible. For continuous operation at ambient temperatures below -25 °C (e.g. refrigeration applications), a fan version with special low-temperature bearings must be used.
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - Alarm relay - Integrated PID controller - Output limit - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start -Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Temperature derating - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA

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Electrical connection	Terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Cable exit	Variable
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	CSA C22.2 no. 77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730-1

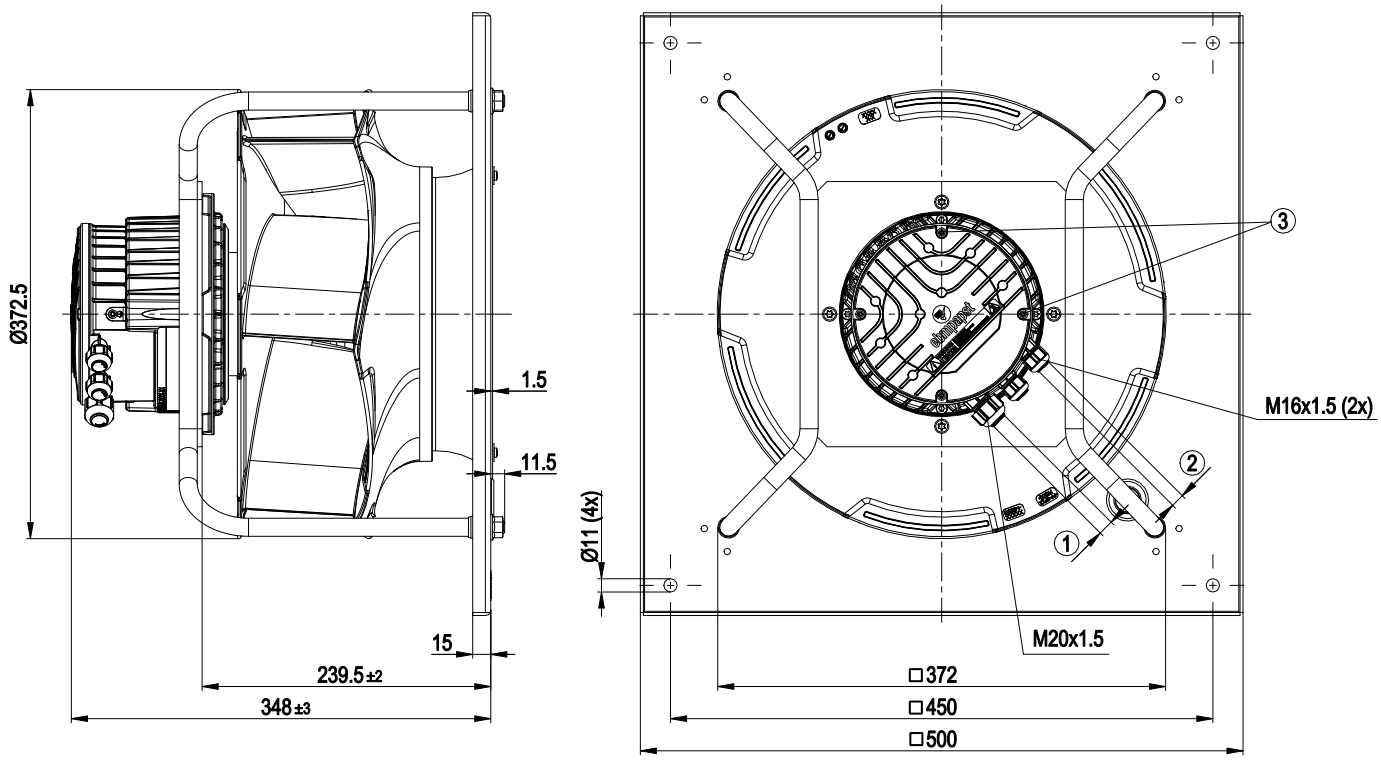
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Product drawing



1	Cable diameter min. 8 mm, max. 12 mm, tightening torque 1.8±0.3 Nm (use the provided seal) Cable diameter min. 4 mm, max. 10 mm, tightening torque 1.8±0.3 Nm
2	Cable diameter min. 6 mm, max. 10 mm, tightening torque 1.8±0.3 Nm (use the provided seal) Cable diameter min. 4 mm, max. 7 mm, tightening torque 1.8±0.3 Nm
3	Tightening torque 1.5±0.2 Nm

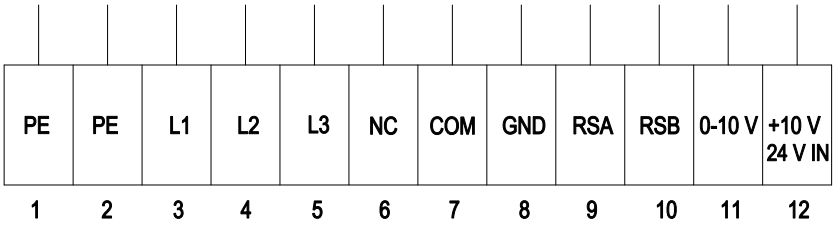
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Connection screen



No.	Conn.	Designation	Function / assignment
	1	PE	Protective earth
	2	PE	Protective earth
	3	L1	Power supply
	4	L2	Power supply
	5	L3	Power supply
	6	NC	Status relay, floating status contact, break for failure, contact rating 250 VAC / 2 A (AC1) / min. 10 mA; reinforced insulation on mains side and basic insulation on control interface side
	7	COM	Status relay, floating status contact, break for failure, contact rating 250 VAC / 2 A (AC1) / min. 10 mA; reinforced insulation on mains side and basic insulation on control interface side
	8	GND	Signal ground for control interface, SELV
	9	RSA	RS-485 interface for MODBUS, RSA; SELV
	10	RSB	RS-485 interface for MODBUS, RSB; SELV
	11	0-10 V	Analogue input (set value) SELV, 0-10 V, Ri=100kΩ, parametrisable curve
	12	+10 V	Fixed voltage output 10 VDC, SELV, +10 V +/-3%, max. 10 mA short-circuit-proof, power supply for ext. devices (e.g. potentiometer); Fixed voltage input 24 VDC for parameter setting via MODBUS without mains power supply

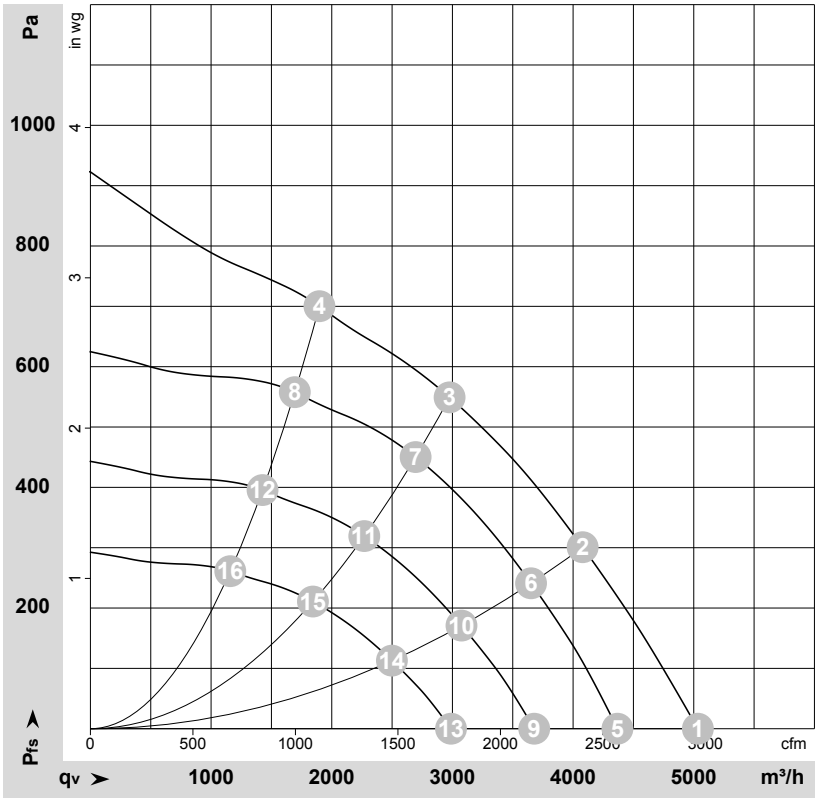
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Charts: Air flow 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-160393-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	m^3/h	Pa	cfm	in. wg
1	400	50	2190	605	0.95	5035	0	2965	0.00
2	400	50	2125	726	1.14	4080	300	2400	1.20
3	400	50	2100	770	1.20	2975	550	1750	2.21
4	400	50	2130	724	1.13	1900	700	1115	2.81
5	400	50	1900	395	0.62	4370	0	2570	0.00
6	400	50	1900	520	0.81	3650	241	2150	0.97
7	400	50	1900	571	0.89	2695	451	1585	1.81
8	400	50	1900	515	0.81	1695	558	995	2.24
9	400	50	1600	236	0.37	3680	0	2165	0.00
10	400	50	1600	311	0.49	3075	171	1810	0.69
11	400	50	1600	341	0.53	2270	320	1335	1.28
12	400	50	1600	308	0.48	1425	396	840	1.59
13	400	50	1300	127	0.20	2990	0	1760	0.00
14	400	50	1300	167	0.26	2500	113	1470	0.45
15	400	50	1300	183	0.29	1845	211	1085	0.85
16	400	50	1300	165	0.26	1160	261	680	1.05

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · q_V = Air flow · p_{fs} = Pressure increase

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