A3G800-AM67-23

EC axial fan - HyBlade

sickle-shaped blades (S series)



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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**A3G800-AM67-23**
Motor	**M3G112-EA**

Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	470
Power consumption	W	220
Current draw	A	1.0
Max. back pressure	Pa	45
Max. back pressure	inH2O	0.18
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	42.6	29.3
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		53.3	40
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	0.2
09 Air flow q_v	m^3/h	7675
09 Pressure increase p_{fs}	Pa	37
10 Speed (rpm) n	min^{-1}	470
11 Specific ratio*		1.00

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-118346

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Technical description

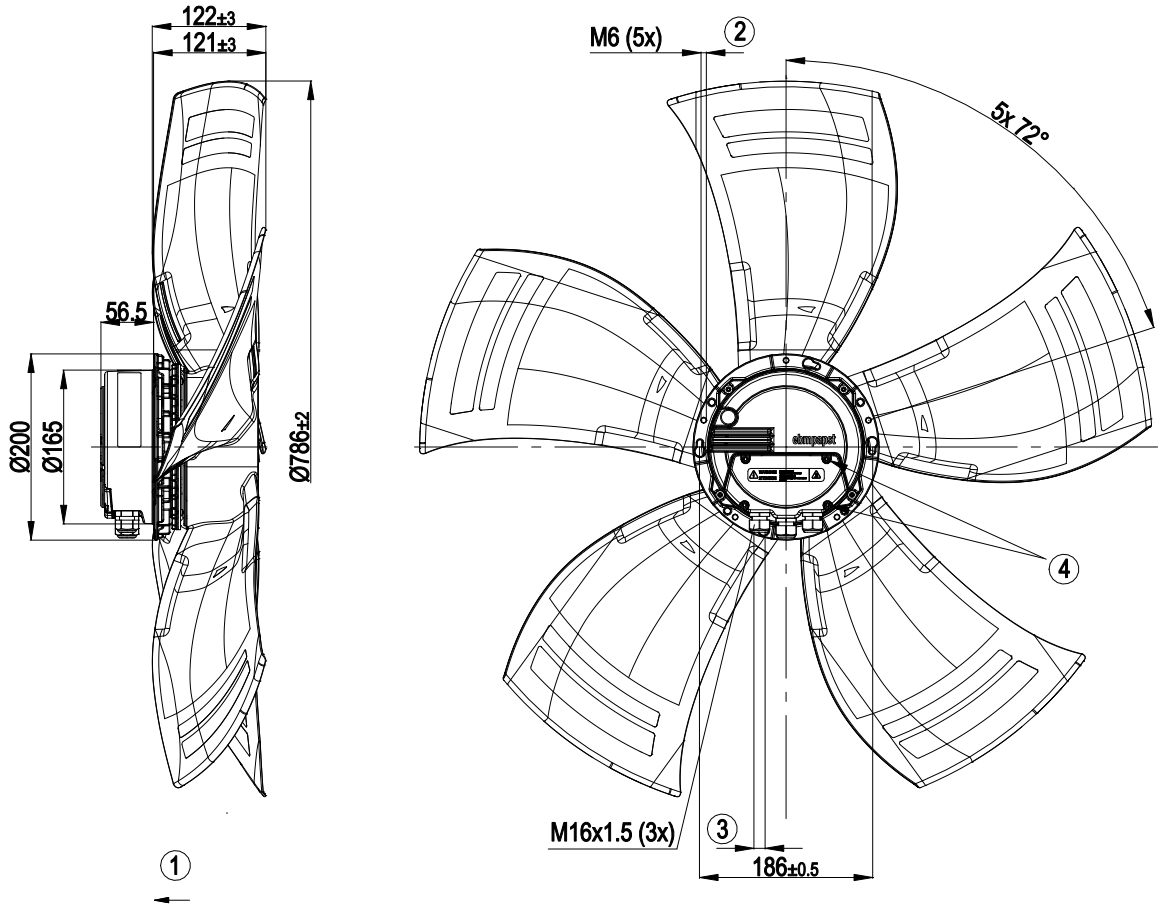
Weight	8 kg
Fan size	800 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Blade material	Press-fitted sheet steel blank, sprayed with PP plastic
Number of blades	5
Airflow direction	"V"
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, active - RS-485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Thermal overload protection for electronics/motor - Line undervoltage detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-4 (industrial environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC

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Product drawing



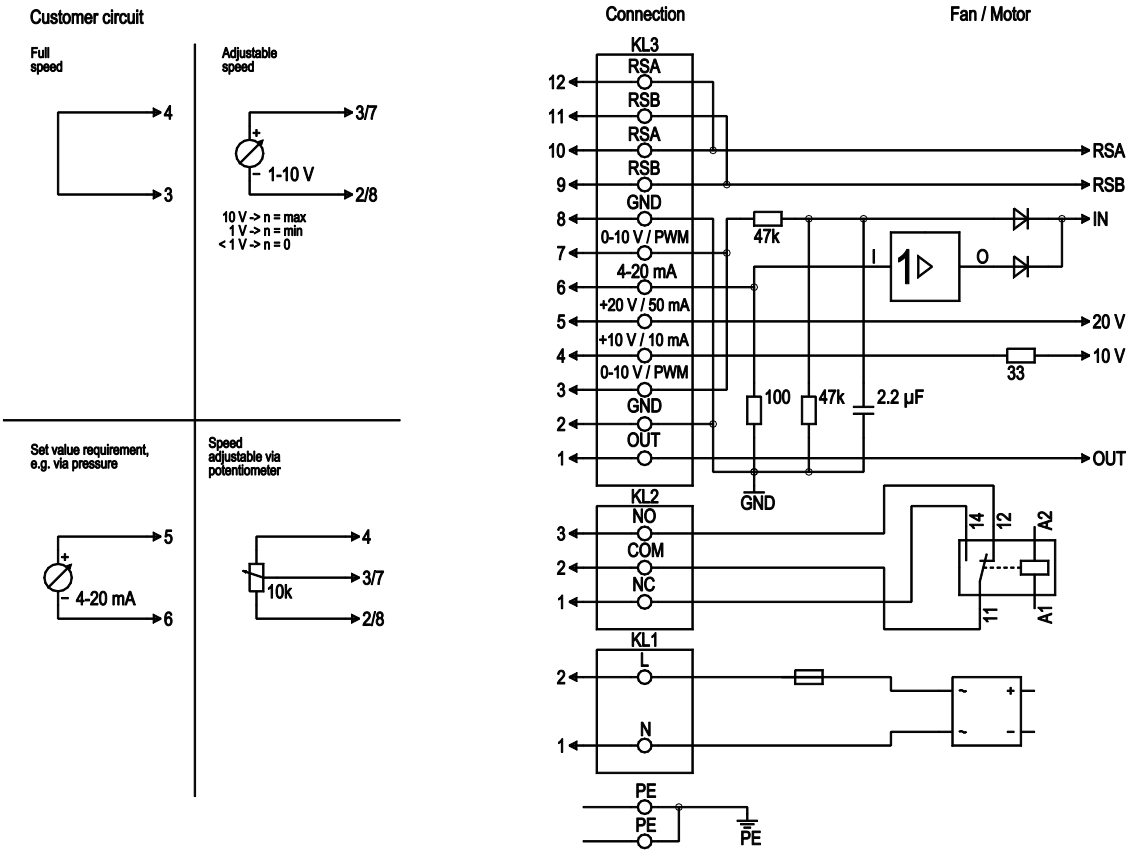
1	Direction of air flow "V"
2	Max. clearance for screw 16 mm
3	Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5 ± 0.4 Nm
4	Tightening torque 3.5±0.5 Nm

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Connection diagram



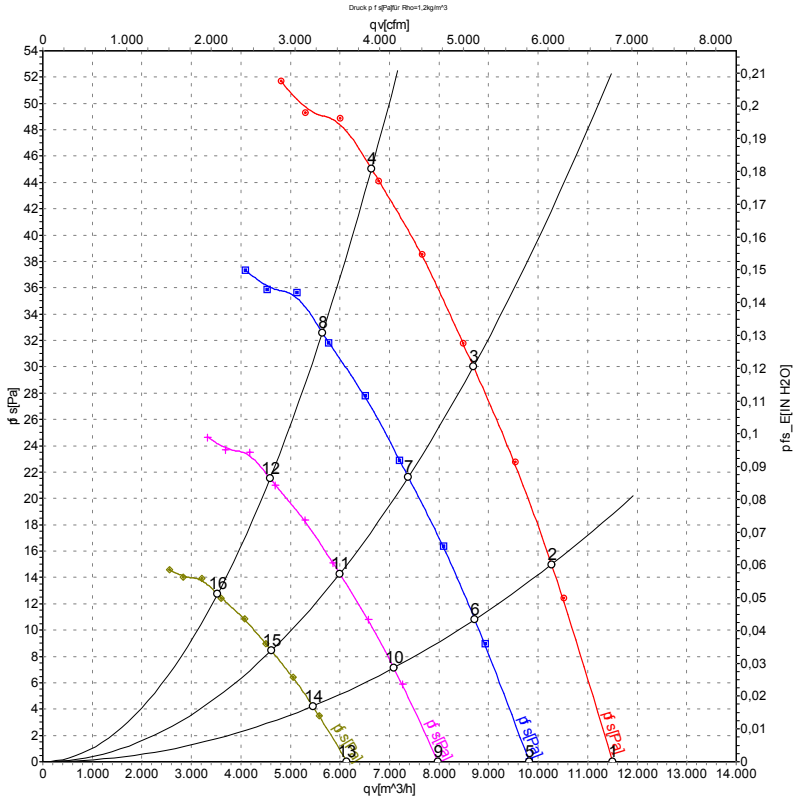
No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2	N, L	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3 %), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25% / -10%), max. 50 mA, power supply for external devices (e.g. sensors); SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBUS, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBUS, RSA, SELV

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Curves: Air performance 50 Hz



Measurement: LU-118346-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	230	50	470	143	0.85	53	59	58	11510	0	6775	0.00
2	230	50	470	172	0.99	51	57	56	10270	15	6045	0.06
3	230	50	470	194	0.95	48	54	53	8695	30	5115	0.12
4	230	50	470	220	1.00	51	58	58	6635	45	3905	0.18
5	230	50	400	89	0.53	49	55	55	9825	0	5780	0.00
6	230	50	400	105	0.61	47	53	53	8720	11	5135	0.04
7	230	50	400	119	0.58	44	50	50	7380	22	4345	0.09
8	230	50	400	134	0.63	47	55	54	5645	33	3325	0.13
9	230	50	325	48	0.28	45	51	50	7980	0	4695	0.00
10	230	50	325	56	0.33	43	49	48	7085	7	4170	0.03
11	230	50	325	64	0.31	40	46	45	5995	14	3530	0.06
12	230	50	325	72	0.34	43	50	50	4585	22	2700	0.09
13	230	50	250	22	0.13	39	45	44	6140	0	3615	0.00
14	230	50	250	26	0.15	37	43	42	5450	4	3210	0.02
15	230	50	250	29	0.14	34	40	40	4610	8	2715	0.03
16	230	50	250	33	0.15	37	44	44	3530	13	2075	0.05

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase

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