R3G500-AF32-11

EC centrifugal fan

backward-curved, single-intake



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Nominal data

Type	**R3G500-AF32-11**
Motor	**M3G112-GA**

Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	1100
Power consumption	W	710
Current draw	A	3.2
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	50

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011 (EN 17166)

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	59.3	49.9
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		71.4	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	0.71
09 Air flow q_v	m^3/h	4735
09 Pressure increase p_{fs}	Pa	292
10 Speed (rpm) n	min^{-1}	1105
11 Specific ratio*		1.00

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-104083

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Technical description

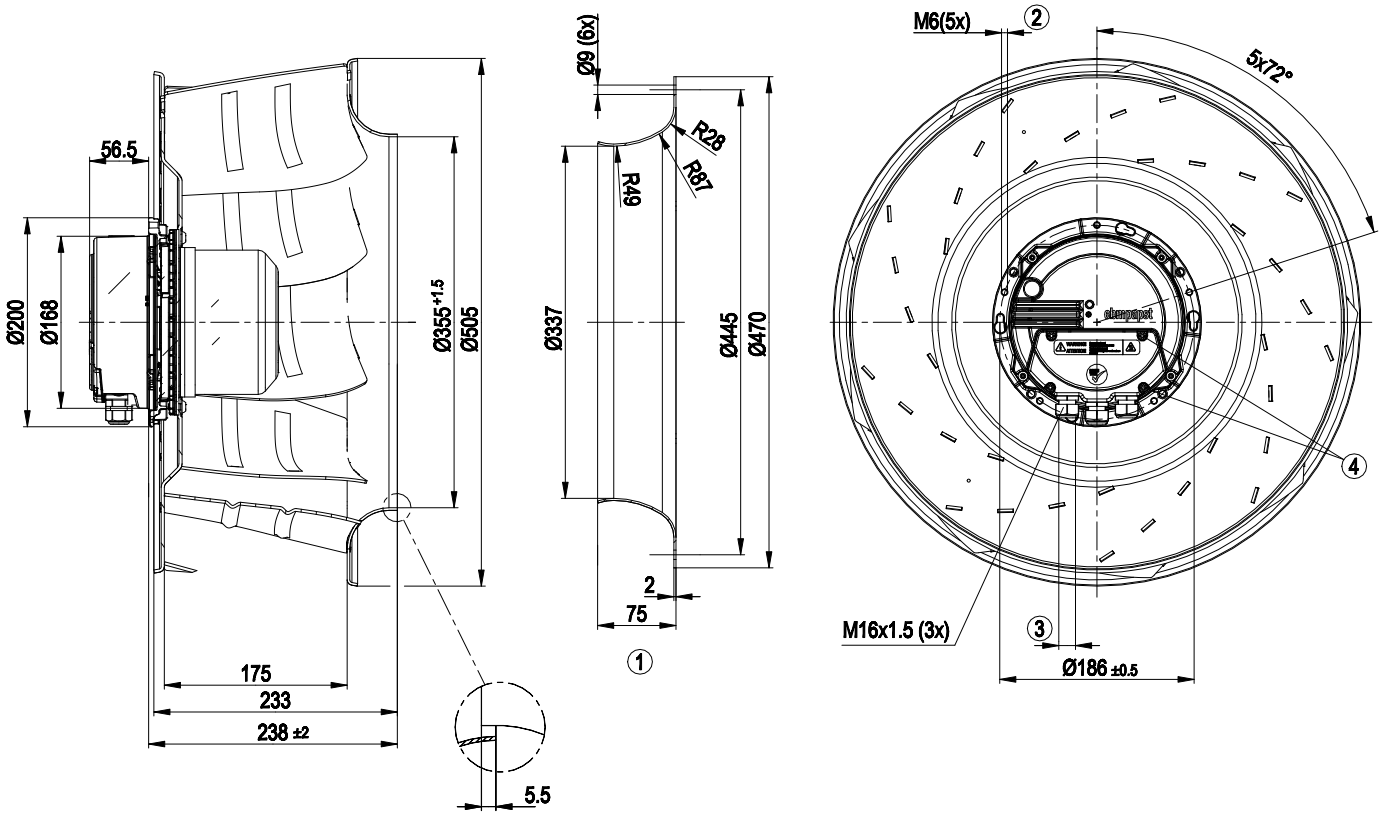
Weight	12.8 kg
Size	500 mm
Motor size	112
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Number of blades	9
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, active - RS-485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from supply - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
EMC immunity to interference	According to EN 61000-6-2 (industrial environment)
EMC circuit feedback	According to EN 61000-3-2/3
EMC interference emission	According to EN 55022 (Class A)
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Thermal overload protector (TOP) internally connected
With cable	Variable
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	CCC; EAC

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Product drawing



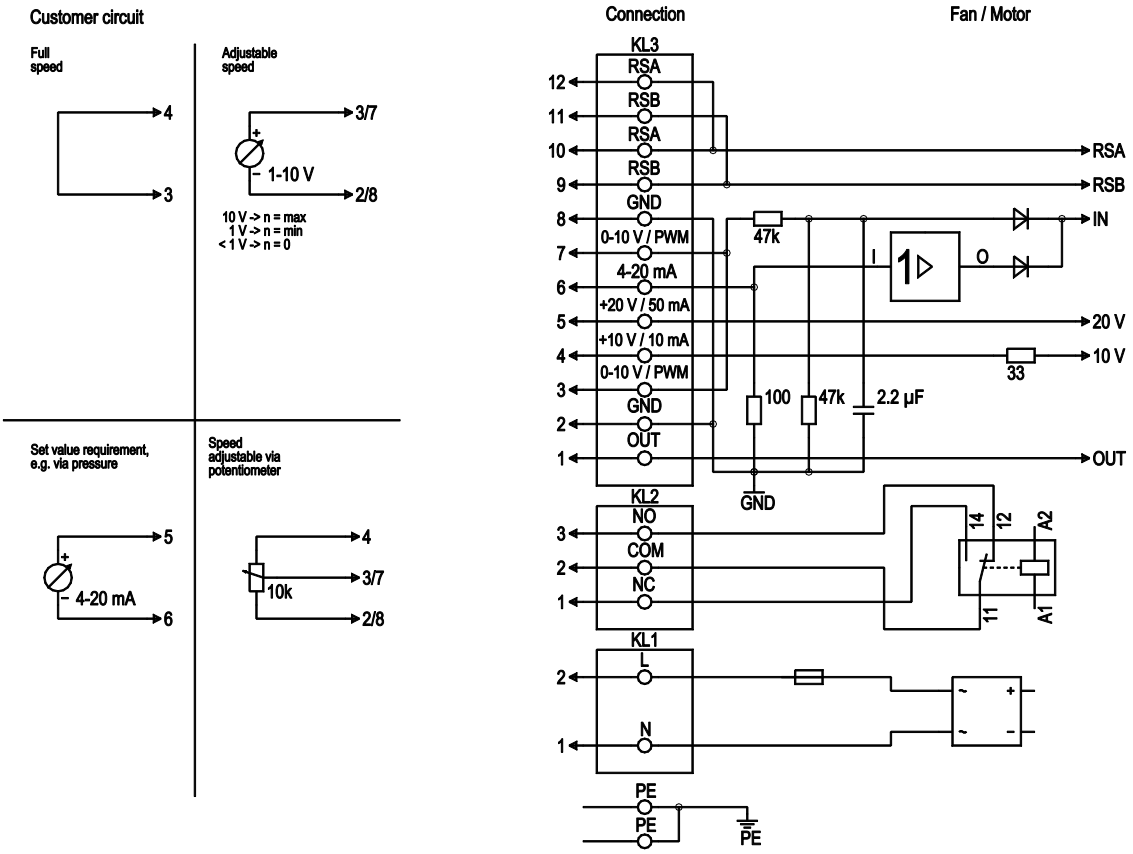
1	Accessory part: Inlet ring 63072-2-4013, not included in scope of delivery.
2	Cable diameter: min. 4 mm, max. 10 mm, tightening torque 2.5±0.4 Nm
3	Max. clearance for screw 16 mm
4	Tightening torque 3.5 ± 0.5 Nm

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Connection diagram



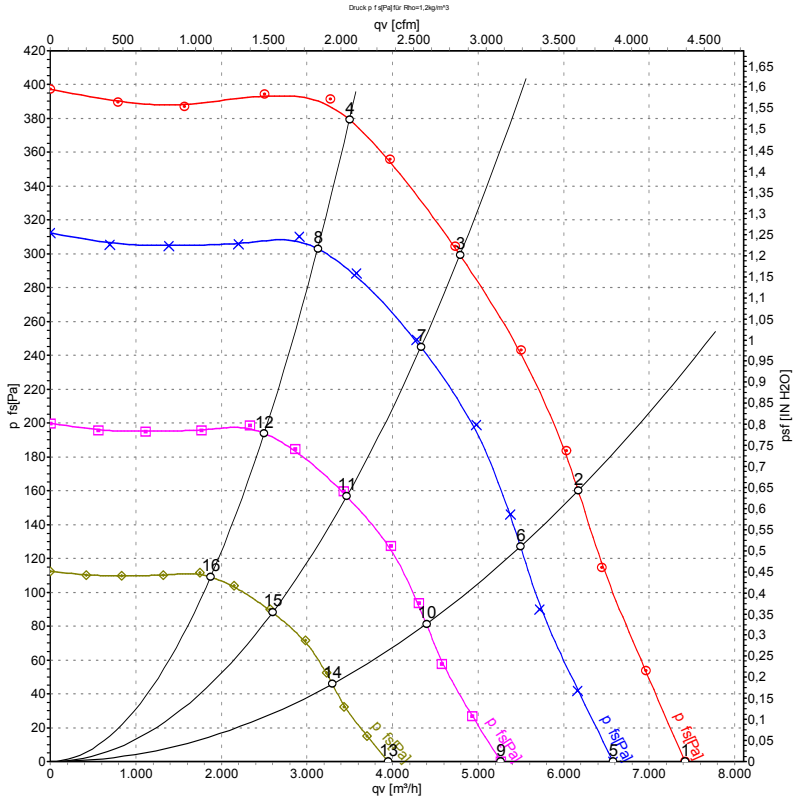
No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2	N, L	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3 %), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25% / -10%), max. 50 mA, power supply for external devices (e.g. sensors); SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBUS, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBUS, RSA, SELV

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Curves: Air performance 50 Hz



Measurement: LU-104083-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	230	50	1120	521	2.41	75	82	85	7415	0	4365	0.00
2	230	50	1120	656	2.97	69	75	80	6170	160	3630	0.64
3	230	50	1100	710	3.20	63	70	75	4790	300	2820	1.20
4	230	50	1120	684	3.08	63	70	76	3495	380	2060	1.53
5	230	50	1000	364	1.68	73	79	82	6580	0	3870	0.00
6	230	50	1000	463	2.10	66	73	77	5495	127	3235	0.51
7	230	50	1000	526	2.37	61	68	73	4330	246	2550	0.99
8	230	50	1000	488	2.20	61	68	74	3125	303	1840	1.22
9	230	50	800	186	0.86	68	75	77	5265	0	3100	0.00
10	230	50	800	237	1.07	61	68	72	4395	81	2585	0.33
11	230	50	800	269	1.21	56	63	68	3465	157	2040	0.63
12	230	50	800	250	1.13	56	63	69	2500	194	1470	0.78
13	230	50	600	79	0.36	61	68	71	3945	0	2325	0.00
14	230	50	600	100	0.45	55	62	66	3295	46	1940	0.18
15	230	50	600	114	0.51	50	57	62	2600	88	1530	0.35
16	230	50	600	106	0.48	50	57	62	1875	109	1105	0.44

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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