K3G310-AV52-07

EC centrifugal module

backward curved, single inlet

with support bracket

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**K3G310-AV52-07**
Motor	**M3G112-EA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min^{-1}	2640
Power input	W	1000
Current draw	A	1.75
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}	%	53.9	47.5	51.5
Efficiency grade N		64.4	58	62
Power input P_{ed}	kW	0.99		
Air flow q_v	m^3/h	3130		
Pressure increase p_{fs}	Pa	567		
Speed n	min^{-1}	2645		

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

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Technical features

Mass	14.1 kg
Size	310 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Material of mounting plate	Sheet steel, galvanised
Material of support bracket	Steel, coated in black
Material of inlet nozzle	Sheet steel, galvanised
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Refer to product drawing
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	With plug
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Approval	UL 1004-1

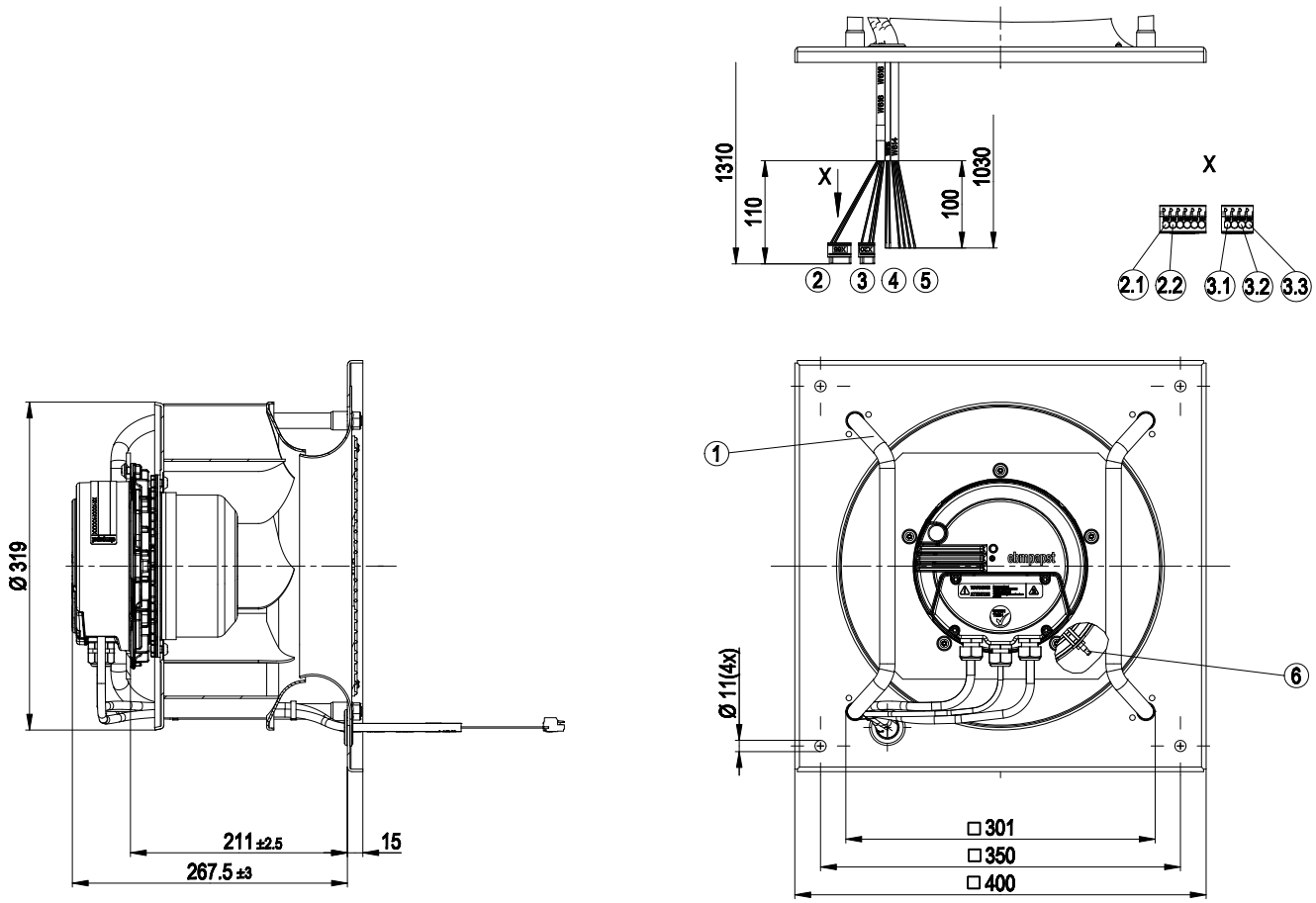
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Product drawing



1	Mounting position: shaft horizontal (install the support struts only vertically as shown in the view!) or rotor on bottom; rotor on top on request
2	Control line with braided copper shielding, WAGO 6-pole multiple connector 2734-0106
2.1	White (out)
2.2	green (GND)
3	Control line with braided copper shielding, WAGO 4-pole multiple connector 2734-0104
3.1	yellow (0 - 10V/PWM)
3.2	GND (grey)
3.3	(+10 V) brown
4	Connection line PVC AWG22, 2 x brass lead tips crimped
5	Connection line silicone 4G 1.5mm², 4x crimped core-end sleeves
6	Inlet nozzle with pressure tap (k-factor: 108)

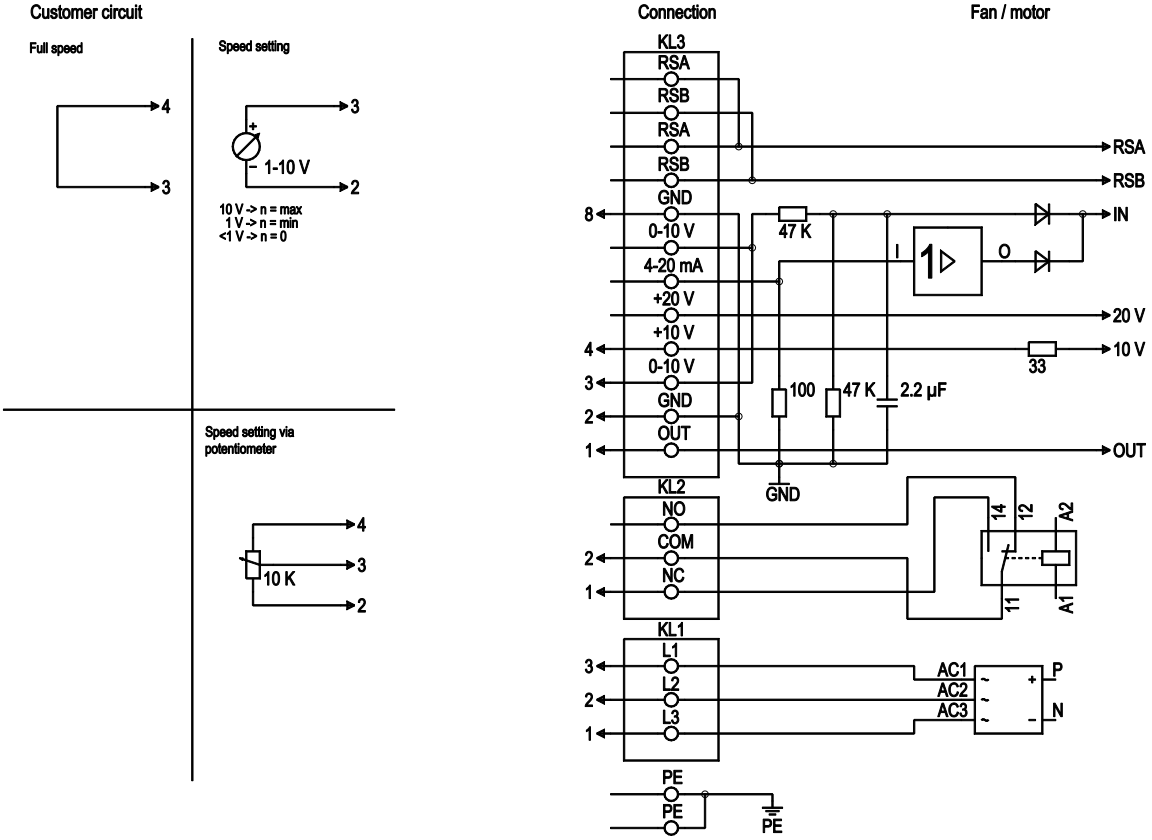
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Connection screen



No.	Pin	Signal	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, break for failure; 2 A, max. 250 VAC, min. 10 mA, AC1
KL3	1	OUT	Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the actual motor control factor (output voltage of electronics): 1 V corresponds to 10% level control coefficient, 10 V correspond to 100% level control coefficient.
KL3	2, 8	GND	Signal ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / actual value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3%), max. 10 mA, supply voltage for external devices (e.g. potentiometer), SELV

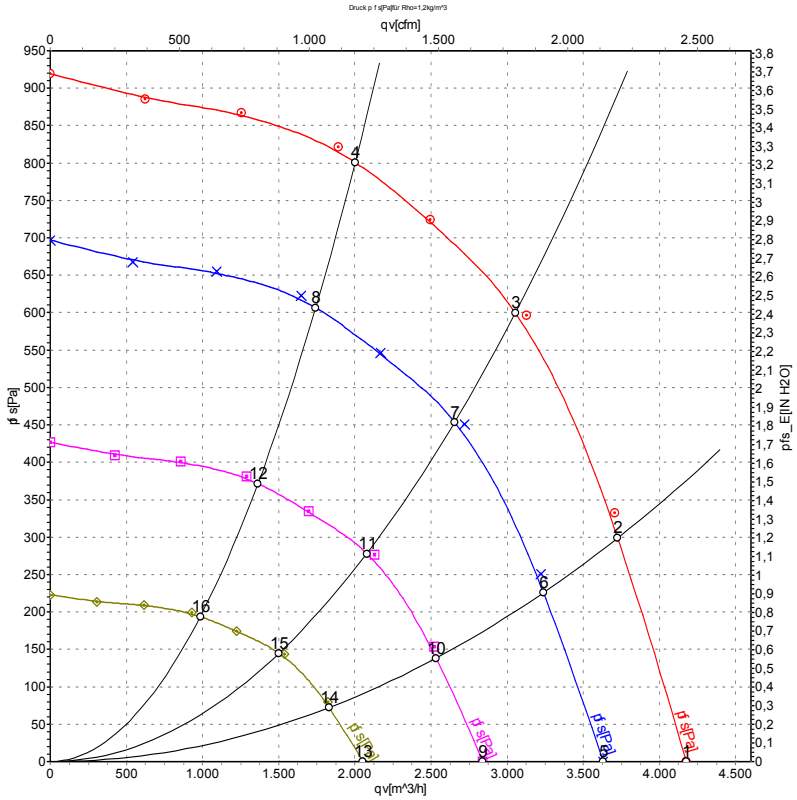
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Charts: Air flow 50 Hz



Measurement: LU-101286

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa
1	400	50	2645	731	1.30	79	86	91	4175	0
2	400	50	2645	871	1.50	74	82	87	3725	320
3	400	50	2640	1000	1.75	71	79	85	3055	600
4	400	50	2640	875	1.53	73	81	85	2000	800
5	400	50	2300	480	0.85	76	83	88	3630	0
6	400	50	2300	571	0.99	71	79	84	3235	242
7	400	50	2300	651	1.13	68	76	82	2655	462
8	400	50	2300	577	1.01	70	78	82	1740	609
9	400	50	1800	230	0.41	70	78	82	2840	0
10	400	50	1800	274	0.47	66	73	79	2535	148
11	400	50	1800	312	0.54	63	71	76	2080	283
12	400	50	1800	277	0.48	64	72	77	1365	373
13	400	50	1300	87	0.15	63	71	75	2050	0
14	400	50	1300	103	0.18	59	66	72	1830	77
15	400	50	1300	118	0.20	56	63	69	1500	148
16	400	50	1300	104	0.18	57	65	70	985	194

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
qv = Air flow · p_{fs} = Pressure increase

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