K3G250-AV29-B4

EC centrifugal module - RadiPac

backward-curved, single-intake

with support bracket

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**K3G250-AV29-B4**
Motor	**M3G084-FA**

Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	3450
Power consumption	W	750
Current draw	A	3.3
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	62.5	50.2
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		74.3	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	0.75
09 Air flow q_v	m^3/h	1755
09 Pressure increase p_{fs}	Pa	889
10 Speed (rpm) n	min^{-1}	3490
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-142908

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Technical description

Weight	10.1 kg
Fan size	250 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum, painted black
Impeller material	Sheet aluminum, painted black
Support plate material	Sheet steel, galvanized and painted black
Support bracket material	Steel, painted black
Inlet nozzle material	Sheet steel, galvanized and painted black
Number of blades	7
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F4-2
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Motor current limitation - PFC, active - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 55022 (Class B, household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (if protective earth is connected by customer to the housing's connection point)
Conformity with standards	EN 61800-5-1; CE
Approval	CCC; EAC

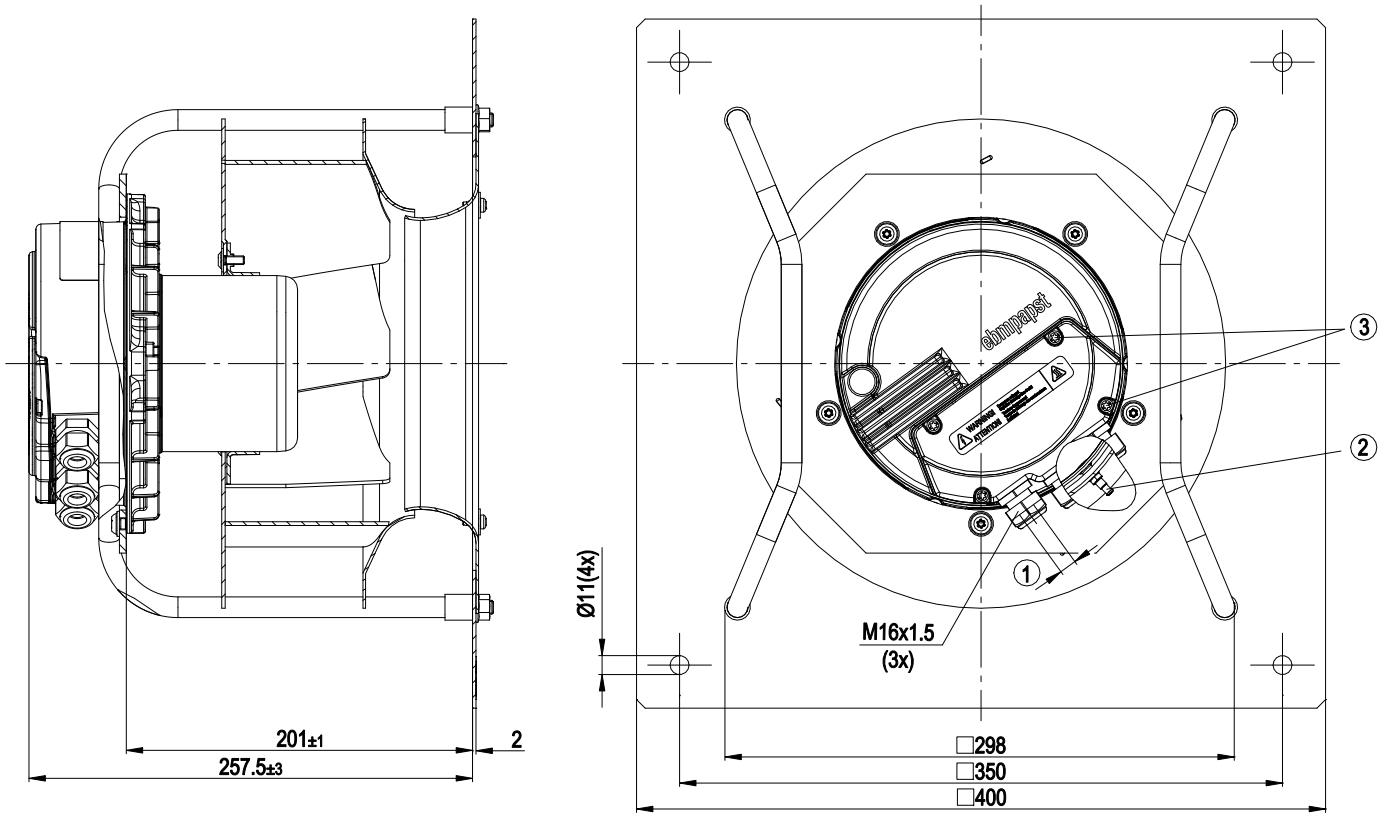
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Product drawing



1	Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5 ± 0.4 Nm
2	Inlet ring with pressure tap (k-factor: 70)
3	Tightening torque 3.5 ± 0.5 Nm

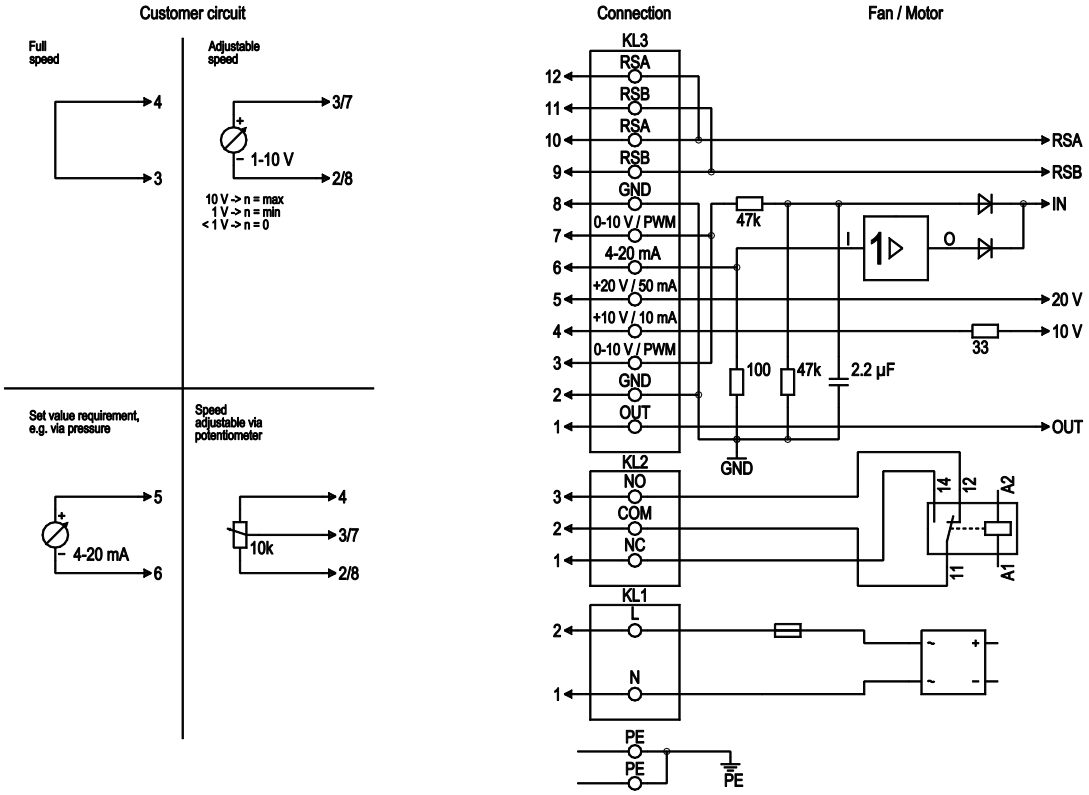
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Connection diagram



No.	Conn.	Designation	Function/assignment
PE	-	PE	Protective earth terminal
KL1	1, 2	N, L	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Control/current sensor value input 0-10 VDC, impedance 100 kΩ, use only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/- 3%), max. 10 mA, power supply for ext. devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA power supply for ext. devices (e.g. sensors), SELV
KL3	6	4-20 mA	Control/current sensor value input 4-20 mA, impedance 100 Ω, use only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

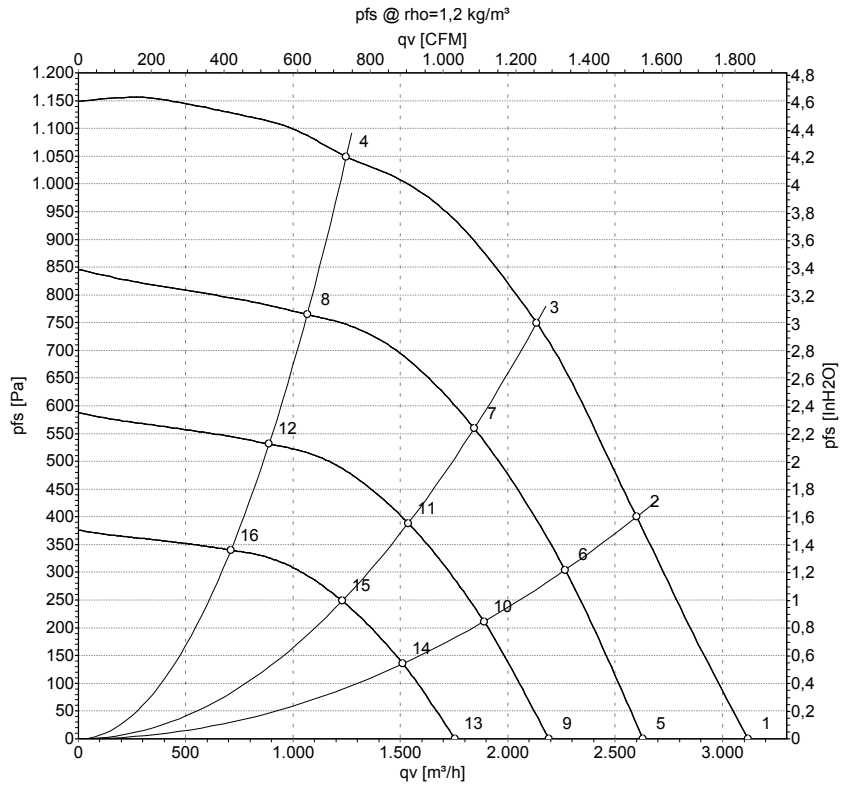
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Curves: Air performance 50 Hz



Measurement: LU-142908-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	230	50	3450	581	2.58	77	85	91	3120	0	1835	0.00
2	230	50	3450	673	2.98	74	82	88	2600	400	1530	1.61
3	230	50	3450	750	3.30	71	79	85	2135	750	1255	3.01
4	230	50	3450	691	3.07	79	86	87	1250	1050	735	4.22
5	230	50	3000	349	1.55	73	80	87	2630	0	1550	0.00
6	230	50	3000	446	1.97	71	78	84	2265	304	1335	1.22
7	230	50	3000	486	2.16	68	75	81	1845	559	1085	2.24
8	230	50	3000	432	1.92	75	82	83	1065	765	625	3.07
9	230	50	2500	202	0.90	68	76	82	2195	0	1290	0.00
10	230	50	2500	258	1.14	66	74	80	1890	211	1110	0.85
11	230	50	2500	281	1.25	63	71	76	1535	388	905	1.56
12	230	50	2500	250	1.11	70	77	78	890	531	525	2.13
13	230	50	2000	103	0.46	63	70	76	1755	0	1030	0.00
14	230	50	2000	132	0.59	60	68	74	1510	135	890	0.54
15	230	50	2000	144	0.64	57	65	71	1230	249	725	1.00
16	230	50	2000	128	0.57	64	72	72	710	340	420	1.36

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase

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