K3G400-PI92-02

EC centrifugal module - RadiPac

backward curved, single inlet

with support bracket

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Nominal data

Type	**K3G400-PI92-02**
Motor	**M3G112-IA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
Speed (rpm)	min^{-1}	2450
Power input	W	2500
Current draw	A	3.8
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	40

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data in accordance with ecodesign regulation EU 327/2011 (prEN 17166)

		Actual	Request 2015
01 Overall efficiency η_{es}	%	69.1	55.6
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		75.5	62
05 Variable speed drive		Yes	

09 Power input P_{ed}	kW	2.46
09 Air flow q_v	m^3/h	6585
09 Pressure increase p_{fs}	Pa	881
10 Speed (rpm) n	min^{-1}	2465
11 Specific ratio*		1.01

Data definition with optimum efficiency.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-196824

The indicated efficiency values for obtaining conformity with the Ecodesign Directive EU 327/2011 were achieved with defined air conduction components (e.g. inlet nozzles).
The dimensions are to be requested from ebm-papst. If other air guide geometries are used on the installation side, the ebm-papst evaluation loses its validity/conformity must be confirmed again.

The product does not fall within the scope of Regulation (EU) 2019/1781 due to the exception specified in Article 2(2a) (motors completely integrated into a product).

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Technical features

Mass	26 kg
Size	400 mm
Motor size	112
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Material of mounting plate	Sheet steel, galvanised
Material of support bracket	Steel, coated in black
Number of blades	5
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP54
Insulation class	"B"
Humidity (F) / environmental protection class (H)	H1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	See key to the product drawing
Condensation drainage holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Output limit - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment), except EN 61000-3-2 for professionally used devices with a total rated power greater than 1 kW
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical connection	Terminal box
Motor protection	Thermal overload protector (TOP) wired internally

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Safety classification	I; If a protective earth is connected by the customer This component to be built-in can have several local protection class ratings. The specification refers to the basic design of this component. The final protection class is based on the intended installation and connection of the component.
Product conforming to standard	EN 61800-5-1; CE
Approval	CSA C22.2 no. 77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730-1

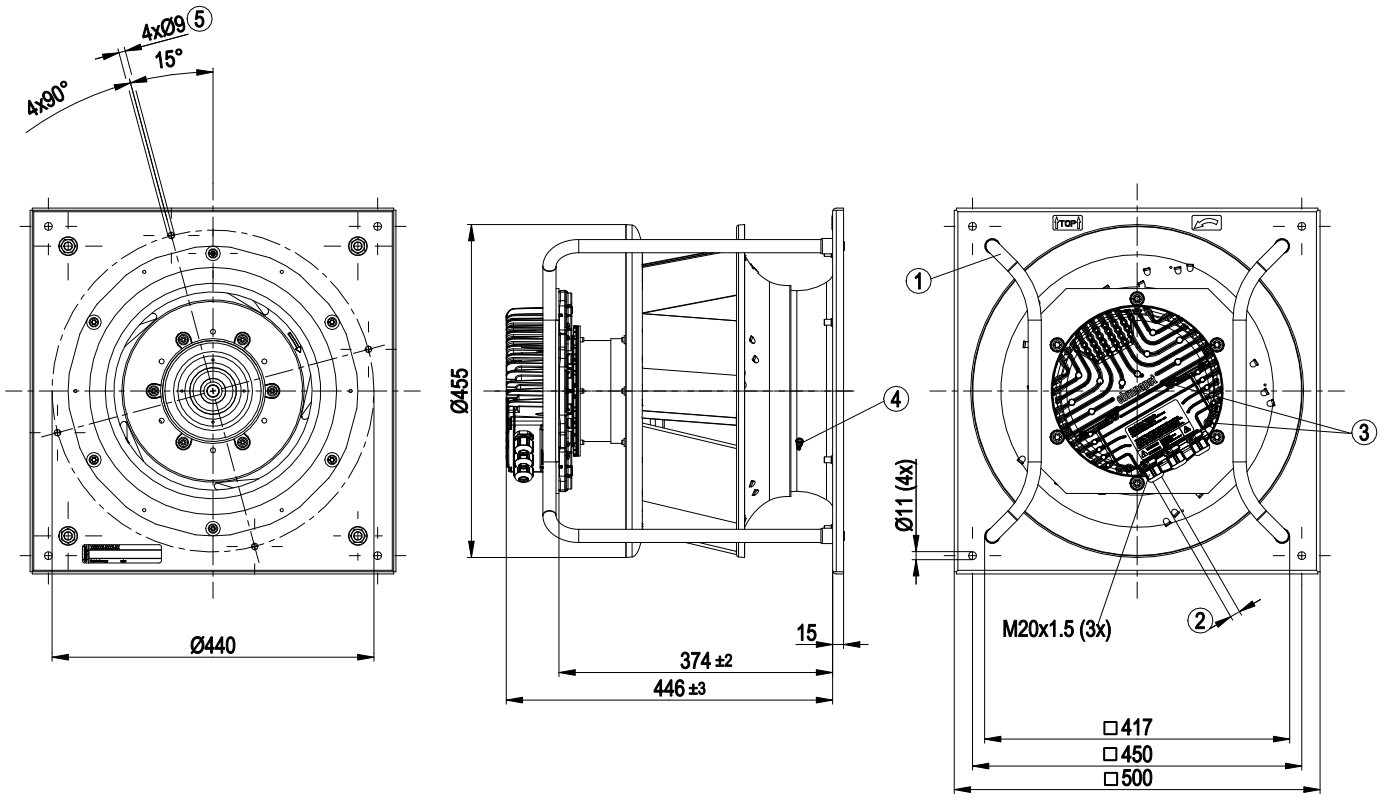
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Product drawing



1	Installation position: Shaft horizontal (install the support struts only vertically as shown in the illustration!) or rotor on bottom; rotor on top on request
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 4±0.6 Nm
3	Tightening torque 3.5±0.5 Nm
4	Inlet nozzle with pressure tap (k-factor: 188)
5	Mounting holes for FlowGrid

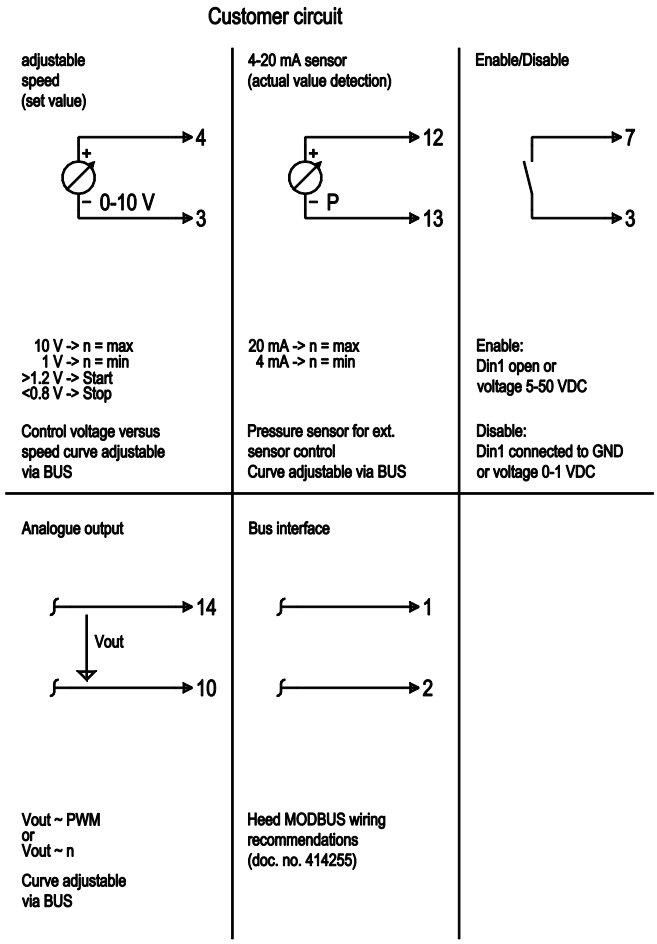
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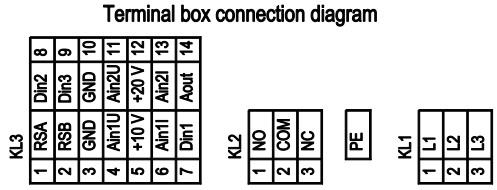
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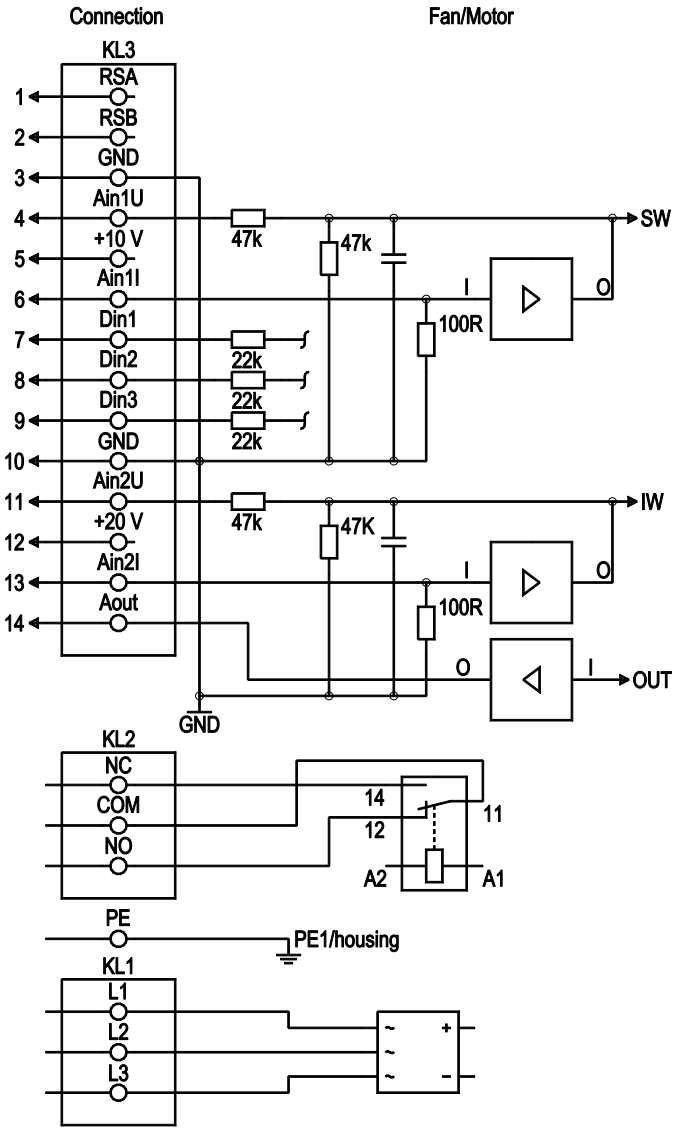
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Connection screen







No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains connection, power supply; see technical data for nominal voltage range
KL 1	2	L2	Mains connection, power supply; see technical data for nominal voltage range
KL 1	3	L3	Mains connection, power supply; see technical data for nominal voltage range
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection; contact rating 30 VAC/max. 2 A (AC1)/min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Reference ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only for use as alternative to input Ain1; SELV

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No.	Conn.	Designation	Function / assignment
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V +/- 3%, max. 10 mA, short-circuit-proof, power supply for ext. devices (e.g. potentiometer); SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω, parametrisable curve, only for use as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: Enabling of electronics, Enabling: Pin open or applied voltage 5-50 VDC Disabling: Bridge to GND or applied voltage <1 VDC Reset function: Triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: Parameter set 1/2 switching, depending on EEPROM setting, the valid/used parameter set can be selected via the bus or via the digital input DIN2. Parameter set 1: Pin open or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: Controller function of integrated controller, depending on EEPROM setting, the controller function of the integrated controller can be selected via the bus or the digital input Din 3 normal: pin open or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC, +20 V +25/-10%, max. 50 mA, short-circuit-proof, power supply for ext. devices (e.g. sensors); SELV Alternatively: +24 VDC input for parametrisation without mains power
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, Ri = 100 Ω, parametrisable curve, only for use as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV

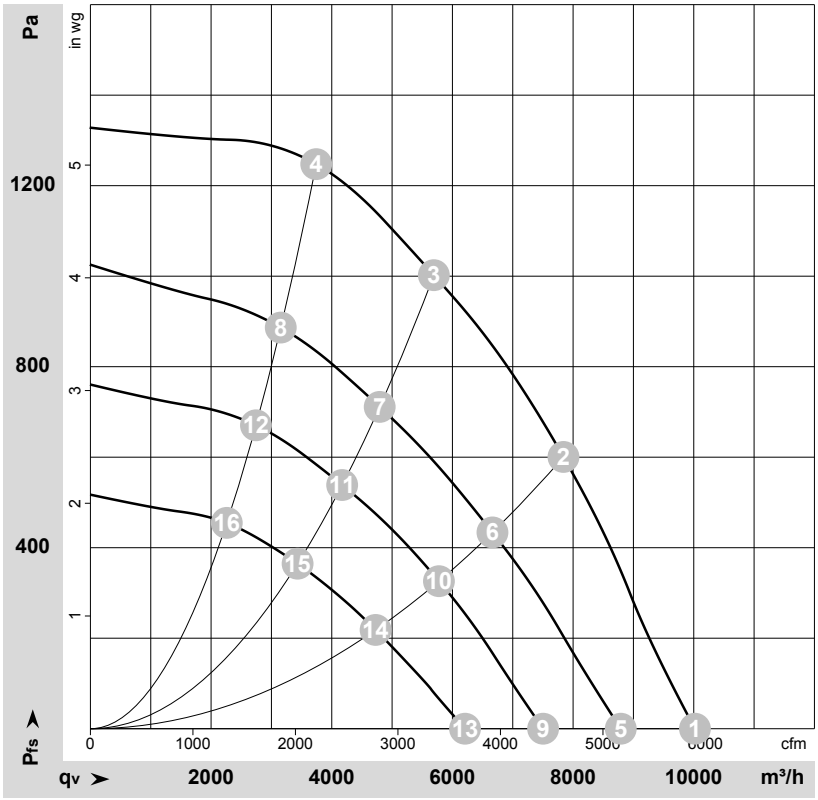
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Charts: Air flow 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-176408-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	Conn.	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
		V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	Y	400	50	2450	1323	2.07	89	96	96	10020	0	5900	0.00
2	Y	400	50	2450	2210	3.38	77	85	88	7840	600	4615	2.41
3	Y	400	50	2450	2500	3.80	74	82	86	5690	1000	3350	4.01
4	Y	400	50	2450	2336	3.57	78	86	90	3745	1250	2205	5.02
5	Y	400	50	2180	921	1.50	84	91	92	8790	0	5175	0.00
6	Y	400	50	2100	1376	2.15	72	80	84	6665	434	3920	1.74
7	Y	400	50	2080	1479	2.30	70	77	83	4795	712	2820	2.86
8	Y	400	50	2090	1420	2.22	74	81	85	3155	887	1855	3.56
9	Y	400	50	1875	626	1.10	80	87	88	7505	0	4415	0.00
10	Y	400	50	1825	923	1.50	69	77	81	5775	326	3400	1.31
11	Y	400	50	1810	994	1.60	66	74	80	4175	539	2455	2.16
12	Y	400	50	1815	955	1.55	69	77	82	2745	671	1615	2.69
13	Y	400	50	1545	377	0.73	74	83	85	6210	0	3655	0.00
14	Y	400	50	1500	545	1.00	64	72	77	4725	220	2780	0.88
15	Y	400	50	1490	585	1.05	62	69	76	3435	365	2020	1.47
16	Y	400	50	1495	566	1.03	64	72	78	2260	455	1330	1.83

Conn. = Connection · U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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