R3G630-AA26-21

EC centrifugal fan

backward curved, single inlet

ebm-papst Mulfingen GmbH & Co. KG
Bachmühle 2 · D-74673 Mulfingen
Phone +49 7938 81-0
Fax +49 7938 81-110
info1@de.ebmpapst.com
www.ebmpapst.com

Limited partnership · Headquarters Mulfingen
County court Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen
County court Stuttgart · HRB 590142

ErP2015 EXCEEDS THE NORM

Nominal data

Type	**R3G630-AA26-21**
Motor	**M3G150-FF**

Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Type of data definition		ml
Speed	min^{-1}	960
Power input	W	1400
Current draw	A	6.1
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	55

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.00

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}	%	56.7	48.9	52.9
Efficiency grade N		65.8	58	62
Power input P_{ed}	kW	1.37		
Air flow q_v	m^3/h	9005		
Pressure increase p_{fs}	Pa	290		
Speed n	min^{-1}	960		

Data definition with optimum efficiency. LU-121784
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

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Technical features

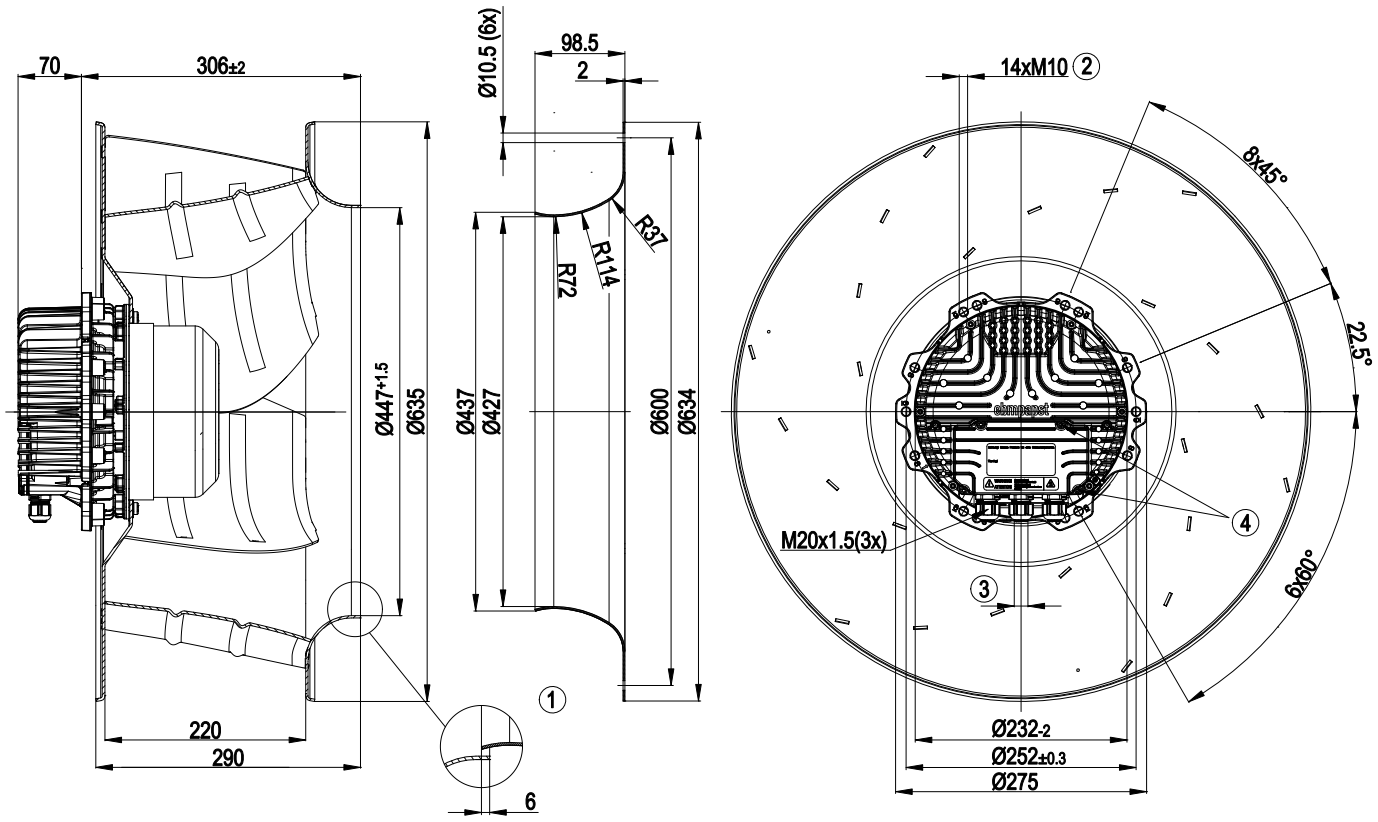
Mass	24.2 kg
Size	630 mm
Material of impeller	Aluminium sheet
Housing material	Die-cast aluminium
Number of blades	6
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+ 80 °C
Min. permissible ambient motor temp. (transp./storage)	- 40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Tach output - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Output limit - Motor current limit - PFC, active - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC

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Product drawing



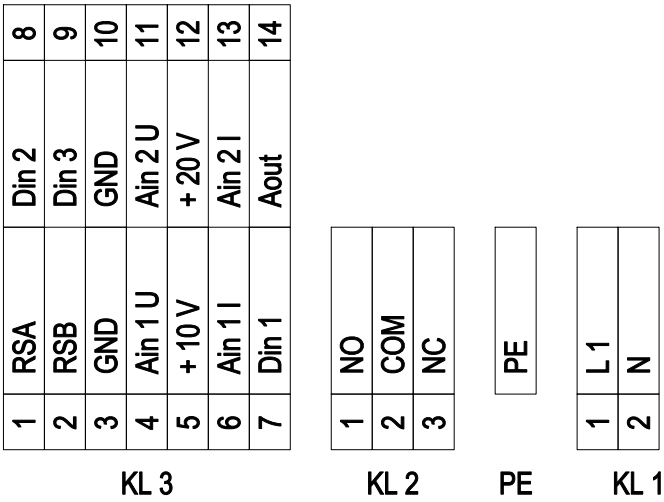
1	Accessory part: inlet nozzle 63070-2-4013 not included in the standard scope of delivery; other inlet nozzles on request
2	Depth of screw max. 25 mm
3	Cable diameter: min. 4 mm, max. 10 mm, tightening torque: 4±0.6 Nm
4	Tightening torque 3.5±0.5 Nm

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Connection screen



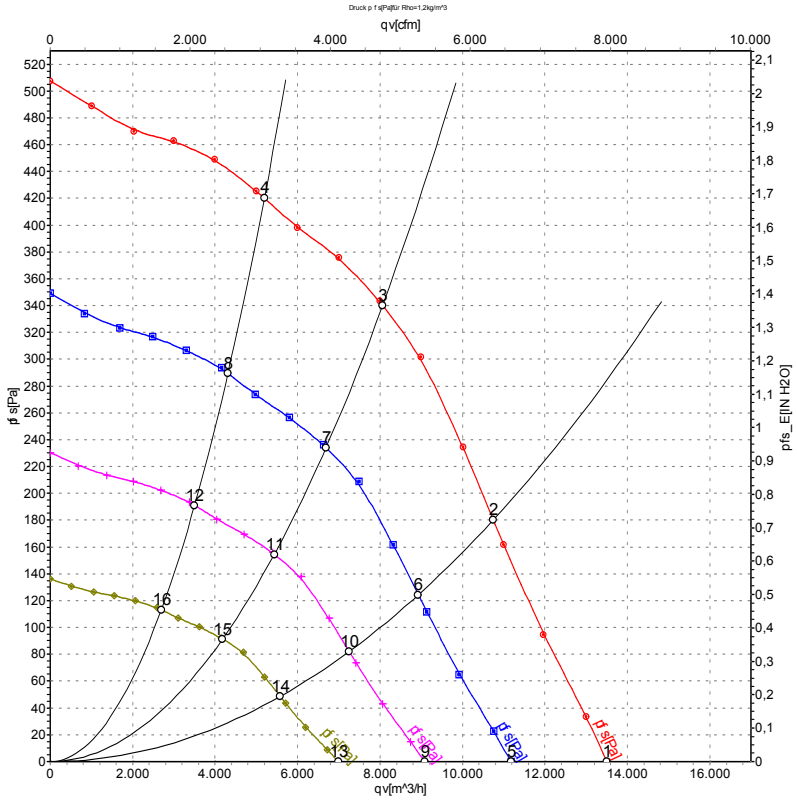
No.	Conn.	Designation	Function / assignment
KL1	1	L1	Mains supply connection, supply voltage 1~200-277 V AC; 50/60 Hz
KL1	2	N	Mains supply connection, supply voltage 1~200-277 V AC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL2	1	NO	Status relay, floating status contact; option 1: close with error; option 2: close with run monitor error message
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; option 1: break with error; option 2: break with error for run monitor error message
KL3	1	RSA	Bus connection RS485; RSA; MODBUS RTU
KL3	2	RSB	Bus connection RS485; RSB; MODBUS RTU
KL3	3	GND	Signal ground for control interface
KL3	4	Ain1 U	Analog input 1 (set value); 0-10 V; Ri= 100kOhm; parametrisable curve; only usable as alternative to input Ain1 I
KL3	5	+10 V	Fixed voltage output 10 VDC; + 10 V +/-3%; max. 10 mA; short circuit proof; power supply for ext. devices (e.g. potentiometer)
KL3	6	Ain1 I	Analog input 1 (set value); 4-20 mA; Ri= 100 Ohm; parametrisable curve; only usable as alternative to input Ain1 U
KL3	7	Din1	Digital input 1: enabling of electronics; enabling: open pin or applied voltage 5 to 50 VDC; disabling: bridge to GND or applied voltage < 0.8 VDC; reset function: triggers software reset after a level change to <0.8 V
KL3	8	Din2	Digital input 2: parameter set switch 1/2; according to EEPROM setting, the valid/used parameter set is selectable per BUS or per digital input DIN2. Parameter set 1: open pin or applied voltage 5 to 50 VDC; parameter set 2: bridge to GND or applied voltage < 0.8 VDC
KL3	9	Din3	Digital input 3: control characteristic of the integrated controller; according to EEPROM setting, the control characteristic of the integrated controller is normally/inversely selectable per BUS or per digital input; normal: open pin or applied voltage 5 to 50 VDC; inverse: bridge to GND or applied voltage < 0.8 VDC
KL3	10	GND	Signal ground for control interface
KL3	11	Ain2 U	Analog input 2; actual sensor value 0-10 V; Ri= 100kOhm; parametrisable curve; only usable as alternative to input Ain2 I
KL3	12	+20 V	Fixed voltage output 20 VDC; + 20V +25/-10%; max. 50 mA; short circuit proof; power supply for ext. devices (e.g. sensors)
KL3	13	Ain2 I	Analog input 2; actual sensor value 4-20 mA; Ri= 100 Ohm; parametrisable curve; only alternative to input Ain2 U
KL3	14	Aout	Analogue output 0-10 V; max. 5 mA; output of the actual motor control factor (output voltage of electronics)/ of the actual motor speed. Parametrisable curve.

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Charts: Air flow 50 Hz



Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa
1	230	50	960	973	4.25	80	88	89	13510	0
2	230	50	960	1219	5.33	72	79	82	10750	180
3	230	50	960	1400	6.10	66	74	80	8065	340
4	230	50	960	1219	5.33	67	74	80	5195	420
5	230	50	800	552	2.41	76	84	85	11180	0
6	230	50	800	698	3.05	68	74	78	8930	124
7	230	50	800	799	3.50	62	70	76	6690	235
8	230	50	800	698	3.05	63	70	76	4310	290
9	230	50	650	296	1.29	71	79	81	9085	0
10	230	50	650	375	1.64	63	70	73	7255	82
11	230	50	650	429	1.88	58	65	71	5435	155
12	230	50	650	374	1.64	58	66	72	3505	191
13	230	50	500	135	0.59	65	73	75	6990	0
14	230	50	500	170	0.75	57	64	68	5580	48
15	230	50	500	195	0.85	52	60	66	4180	92
16	230	50	500	170	0.74	52	60	66	2695	113

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
qv = Air flow · p_{fs} = Pressure increase

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