K3G280-AK54-01

EC centrifugal module - AHU

backward-curved, single-intake

with support plate

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**K3G280-AK54-01**
Motor	**M3G112-EA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	3400
Power consumption	W	1030
Current draw	A	1.8
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	52.8	51.6
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		63.2	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	1.02
09 Air flow q_v	m^3/h	1790
09 Pressure increase p_{fs}	Pa	1003
10 Speed (rpm) n	min^{-1}	3420
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-114283

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Technical description

Weight	13.6 kg
Fan size	280 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Spacer material	Aluminum
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	CCC

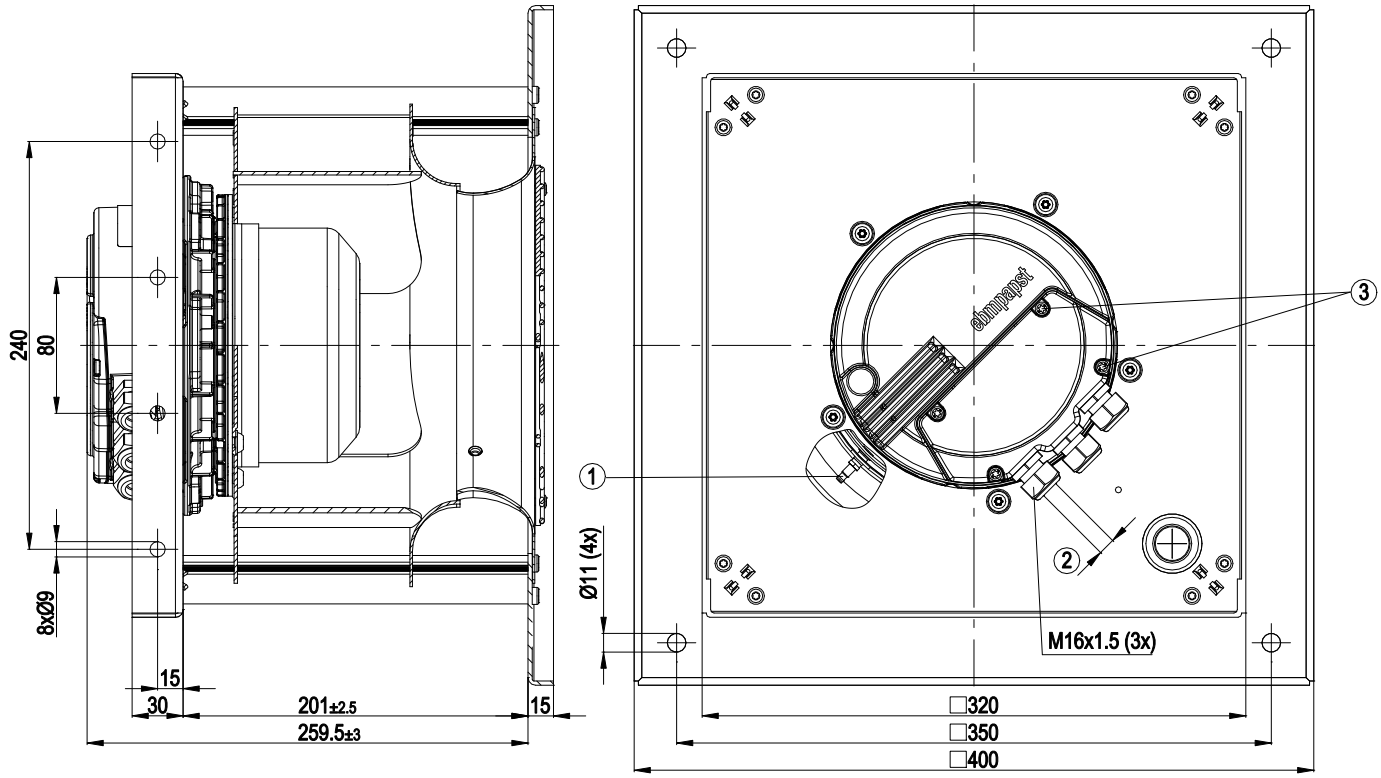
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Product drawing



1	Inlet ring with pressure tap (k-factor: 88)
2	Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5±0.4 Nm
3	Tightening torque 3.5 ± 0.5 Nm

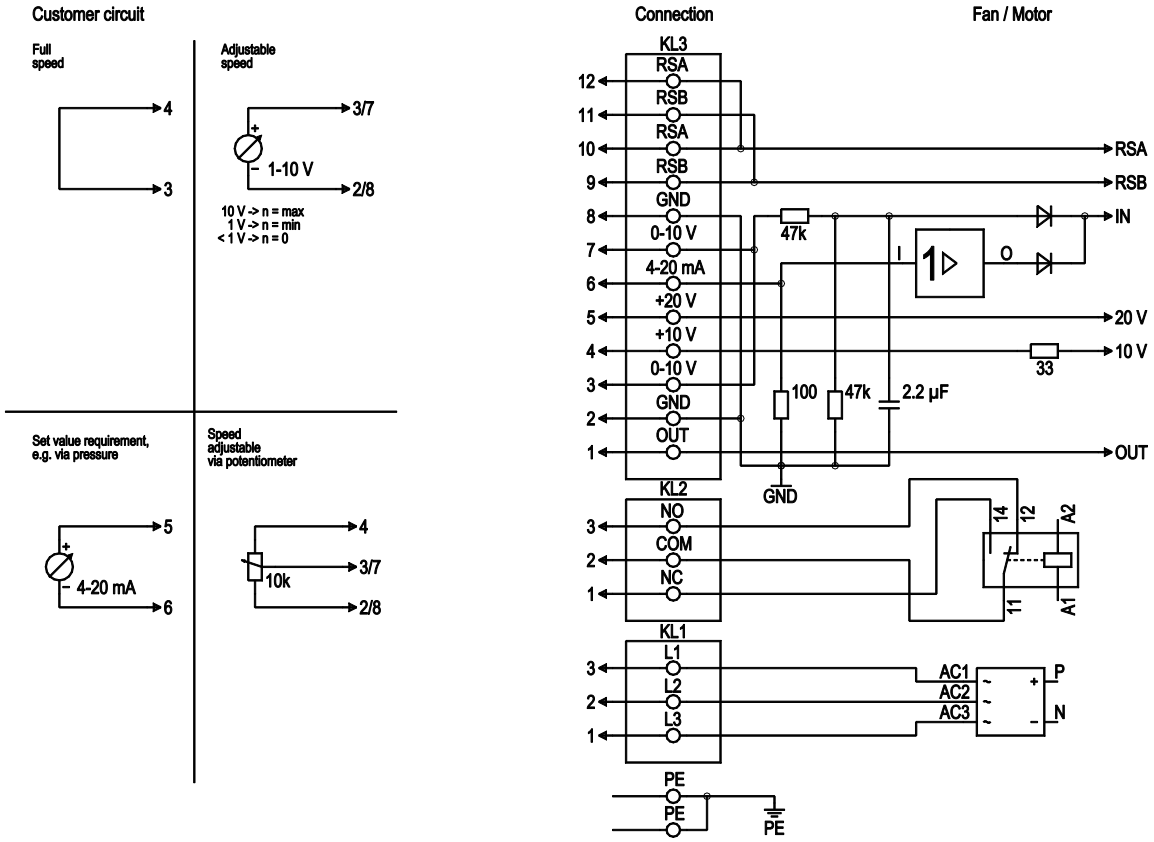
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Connection diagram



No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBUS, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBUS, RSA, SELV

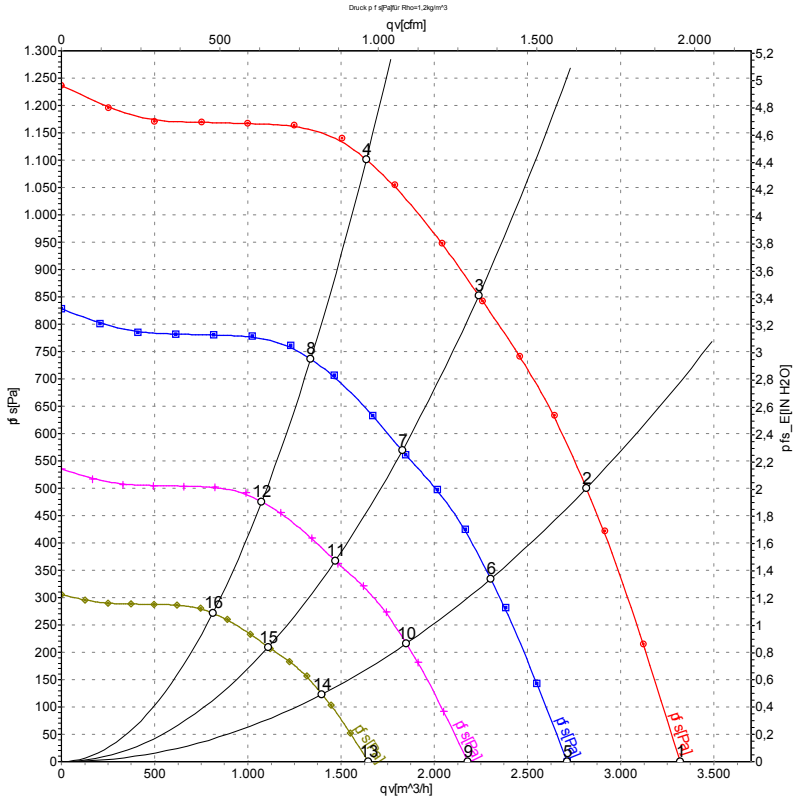
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Curves: Air performance 50 Hz



Measurement: LU-114283-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	400	50	3400	817	1.44	84	91	3320	0	1955	0.00
2	400	50	3400	997	1.72	80	88	2815	500	1655	2.01
3	400	50	3400	1030	1.80	78	86	2240	850	1320	3.41
4	400	50	3400	980	1.69	77	84	1635	1100	960	4.42
5	400	50	2800	446	0.79	80	87	2715	0	1595	0.00
6	400	50	2800	545	0.94	76	83	2305	335	1355	1.34
7	400	50	2800	575	0.95	74	81	1830	568	1075	2.28
8	400	50	2800	547	0.93	72	80	1335	736	785	2.95
9	400	50	2250	232	0.41	75	82	2180	0	1285	0.00
10	400	50	2250	283	0.49	71	79	1850	216	1090	0.87
11	400	50	2250	298	0.49	69	77	1470	367	865	1.47
12	400	50	2250	284	0.48	67	75	1075	475	635	1.91
13	400	50	1700	100	0.18	69	76	1645	0	970	0.00
14	400	50	1700	122	0.21	65	72	1400	123	825	0.49
15	400	50	1700	129	0.21	63	70	1110	209	655	0.84
16	400	50	1700	122	0.21	61	69	810	271	480	1.09

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
qv = Air flow · p_{fs} = Pressure increase

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