**R3G250-AY11-C1**

# EC centrifugal fan - RadiPac

backward-curved

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ErP2015 EXCEEDS THE NORM

## Nominal data

| | |
|---|---|
| **Type** | **R3G250-AY11-C1** |
| **Motor** | **M3G084-GF** |

| | | |
|---|---|---|
| Phase | | 3~ |
| Nominal voltage | VAC | 400 |
| Nominal voltage range | VAC | 380 .. 480 |
| Frequency | Hz | 50/60 |
| Method of obtaining data | | ml |
| Speed (rpm) | $min^{-1}$ | 3580 |
| Power consumption | W | 820 |
| Current draw | A | 1.35 |
| Min. ambient temperature | °C | -25 |
| Max. ambient temperature | °C | 60 |

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

## Data according to ErP Directive

| | | Actual | Req. 2015 |
|---|---|---|---|
| 01 Overall efficiency $\eta_{es}$ | % | 62.1 | 50.2 |
| 02 Measurement category | | A | |
| 03 Efficiency category | | Static | |
| 04 Efficiency grade N | | 73.9 | 62 |
| 05 Variable speed drive | | Yes | |

| | | |
|---|---|---|
| 09 Power consumption $P_{ed}$ | kW | 0.75 |
| 09 Air flow $q_v$ | $m^3/h$ | 1465 |
| 09 Pressure increase $p_{fs}$ | Pa | 1051 |
| 10 Speed (rpm) n | $min^{-1}$ | 3610 |
| 11 Specific ratio* | | 1.01 |

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + $p_{fs}$ / 100 000 Pa

LU-131307

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## Technical description

| | |
|---|---|
| **Weight** | 6.4 kg |
| **Fan size** | 250 mm |
| **Rotor surface** | Painted black |
| **Electronics housing material** | Die-cast aluminum |
| **Impeller material** | Sheet aluminum |
| **Number of blades** | 7 |
| **Direction of rotation** | Clockwise, viewed toward rotor |
| **Degree of protection** | IP54 |
| **Insulation class** | "B" |
| **Moisture (F) / Environmental (H) protection class** | F3-1 |
| **Max. permitted ambient temp. for motor (transport/storage)** | +80 °C |
| **Min. permitted ambient temp. for motor (transport/storage)** | -40 °C |
| **Installation position** | Shaft horizontal or rotor on bottom; rotor on top on request |
| **Condensation drainage holes** | On rotor side |
| **Mode** | S1 |
| **Motor bearing** | Ball bearing |
| **Technical features** | - Output 10 VDC, max. 10 mA<br>- Output 20 VDC, max. 50 mA<br>- Output for slave 0-10 V<br>- Input for sensor 0-10 V or 4-20 mA<br>- External 24 V input (parameter setting)<br>- Alarm relay<br>- Integrated PID controller<br>- Motor current limitation<br>- PFC, passive<br>- RS-485 MODBUS-RTU<br>- Soft start<br>- Control input 0-10 VDC / PWM<br>- Control interface with SELV potential safely disconnected from supply<br>- Thermal overload protection for electronics/motor<br>- Line undervoltage / phase failure detection |
| **Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)** | <= 3.5 mA |
| **Electrical hookup** | Via terminal box |
| **Motor protection** | Thermal overload protector (TOP) internally connected |
| **Protection class** | I (if protective earth is connected by customer to the housing's connection point) |
| **Conformity with standards** | EN 61800-5-1; CE |
| **Approval** | CCC; EAC; UL 1004-7 + 60730; C22.2 No.77 + CAN/CSA-E60730-1 |

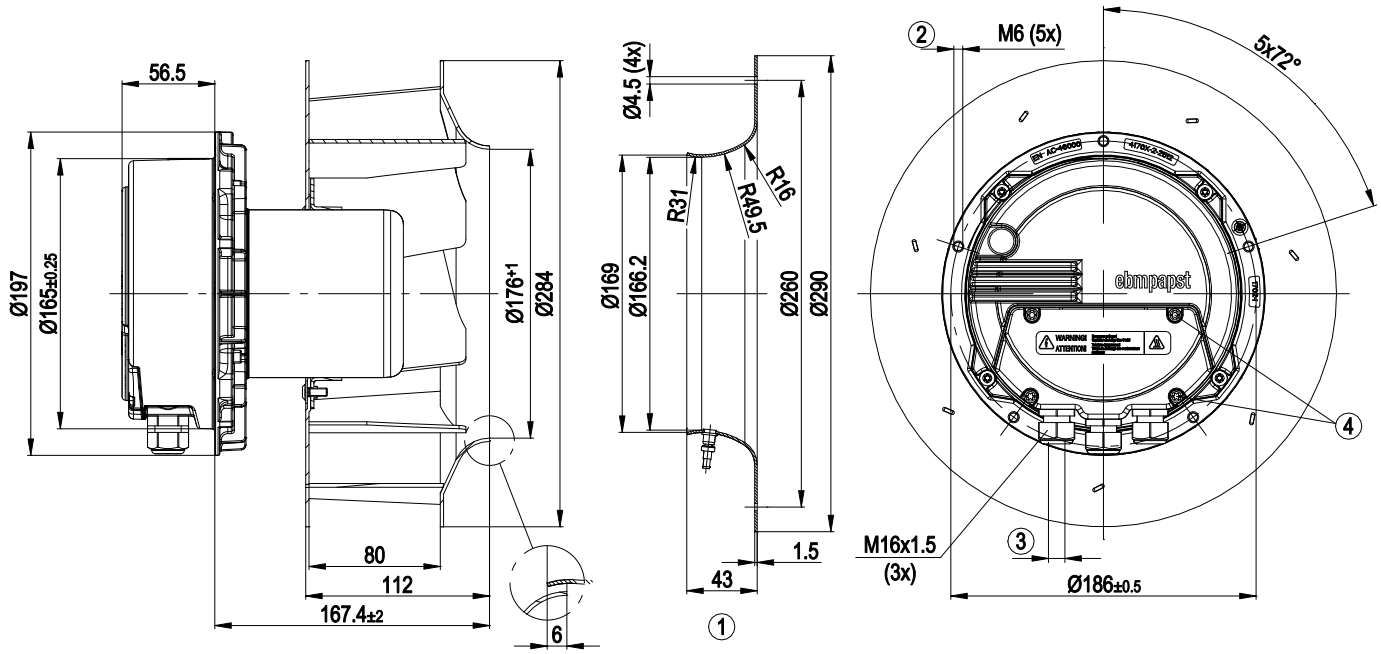


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## Product drawing




| | |
|---|---|
| 1 | Accessory part: inlet ring 25075-2-4013 with pressure tap (k-factor: 70) not included in scope of delivery |
| 2 | Max. clearance for screw 16 mm |
| 3 | Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5±0.4 Nm |
| 4 | Tightening torque 3.5 ± 0.5 Nm |

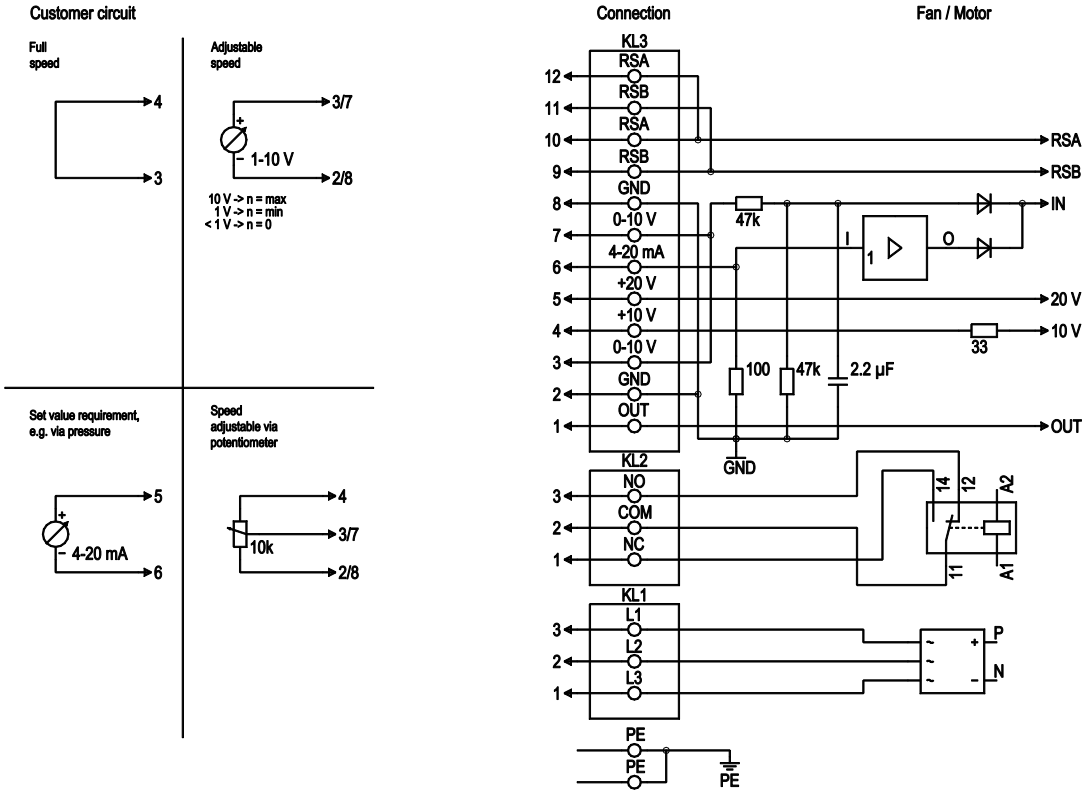


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## Connection diagram




| No. | Conn. | Designation | Function/assignment |
|---|---|---|---|
| PE | | PE | Protective earth terminal |
| KL1 | 1, 2, 3 | L1, L2, L3 | Power supply, voltage range (see nameplate), 50/60 Hz |
| KL2 | 1 | NC | Floating status contact, break for failure |
| KL2 | 2 | COM | floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1) |
| KL2 | 3 | NO | Floating status contact, make for failure |
| KL3 | 1 | OUT | Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level. |
| KL3 | 2, 8 | GND | Reference ground for control interface, SELV |
| KL3 | 3, 7 | 0-10 V | Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV |
| KL3 | 4 | +10 V | Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV |
| KL3 | 5 | +20 V | Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV |
| KL3 | 6 | 4-20 mA | Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV |
| KL3 | 9, 11 | RSB | RS485 interface for MODBUS, RSB |
| KL3 | 10, 12 | RSA | RS485 interface for MODBUS, RSA |

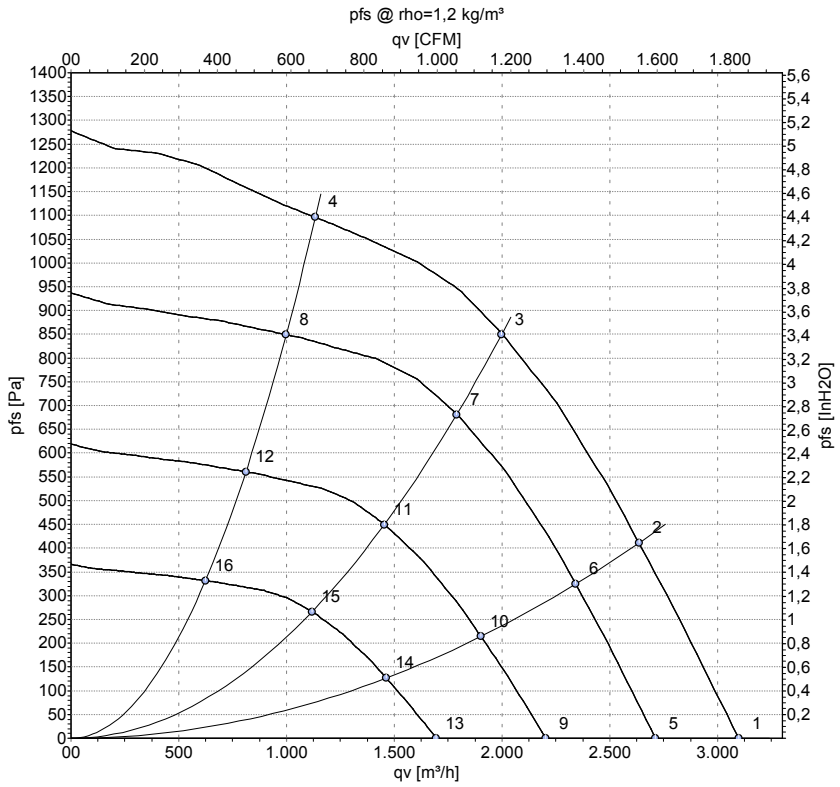


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## Curves: Air performance 50 Hz




Measurement: LU-154881-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

## Measured values

| | U | f | n | $P_{ed}$ | I | $LwA_{in}$ | qv | $p_{fs}$ | qv | $p_{fs}$ |
|---|---|---|---|---|---|---|---|---|---|---|
| | V | Hz | $min^{-1}$ | W | A | dB(A) | $m^3/h$ | Pa | CFM | inH2O |
| 1 | 400 | 50 | 3655 | 642 | 1.25 | 87 | 3095 | 0 | 1820 | 0.00 |
| 2 | 400 | 50 | 3605 | 735 | 1.32 | 84 | 2635 | 410 | 1550 | 1.65 |
| 3 | 400 | 50 | 3580 | 820 | 1.35 | 80 | 2000 | 850 | 1175 | 3.41 |
| 4 | 400 | 50 | 3635 | 709 | 1.32 | 88 | 1135 | 1100 | 665 | 4.42 |
| 5 | 400 | 50 | 3200 | 431 | 0.84 | | 2710 | 0 | 1595 | 0.00 |
| 6 | 400 | 50 | 3200 | 515 | 0.98 | | 2340 | 324 | 1375 | 1.30 |
| 7 | 400 | 50 | 3200 | 567 | 1.08 | | 1790 | 683 | 1050 | 2.74 |
| 8 | 400 | 50 | 3200 | 484 | 0.94 | | 1000 | 849 | 585 | 3.41 |
| 9 | 400 | 50 | 2600 | 231 | 0.45 | | 2205 | 0 | 1295 | 0.00 |
| 10 | 400 | 50 | 2600 | 276 | 0.53 | | 1900 | 214 | 1120 | 0.86 |
| 11 | 400 | 50 | 2600 | 304 | 0.58 | | 1455 | 451 | 855 | 1.81 |
| 12 | 400 | 50 | 2600 | 259 | 0.50 | | 810 | 561 | 475 | 2.25 |
| 13 | 400 | 50 | 2000 | 105 | 0.20 | | 1695 | 0 | 995 | 0.00 |
| 14 | 400 | 50 | 2000 | 126 | 0.24 | | 1465 | 127 | 860 | 0.51 |
| 15 | 400 | 50 | 2000 | 138 | 0.26 | | 1115 | 267 | 655 | 1.07 |
| 16 | 400 | 50 | 2000 | 118 | 0.23 | | 625 | 332 | 365 | 1.33 |

U = Power supply · f = Frequency · n = Speed (rpm) · $P_{ed}$ = Power consumption · I = Current draw · $LwA_{in}$ = Sound power level intake side · qv = Air flow · $p_{fs}$ = Pressure increase



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