R3G400-RG53-05

EC centrifugal fan - RadiCal

backward-curved, single-intake

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Nominal data

Type	**R3G400-RG53-05**
Motor	**M3G112-EA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	1840
Power consumption	W	960
Current draw	A	1.75
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	55

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	66.2	51.1
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		77.1	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	0.9
09 Air flow q_v	m^3/h	4055
09 Pressure increase p_{fs}	Pa	491
10 Speed (rpm) n	min^{-1}	1850
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-188758

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Technical description

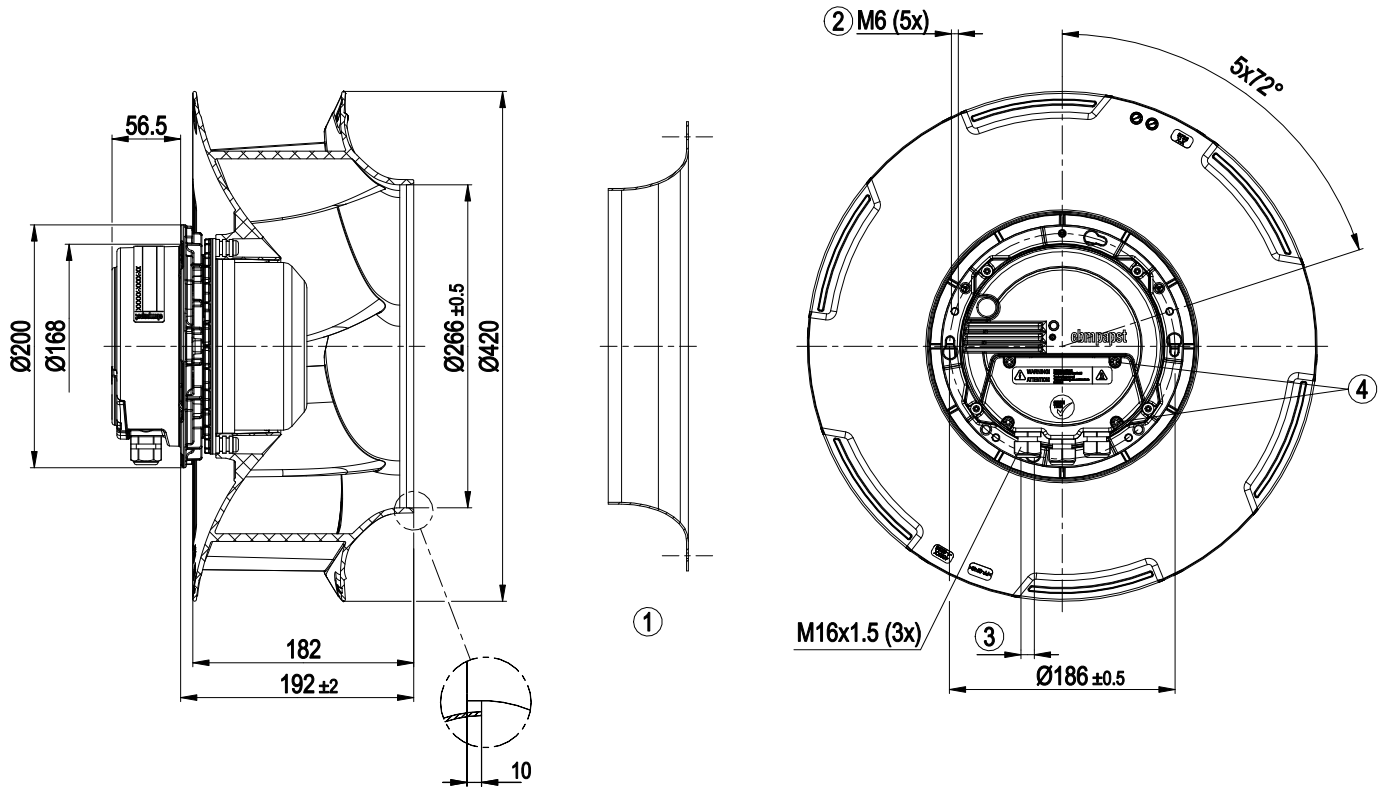
Weight	9.1 kg
Size	400 mm
Motor size	112
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	PP plastic (black)
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H0 - dry environment
Max. permitted ambient temp. for motor (transport/storage)	+ 80 °C
Min. permitted ambient temp. for motor (transport/storage)	- 40 °C
Installation position	Any
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Operation and alarm display - Tach output - Input for sensor 0-10 V or 4-20 mA - External 24 V input (parameter setting) - Alarm relay - Integrated PID controller - Power limiter - Motor current limitation - PFC, passive - RS-485 MODBUS-RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 61000-6-3 (household environment)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	CSA C22.2 No. 77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730-1; CCC

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Product drawing



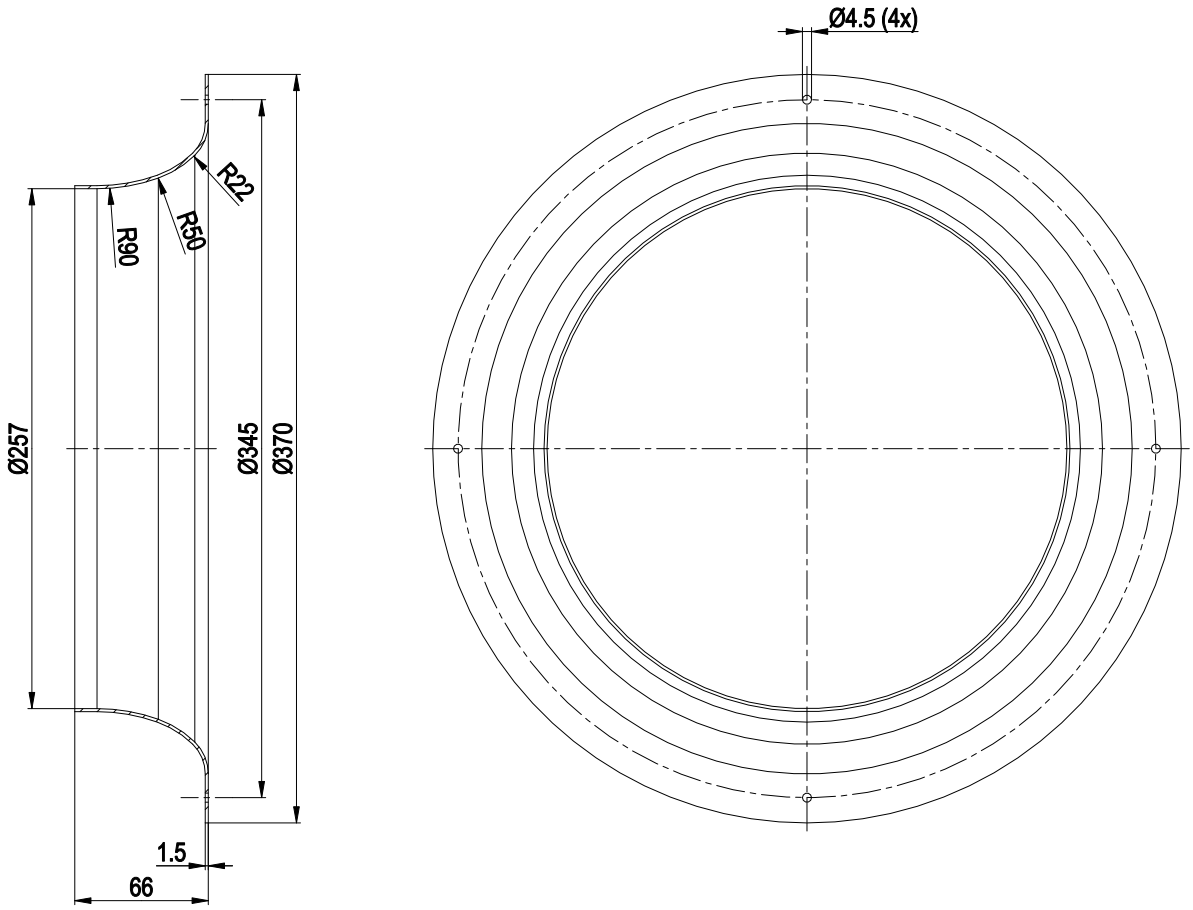
1	Accessory part: inlet ring 54476-2-4013 not included in scope of delivery
2	Max. clearance for screw 16 mm
3	Cable diameter min. 4 mm; max. 10 mm, tightening torque 2.5±0.4 Nm
4	Tightening torque 3.5±0.5 Nm

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Accessory part



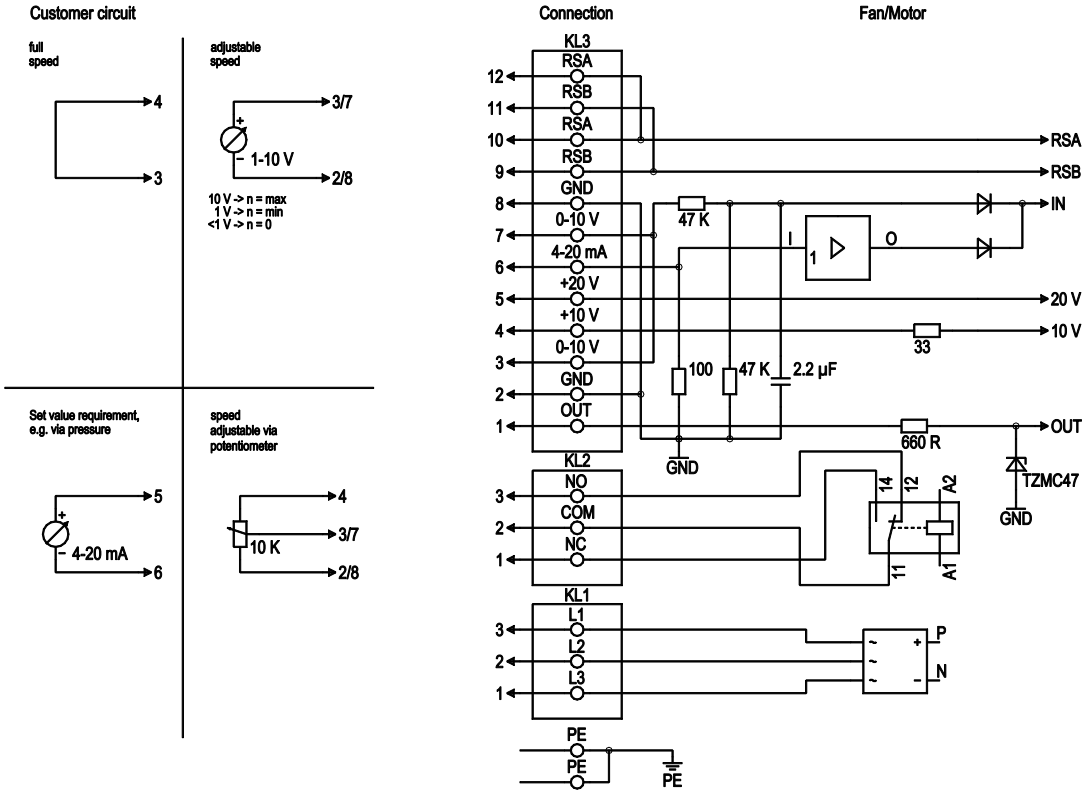
Inlet ring 54476-2-4013 not included in scope of delivery

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Connection diagram



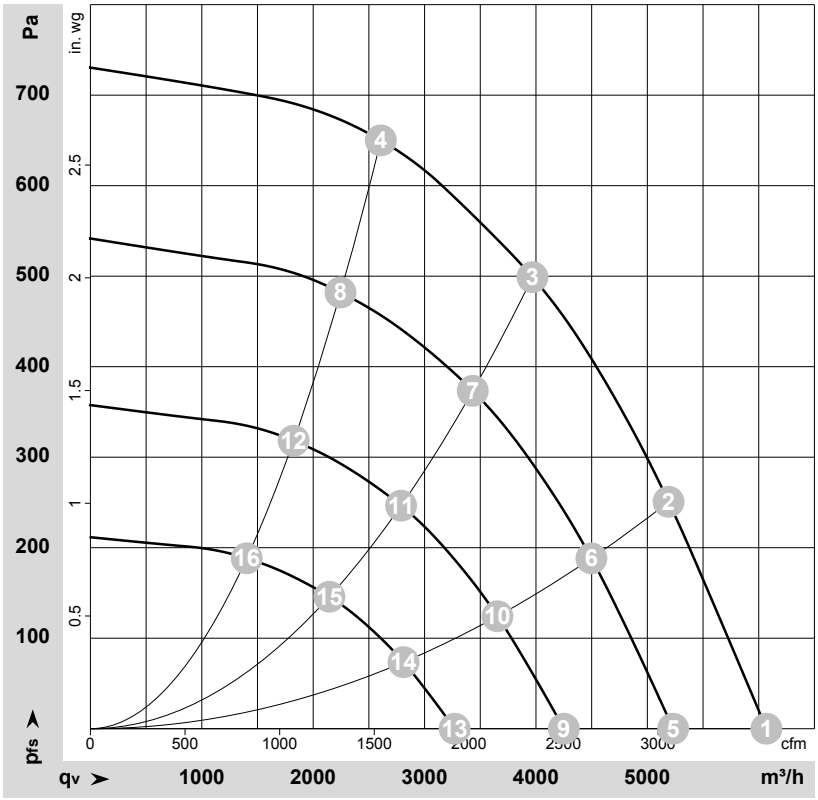
No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2, 3	L1, L2, L3	Power supply, voltage range (see nameplate), 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Tach output, pulses per revolution configurable, max. 50 V/10 mA open collector, Ri=660 ohms, SELV
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3%), max. 10 mA, power supply for external devices (e.g. potentiometers), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25%/-10%), max. 50 mA, power supply for external devices (e.g. sensors), SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for MODBUS, RSB
KL3	10, 12	RSA	RS485 interface for MODBUS, RSA

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Curves: Air performance 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-188758-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	Wired	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
		V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	3~	400	50	1840	623	1.14	78	84	87	6070	0	3570	0.00
2	3~	400	50	1840	822	1.42	71	77	83	5190	250	3055	1.00
3	3~	400	50	1840	960	1.75	64	71	78	3970	500	2335	2.01
4	3~	400	50	1840	863	1.48	68	74	79	2610	650	1535	2.61
5	3~	400	50	1600	399	0.73	74	80	84	5230	0	3080	0.00
6	3~	400	50	1600	535	0.92	67	74	80	4495	190	2645	0.76
7	3~	400	50	1600	587	1.00	61	67	75	3435	375	2020	1.51
8	3~	400	50	1600	551	0.94	64	70	75	2245	482	1320	1.94
9	3~	400	50	1300	214	0.39	69	75	78	4250	0	2500	0.00
10	3~	400	50	1300	287	0.49	62	68	75	3655	126	2150	0.51
11	3~	400	50	1300	315	0.54	55	62	69	2790	247	1640	0.99
12	3~	400	50	1300	296	0.51	59	65	70	1825	318	1075	1.28
13	3~	400	50	1000	98	0.18	62	69	72	3270	0	1925	0.00
14	3~	400	50	1000	131	0.23	55	62	68	2810	74	1655	0.30
15	3~	400	50	1000	143	0.24	49	55	63	2145	146	1265	0.59
16	3~	400	50	1000	135	0.23	52	58	63	1405	188	825	0.75

Wired = Wiring · U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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