R3G500-AF34-05

EC centrifugal fan

backward curved, single inlet

ebm-papst Mulfingen GmbH & Co. KG
Bachmühle 2 · D-74673 Mulfingen
Phone +49 7938 81-0
Fax +49 7938 81-110
info1@de.ebmpapst.com
www.ebmpapst.com

Limited partnership · Headquarters Mulfingen
County court Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen
County court Stuttgart · HRB 590142

ErP2015 EXCEEDS THE NORM

Nominal data

Type	**R3G500-AF34-05**
Motor	**M3G112-GA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed	min^{-1}	1160
Power input	W	810
Current draw	A	1.55
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.00

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}		61.7	46.4	50.4
Efficiency grade N		73.3	58	62
Power input P_{ed}	kW	0.79		
Air flow q_v	m^3/h	5405		
Pressure increase p_{fs}	Pa	300		
Speed n	min^{-1}	1160		

Data established at point of optimum efficiency.

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Technical features

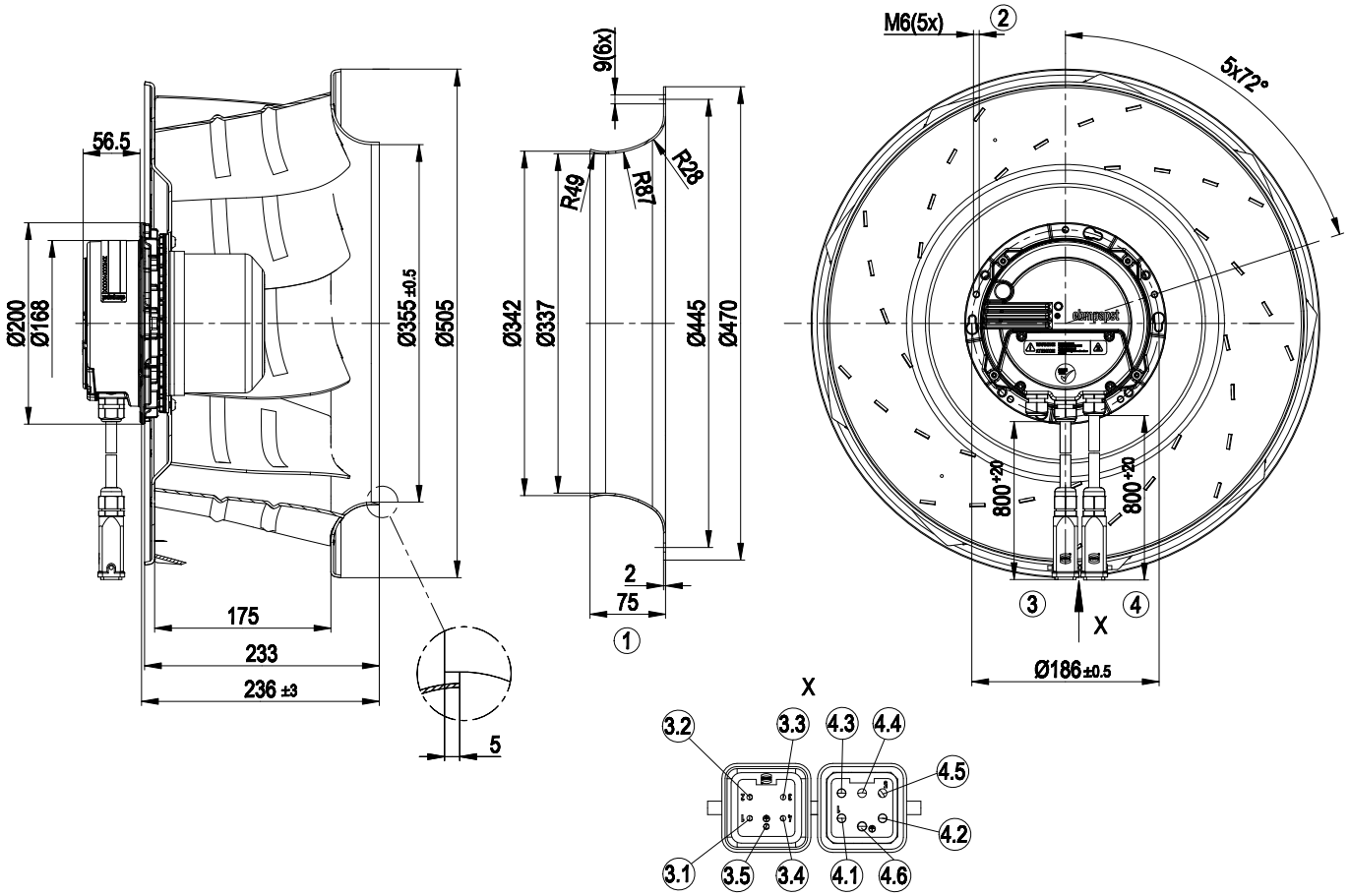
Mass	13.3 kg
Size	500 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Number of blades	9
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC harmonics	Acc. to EN 61000-3-2/3
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Thermal overload protector (TOP) wired internally
Cable exit	Variable
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE

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Product drawing



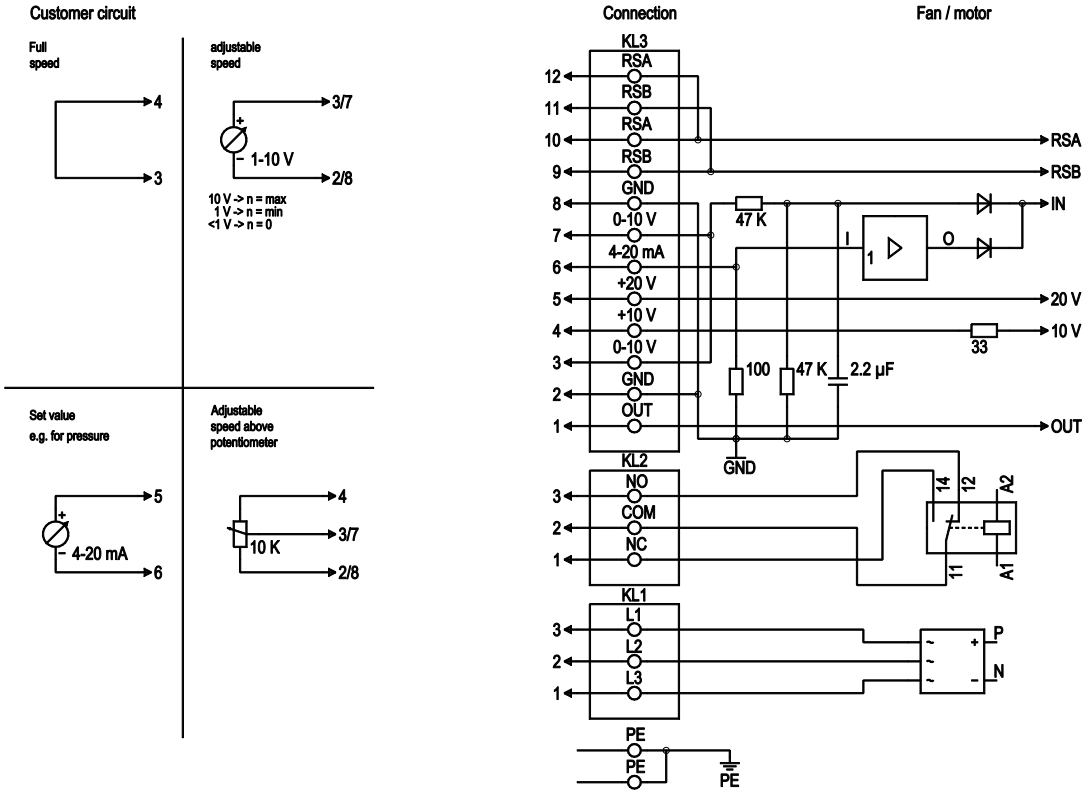
1	Accessory part: Inlet nozzle 63072-2-4013, not included in the standard scope of delivery
2	Depth of screw max. 16 mm
3	Control cable with Harting connector shell 09 20 003 0420 and Harting pin insert 09 20 004 2611
3.1	NC (black1)
3.2	COM (black2)
3.3	GND (black3)
3.4	0-10V (black4)
3.5	PE (not assigned)
4	Motor cable with Harting connector shell 09 20 003 0420 and Harting pin insert 09 12 005 3001
4.1	L1 (black1)
4.2	L2 (black2)
4.3	L3 (black2)
4.4	Not assigned
4.5	Not assigned
4.6	PE (green/yellow)

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Connection screen



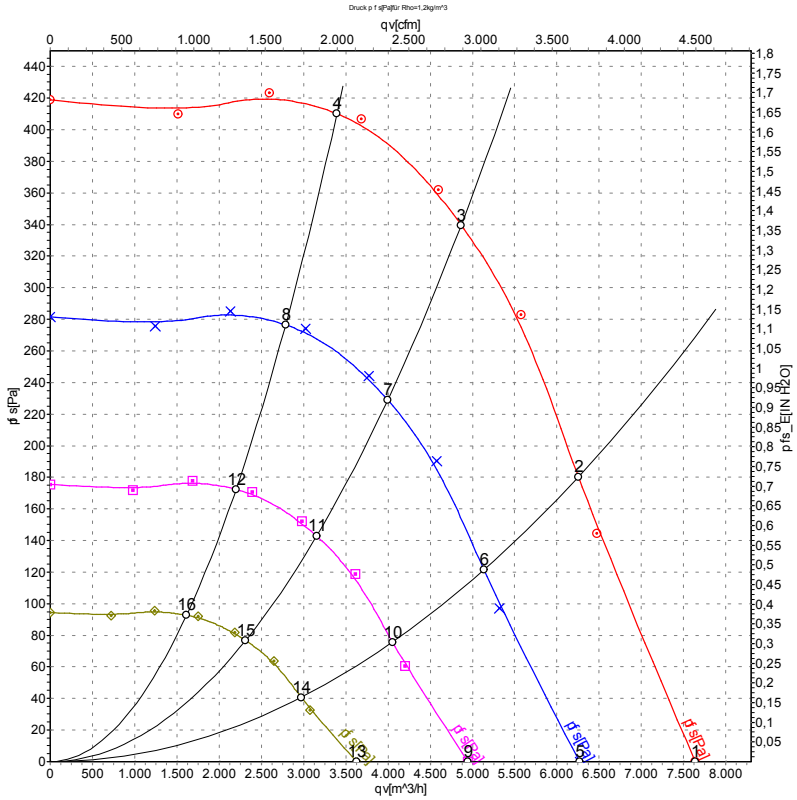
No.	Pin	Signal	Function / assignment
PE		PE	Protective earth connection
KL1	1, 2, 3	L1, L2, L3	Supply voltage, voltage range (see type plate), 50/60 Hz
KL2	1	NC	Floating status contact, break with error
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, close with error
KL3	1	OUT	Analogue output, 0-10 VDC, max. 3 mA, SELV, Output of the actual motor duty cycle (PWM): 1 V corresponds to 10% PWM, 10 V correspond to 100% PWM.
KL3	2, 8	GND	Signal ground for control interface, SELV
KL3	3, 7	0-10 V	Set value / actual sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (+/-3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, supply voltage for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Set value / actual sensor value input 4-20 mA, impedance 100 Ω, only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

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Charts: Air flow 50 Hz



Measurement: LU-105321

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa
1	400	50	1160	563	0.96	76	83	86	7640	0
2	400	50	1160	721	1.22	69	76	80	6255	180
3	400	50	1160	810	1.55	64	71	77	4865	340
4	400	50	1160	726	1.22	64	72	77	3395	410
5	400	50	950	311	0.53	72	79	81	6265	0
6	400	50	950	399	0.67	65	72	76	5135	120
7	400	50	950	445	0.73	60	67	73	3995	229
8	400	50	950	402	0.68	60	67	73	2785	277
9	400	50	750	153	0.26	67	74	76	4945	0
10	400	50	750	196	0.33	60	67	71	4055	75
11	400	50	750	219	0.36	55	62	68	3155	143
12	400	50	750	198	0.33	55	62	68	2200	173
13	400	50	550	60	0.10	60	67	69	3630	0
14	400	50	550	77	0.13	53	60	64	2975	40
15	400	50	550	86	0.14	48	55	61	2315	77
16	400	50	550	78	0.13	48	55	61	1615	93

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
qv = Air flow · p_{fs} = Pressure increase

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