R3G630-AE06-03

EC centrifugal fan

backward-curved, single-intake



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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**R3G630-AE06-03**
Motor	**M3G150-IF**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Status		prelim.
Speed (rpm)	min^{-1}	1200
Power consumption	W	2500
Current draw	A	4.1
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	61.2	55.5
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		67.7	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	2.4
09 Air flow q_v	m^3/h	8370
09 Pressure increase p_{fs}	Pa	597
10 Speed (rpm) n	min^{-1}	1210
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-112222

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Technical description

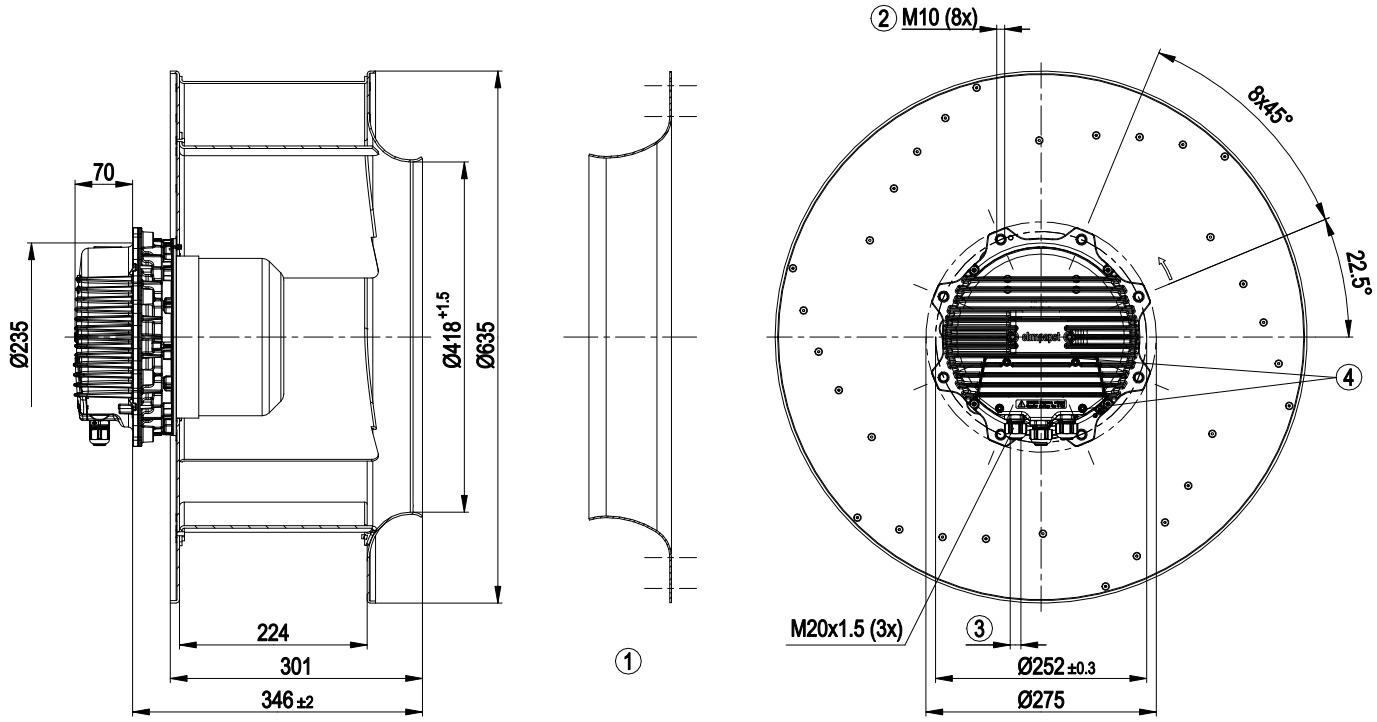
Weight	28.6 kg
Fan size	630 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP55
Insulation class	"F"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	CSA C22.2 No. 77; EAC; UL 2111; VDE

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Product drawing



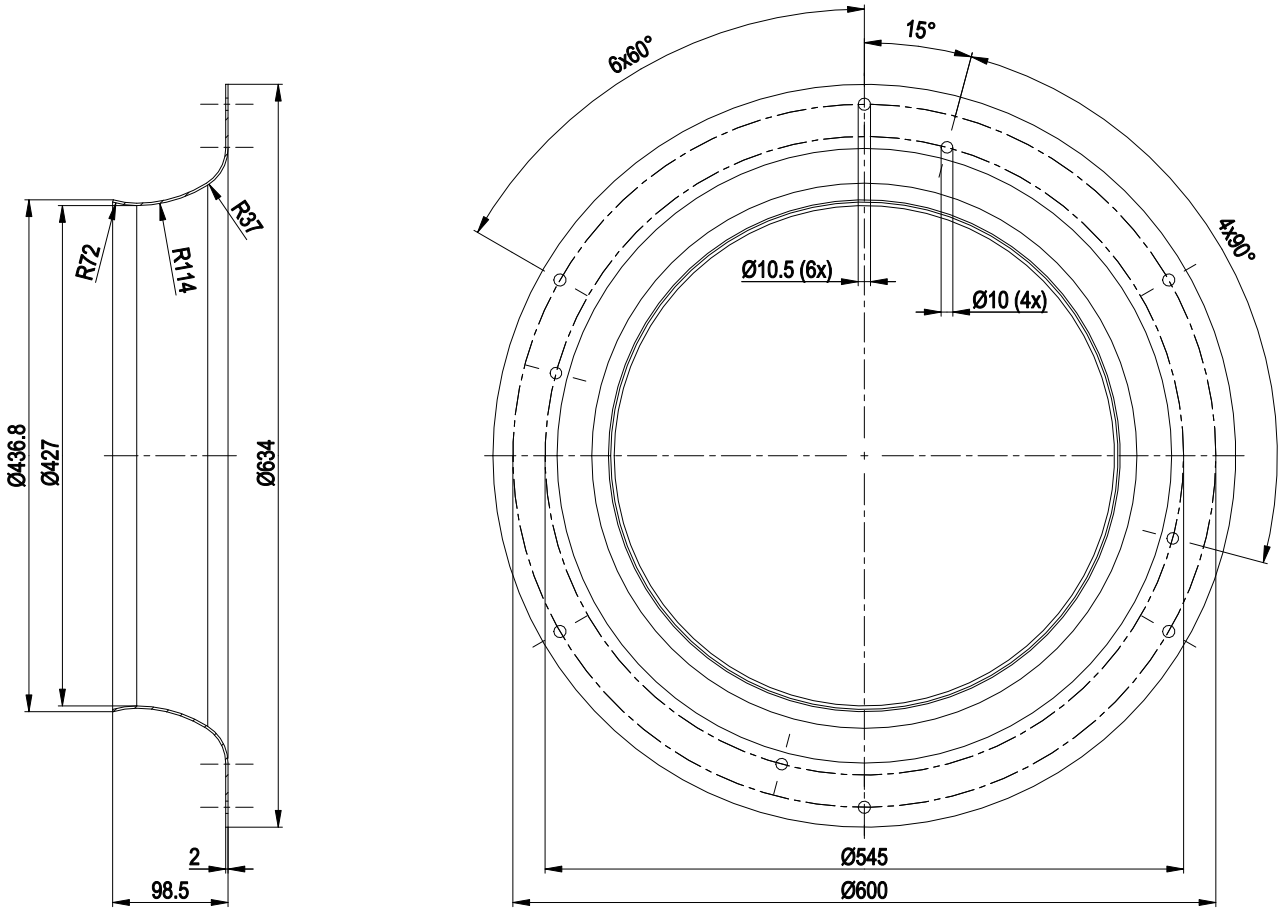
1	Accessory part: inlet ring 63070-2-4013 not included in scope of delivery
2	Max. clearance for screw 25 mm
3	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4 ± 0.6 Nm
4	Tightening torque 3.5 ± 0.5 Nm

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Accessory part



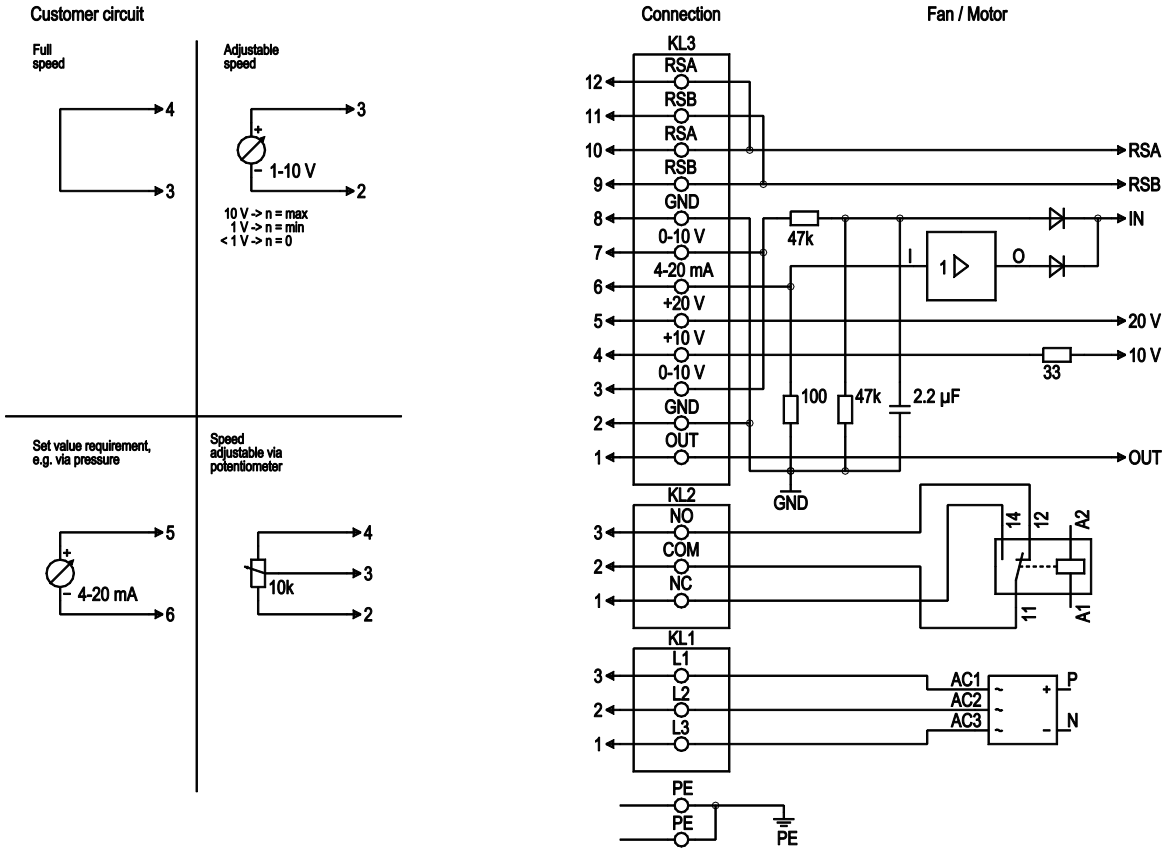
Inlet ring 63070-2-4013 not included in scope of delivery

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Connection diagram



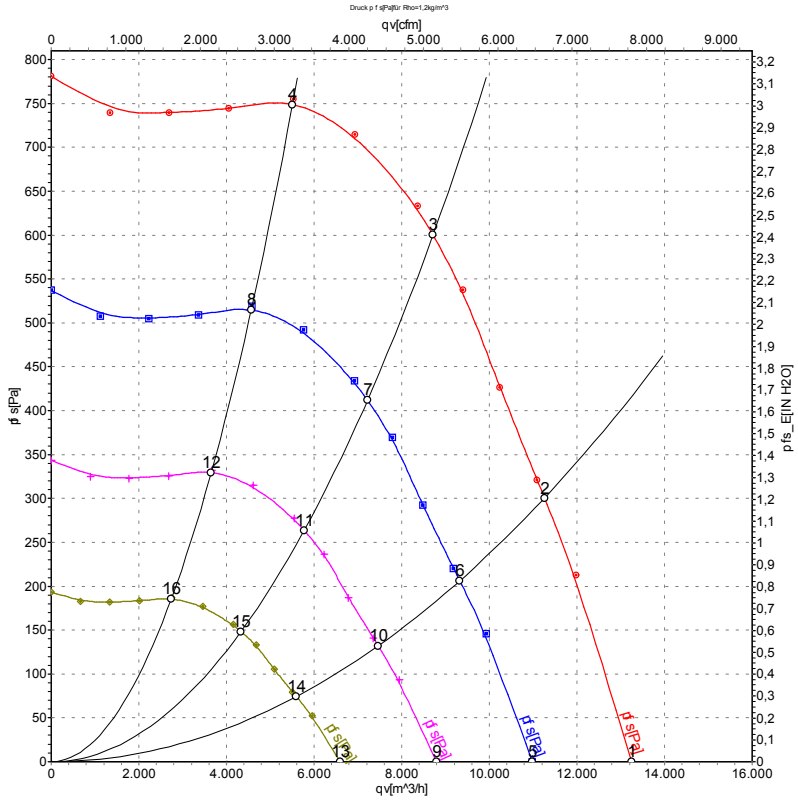
No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10 % modulation level. 10 V corresponds to 100 % modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3 %), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25% / -10%), max. 50 mA, power supply for external devices (e.g. sensors); SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBUS, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBUS, RSA, SELV

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Curves: Air performance 50 Hz Y



Measurement: LU-112222-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}	qv	p_{fs}
		V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	Y	400	50	1200	1712	2.58	76	84	90	13250	0	7800	0.00
2	Y	400	50	1200	2037	3.08	73	82	88	11260	300	6625	1.20
3	Y	400	50	1200	2400	3.70	70	78	84	8715	600	5130	2.41
4	Y	400	50	1200	2100	3.17	71	79	84	5505	755	3240	3.03
5	Y	400	50	1000	976	1.47	72	80	86	10990	0	6470	0.00
6	Y	400	50	1000	1158	1.75	69	77	84	9325	206	5490	0.83
7	Y	400	50	1000	1361	2.07	66	74	80	7220	412	4250	1.65
8	Y	400	50	1000	1197	1.80	67	75	80	4565	519	2685	2.08
9	Y	400	50	800	500	0.75	67	75	81	8790	0	5170	0.00
10	Y	400	50	800	593	0.90	64	73	79	7460	132	4390	0.53
11	Y	400	50	800	697	1.06	61	69	75	5775	264	3400	1.06
12	Y	400	50	800	613	0.92	62	70	75	3650	332	2150	1.33
13	Y	400	50	600	211	0.32	61	69	75	6590	0	3880	0.00
14	Y	400	50	600	250	0.38	58	66	73	5595	74	3295	0.30
15	Y	400	50	600	294	0.45	55	63	69	4330	148	2550	0.59
16	Y	400	50	600	259	0.39	56	64	69	2740	187	1610	0.75

Wired = Wiring · U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase

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