K3G355-AI56-02

EC centrifugal module

backward-curved, single-intake

with support bracket

ebm-papst Mulfingen GmbH & Co. KG
Bachmühle 2 · D-74673 Mulfingen
Phone +49 7938 81-0
Fax +49 7938 81-110
info1@de.ebmpapst.com
www.ebmpapst.com

Limited partnership · Headquarters Mulfingen
Amtsgericht (court of registration) Stuttgart · HRA 590344

General partner Elektrobau Mulfingen GmbH · Headquarters Mulfingen
Amtsgericht (court of registration) Stuttgart · HRB 590142

ErP2015 EXCEEDS THE NORM

Nominal data

Type	**K3G355-AI56-02**
Motor	**M3G112-EA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	2200
Power consumption	W	950
Current draw	A	1.75
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to ErP Directive

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	59.9	51
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		70.9	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	0.9
09 Air flow q_v	m^3/h	2805
09 Pressure increase p_{fs}	Pa	642
10 Speed (rpm) n	min^{-1}	2220
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-78488

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Technical description

Weight	16.3 kg
Fan size	355 mm
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Support bracket material	Steel, galvanized and painted black
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	F4-1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, passive - RS-485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Via terminal box
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC

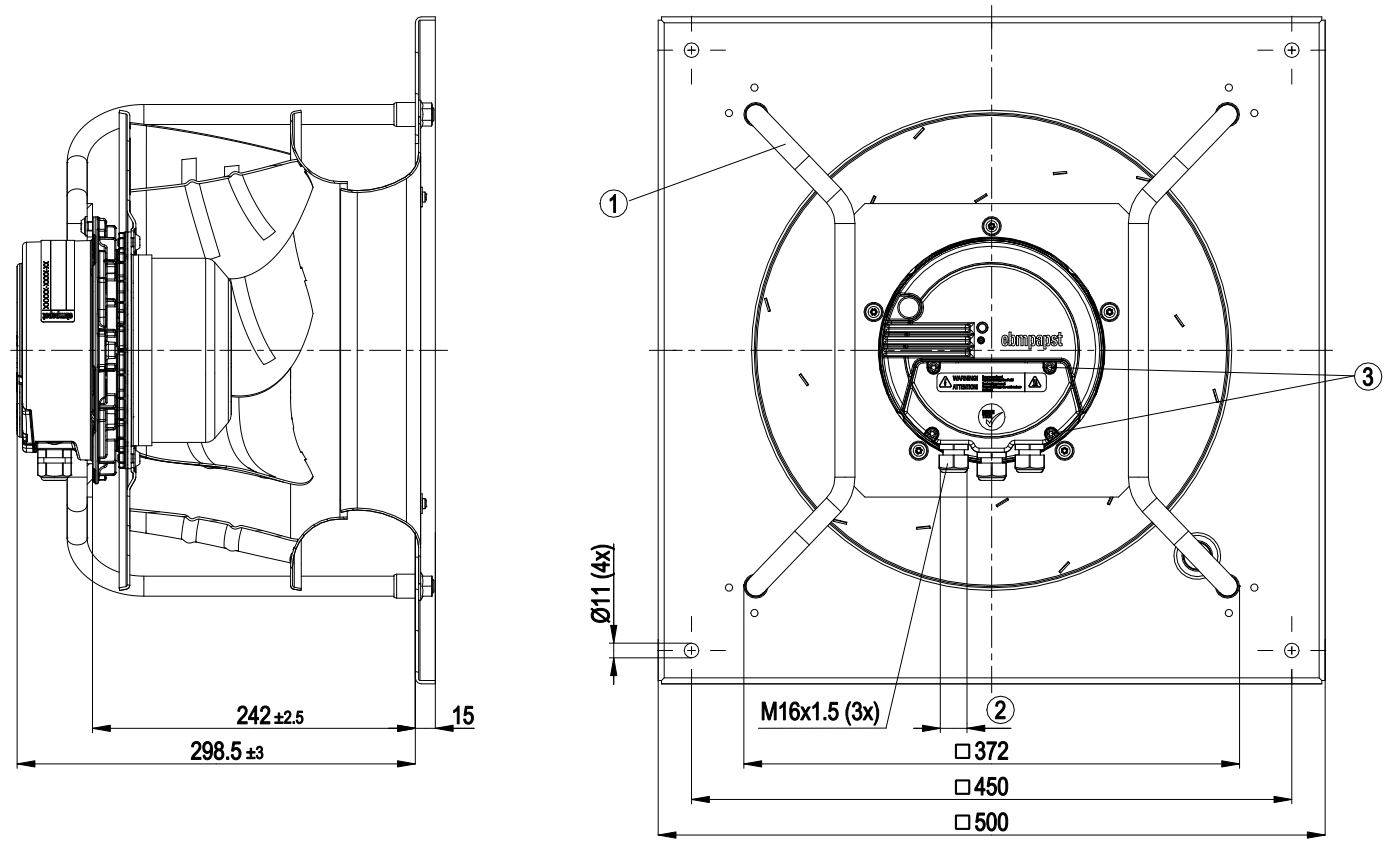
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Product drawing



1	Installation position: Shaft horizontal (only install support struts vertically as illustrated) or rotor on bottom; rotor on top on request
2	Cable diameter min. 4 mm, max. 10 mm; tightening torque 2.5±0.4 Nm
3	Tightening torque 3.5 ± 0.5 Nm

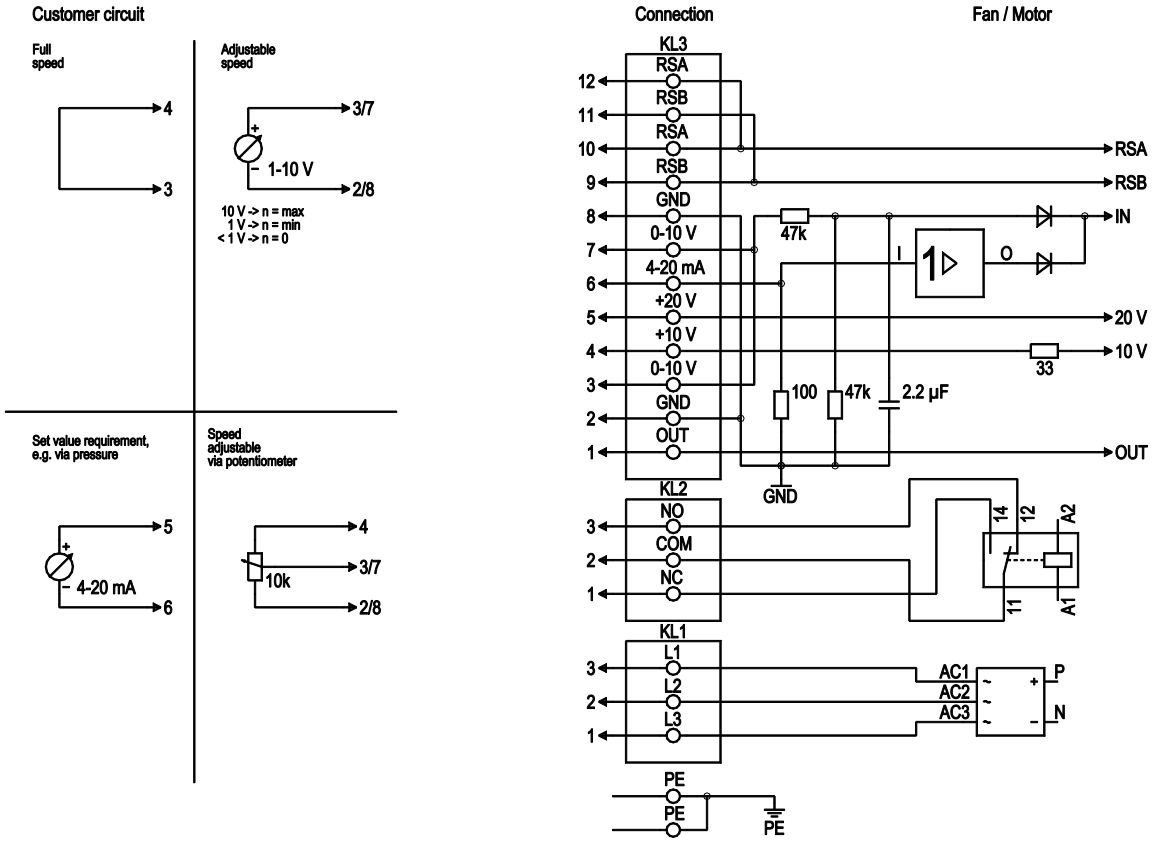
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Connection diagram



No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBUS, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBUS, RSA, SELV

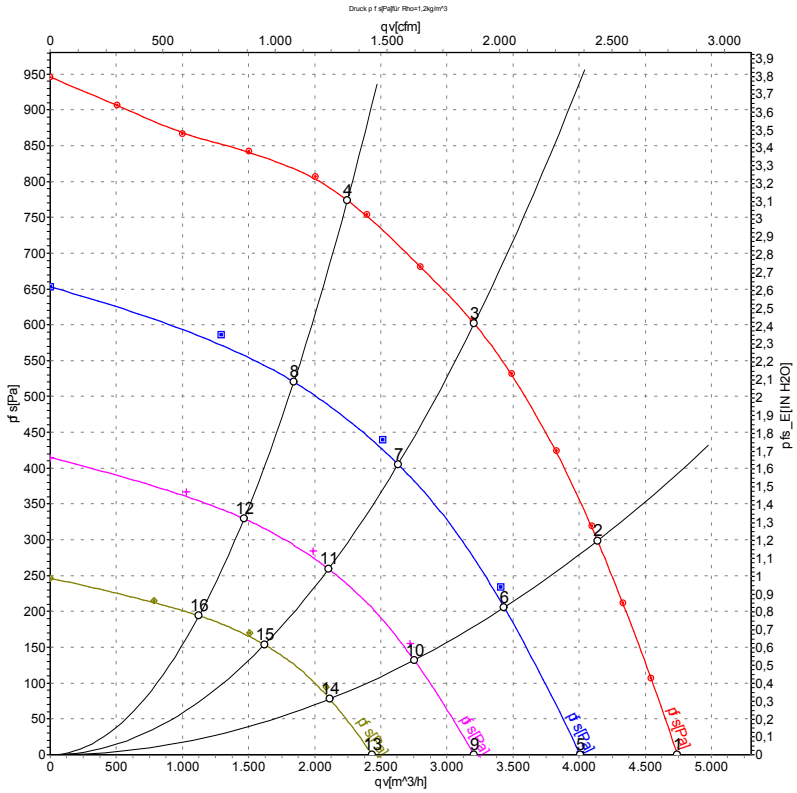
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Curves: Air performance 50 Hz



Measurement: LU-78488-1
Measurement: LU-120618-1
Measurement: LU-120619-1
Measurement: LU-120620-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	CFM	inH2O
1	400	50	2200	690	1.35	81	88	94	4745	0	2790	0.00
2	400	50	2200	859	1.61	77	84	90	4140	300	2435	1.20
3	400	50	2200	950	1.75	73	80	86	3205	600	1885	2.41
4	400	50	2200	851	1.61	76	83	88	2245	775	1325	3.11
5	400	50	1825	386	0.72	74	81	87	4010	0	2360	0.00
6	400	50	1825	476	0.87	70	77	84	3430	224	2020	0.90
7	400	50	1825	502	0.90	67	74	80	2630	414	1550	1.66
8	400	50	1825	462	0.84	69	76	82	1840	520	1085	2.09
9	400	50	1450	206	0.43	67	73	79	3205	0	1885	0.00
10	400	50	1450	251	0.51	64	71	77	2750	145	1620	0.58
11	400	50	1450	265	0.53	61	67	73	2105	264	1240	1.06
12	400	50	1450	244	0.49	62	69	74	1465	329	865	1.32
13	400	50	1100	106	0.26	58	65	71	2435	0	1435	0.00
14	400	50	1100	123	0.29	56	63	68	2115	87	1245	0.35
15	400	50	1100	126	0.29	53	60	66	1620	156	955	0.63
16	400	50	1100	118	0.28	54	61	67	1125	194	660	0.78

U = Power supply · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · qv = Air flow · p_{fs} = Pressure increase

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