K3G450-PA23-B1

EC centrifugal module - RadiPac

backward curved, single inlet

with support bracket

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Nominal data

Type	**K3G450-PA23-B1**
Motor	**M3G150-FF**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min^{-1}	2140
Power input	W	2900
Current draw	A	4.5
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

		Actual	Request 2015
01 Overall efficiency η_{es}	%	70.1	56.3
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		75.8	62
05 Variable speed drive		Yes	

09 Power input P_{ed}	kW	2.89
09 Air flow q_v	m^3/h	6655
09 Pressure increase p_{fs}	Pa	1050
10 Speed (rpm) n	min^{-1}	2155
11 Specific ratio*		1.01

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-175860

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Technical features

Mass	37 kg
Size	450 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of impeller	Aluminium sheet, coated in black
Material of mounting plate	Sheet steel, galvanised and coated in black
Material of support bracket	Steel, galvanised and coated in black
Material of inlet nozzle	Sheet steel, galvanised and coated in black
Number of blades	5
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 55
Insulation class	"F"
Humidity (F)/environmental protection class (H)	H2+
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Refer to product drawing
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Operation and alarm display - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used devices with a total rated power greater than 1 kW
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	EAC

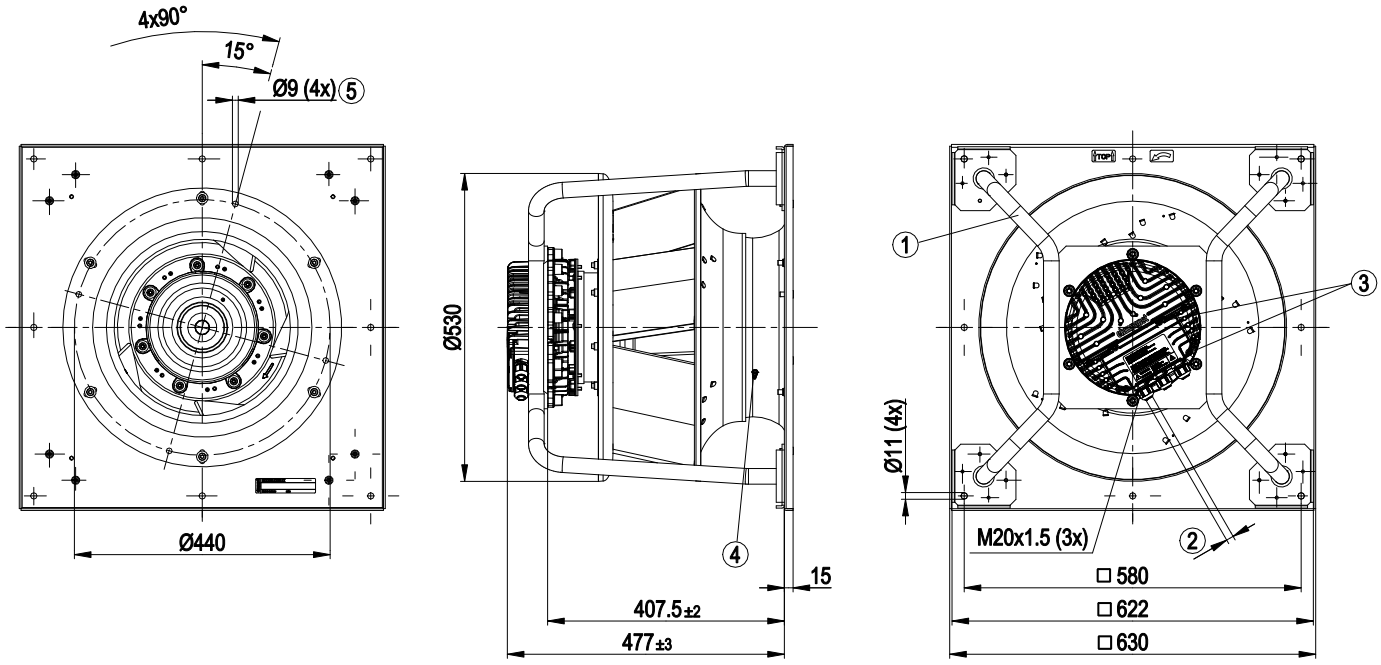
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Product drawing



1	Installation position: Shaft horizontal (install the support struts only vertically as shown in the illustration!) or rotor on bottom; rotor on top on request
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4±0.6 Nm
3	Tightening torque 3.5±0.5 Nm
4	Inlet nozzle with pressure tap (k-factor: 240)
5	Mounting holes for FlowGrid

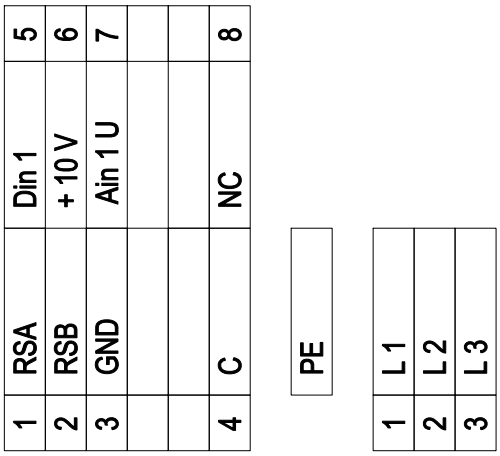
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Connection screen



No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3~380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 2	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 2	3	GND	Signal ground for control interface; SELV
KL2	4	C	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / 2 A (AC1)
KL 2	5	Din1	Digital input 1 enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 V; SELV
KL 2	6	+ 10 V	Fixed voltage output 10 VDC; +10 V -3 %, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer); SELV Alternative: +24 VDC input for parametrisation via MODBUS without mains power
KL 2	7	Ain1 U	Analogue input 1 (set value) 0-10 V, Ri=100 kΩ, parametrisable curve; SELV
KL2	8	NC	Status relay, floating status contact; break for failure

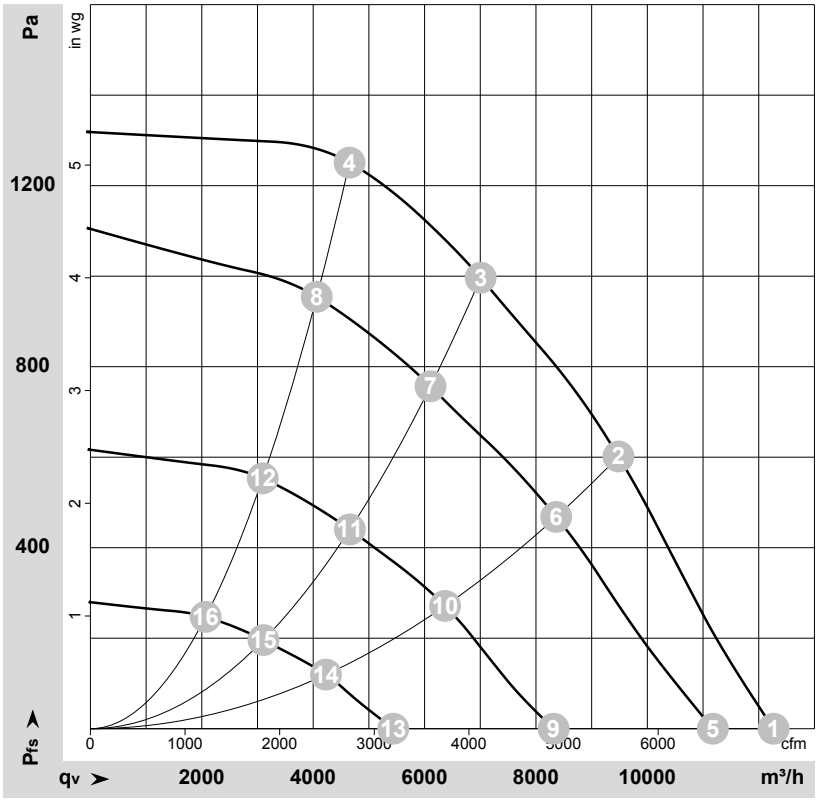
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Charts: Air flow 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-175860-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	inH2O
1	400	50	2140	1709	2.69	89	96	95	12265	0	7220	0.00
2	400	50	2140	2655	4.09	78	85	88	9480	600	5580	2.41
3	400	50	2140	2900	4.50	74	81	87	7010	1000	4125	4.01
4	400	50	2140	2763	4.25	79	86	90	4655	1250	2740	5.02
5	400	50	1960	1302	2.11	86	93	93	11175	0	6580	0.00
6	400	50	1890	1825	2.87	74	82	85	8365	469	4925	1.88
7	400	50	1875	1938	3.03	71	78	83	6105	757	3595	3.04
8	400	50	1885	1851	2.90	75	82	87	4065	954	2390	3.83
9	400	50	1470	580	1.14	79	87	87	8315	0	4895	0.00
10	400	50	1435	827	1.45	68	75	79	6370	272	3750	1.09
11	400	50	1430	879	1.52	65	72	77	4660	440	2740	1.77
12	400	50	1435	840	1.47	68	75	80	3095	553	1820	2.22
13	400	50	980	208	0.57	66	75	76	5440	0	3200	0.00
14	400	50	960	277	0.69	57	65	69	4230	121	2490	0.49
15	400	50	955	295	0.72	56	63	68	3110	196	1830	0.79
16	400	50	960	283	0.70	58	65	70	2070	247	1215	0.99

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
q_V = Air flow · p_{fs} = Pressure increase

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