R3G400-AY87-01

EC centrifugal fan - RadiPac

backward curved



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Nominal data

Type	**R3G400-AY87-01**
Motor	**M3G112-IA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min^{-1}	2180
Power input	W	1850
Current draw	A	2.9
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data in accordance with ecodesign regulation EU 327/2011 (EN 17166)

		Actual	Request 2015
01 Overall efficiency η_{es}	%	65.3	54.1
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		73.2	62
05 Variable speed drive		Yes	

09 Power input P_{ed}	kW	1.78
09 Air flow q_v	m^3/h	5490
09 Pressure increase p_{fs}	Pa	712
10 Speed (rpm) n	min^{-1}	2160
11 Specific ratio*		1.01

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-122009

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Technical features

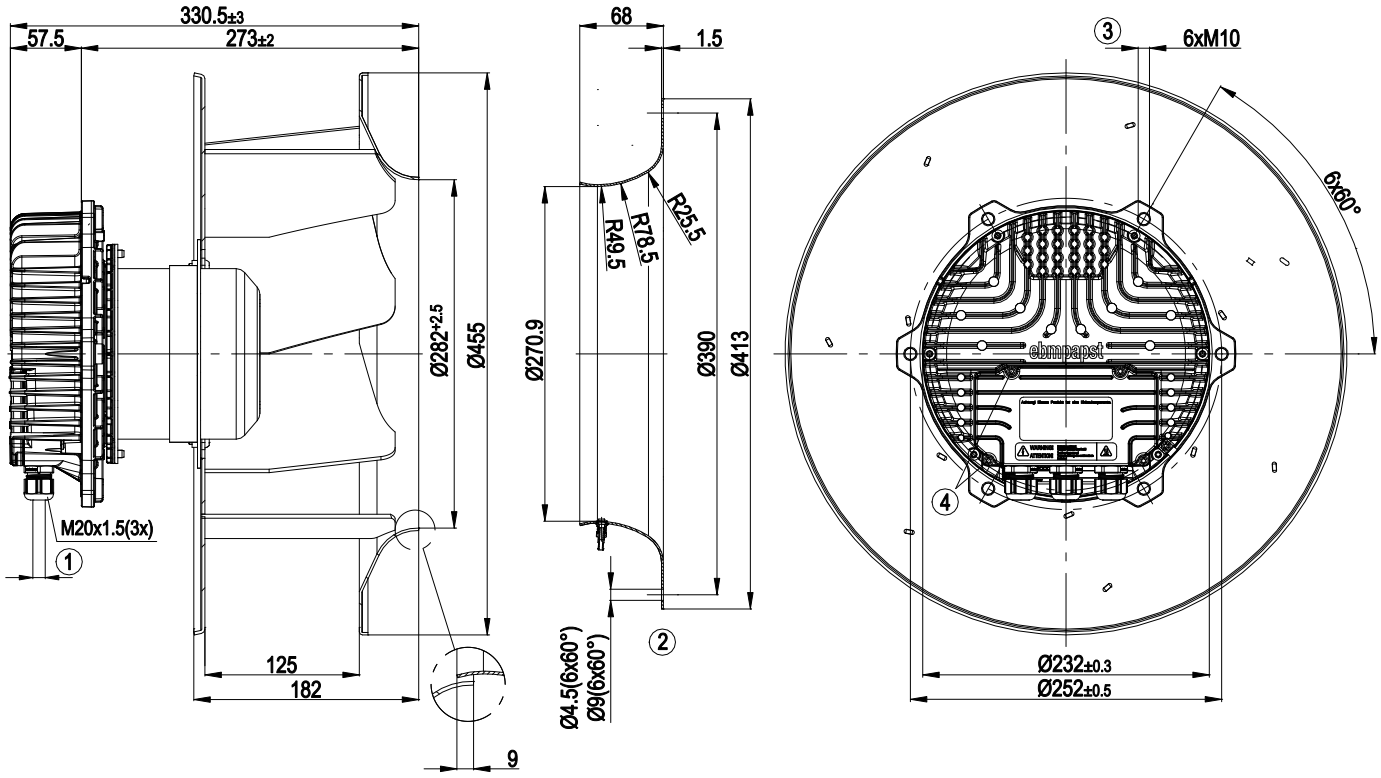
Mass	15 kg
Size	400 mm
Motor size	112
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP54
Insulation class	"B"
Humidity (F) / environmental protection class (H)	H1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2
EMC interference emission	Acc. to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used devices with a total rated power greater than 1 kW
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical connection	Terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC; UL 1004-7 + 60730-1

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Product drawing



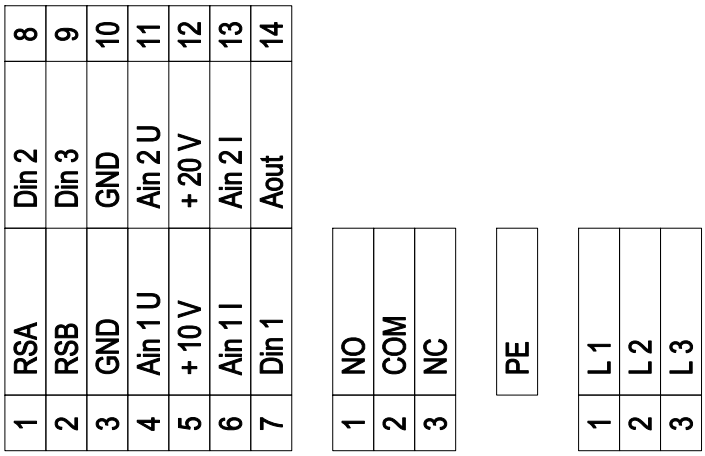
1	Cable diameter: min. 4 mm, max. 10 mm; tightening torque: 4±0.6 Nm
2	Accessory part: inlet nozzle 40075-2-4013 with a pressure tap not included in the standard scope of delivery; other inlet nozzles on request
3	Depth of screw 12 - 16 mm
4	Tightening torque 3.5±0.5 Nm

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Connection screen



No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; close with error
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break with error
KL 3	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Signal ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain1; SELV
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer), SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: parameter set switch 1/2, according to EEPROM setting, the valid/used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: open pin or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: controller function of integrated controller, according to EEPROM setting, the controller function of the integrated controller is normally/inversely selectable per bus or per digital input normal: open pin or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof, power supply for external devices (e.g. sensors); SELV

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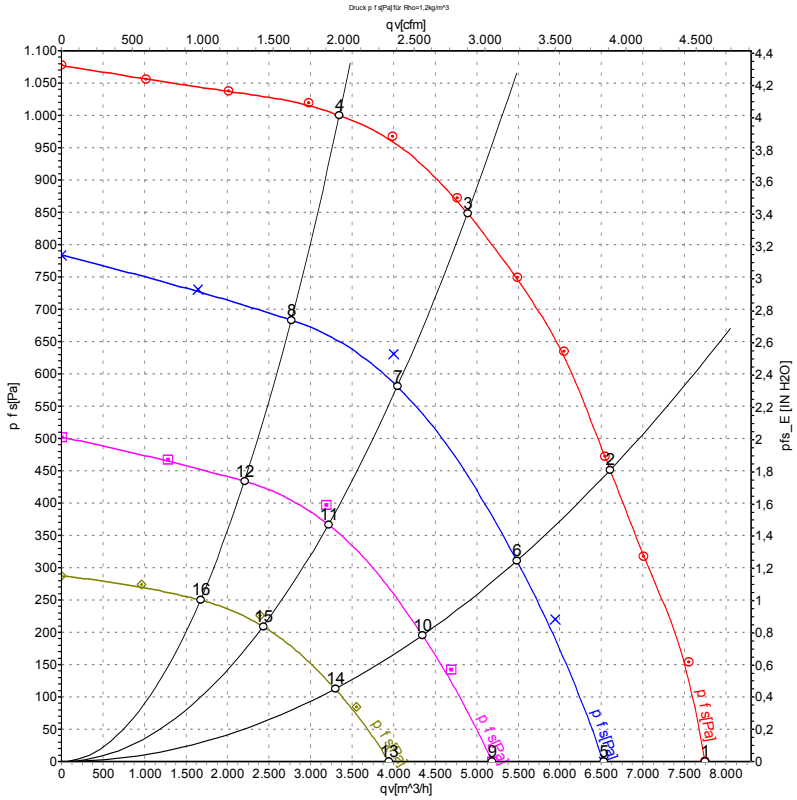
No.	Conn.	Designation	Function / assignment
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV

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Charts: Air flow 50 Hz



Measurement: LU-122009-1
Measurement: LU-122096-1
Measurement: LU-122097-1
Measurement: LU-122098-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	400	50	2180	1162	1.76	82	89	95	7745	0	4560	0.00
2	400	50	2180	1562	2.37	76	84	89	6605	450	3890	1.81
3	400	50	2180	1850	2.90	74	81	87	4890	850	2880	3.41
4	400	50	2180	1694	2.56	76	84	90	3345	1000	1970	4.01
5	400	50	1810	672	1.04	77	85	90	6525	0	3840	0.00
6	400	50	1810	877	1.34	72	80	85	5480	318	3225	1.28
7	400	50	1810	1040	1.59	71	78	84	4045	622	2380	2.50
8	400	50	1810	905	1.38	72	79	85	2765	683	1630	2.74
9	400	50	1440	346	0.59	71	79	84	5185	0	3050	0.00
10	400	50	1440	447	0.75	68	74	80	4345	200	2560	0.80
11	400	50	1440	475	0.85	66	73	78	3215	393	1890	1.58
12	400	50	1440	430	0.74	67	74	79	2205	434	1295	1.74
13	400	50	1090	172	0.38	64	73	80	3940	0	2320	0.00
14	400	50	1090	204	0.42	61	69	74	3295	116	1940	0.47
15	400	50	1090	228	0.47	61	67	72	2425	222	1430	0.89
16	400	50	1090	204	0.43	61	67	73	1675	250	985	1.00

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
q_V = Air flow · p_{fs} = Pressure increase

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