W3G990-CU28-86

EC axial fan - HyBlade

sickled blades (S series)

with full round nozzle, Transformator fan

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Nominal data

Type	**W3G990-CU28-86**
Motor	**M3G150-IF**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		fa
Speed (rpm)	min^{-1}	750
Power input	W	1300
Current draw	A	2
Max. back pressure	Pa	140
Min. ambient temperature	°C	-40
Max. ambient temperature	°C	60

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Occasional start-up between -40 °C and -25 °C is permissible. For continuous operation at ambient temperatures below -25 °C (such as refrigeration applications), a fan design with special low-temperature bearings must be used.

Data in accordance with ecodesign regulation EU 327/2011 (EN 17166)

		Actual	Request 2015
01 Overall efficiency η_{es}	%	49.3	35.1
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		54.2	40
05 Variable speed drive		Yes	

09 Power input P_{ed}	kW	1.71
09 Air flow q_v	m^3/h	22900
09 Pressure increase p_{fs}	Pa	124
10 Speed (rpm) n	min^{-1}	760
11 Specific ratio*		1.00

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

LU-171007

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Technical features

Mass	61.4 kg
Size	990 mm
Motor size	150
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium, coated in black
Material of blades	Aluminium sheet insert (coated in black), sprayed with PP plastic
Material of wall ring	Sheet steel, galvanised and coated with light grey plastic (ANSI 70)
Material of guard grille	Steel, coated with light grey plastic (ANSI 70)
Number of blades	5
Blade angle	0°
Direction of air flow	A
Direction of rotation	Counter-clockwise, seen on rotor
Type of protection	IP55
Insulation class	"F"
Humidity (F) / environmental protection class (H)	H2+T
Note ambient temperature	Occasional start-up between -40 °C and -25 °C is permissible. For continuous operation at ambient temperatures below -25 °C (e.g. refrigeration applications), a fan version with special low-temperature bearings must be used.
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on top
Condensation drainage holes	On the stator side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Operation and alarm display - Input for sensor 0-10 V or 4-20 mA - External 24 V input (programming) - External release input - Alarm relay - Integrated PID controller - Motor current limit - PFC, passive - RS485 MODBUS RTU - Soft start -Maximum EEPROM write cycles 100,000 - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Over-temperature protected electronics / motor - Line undervoltage / phase failure detection
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical connection	Terminal box
Motor protection	Reverse polarity and locked-rotor protection

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Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE
Approval	CSA C22.2 no. 77 + CAN/CSA-E60730-1; EAC; UL 1004-7 + 60730-1

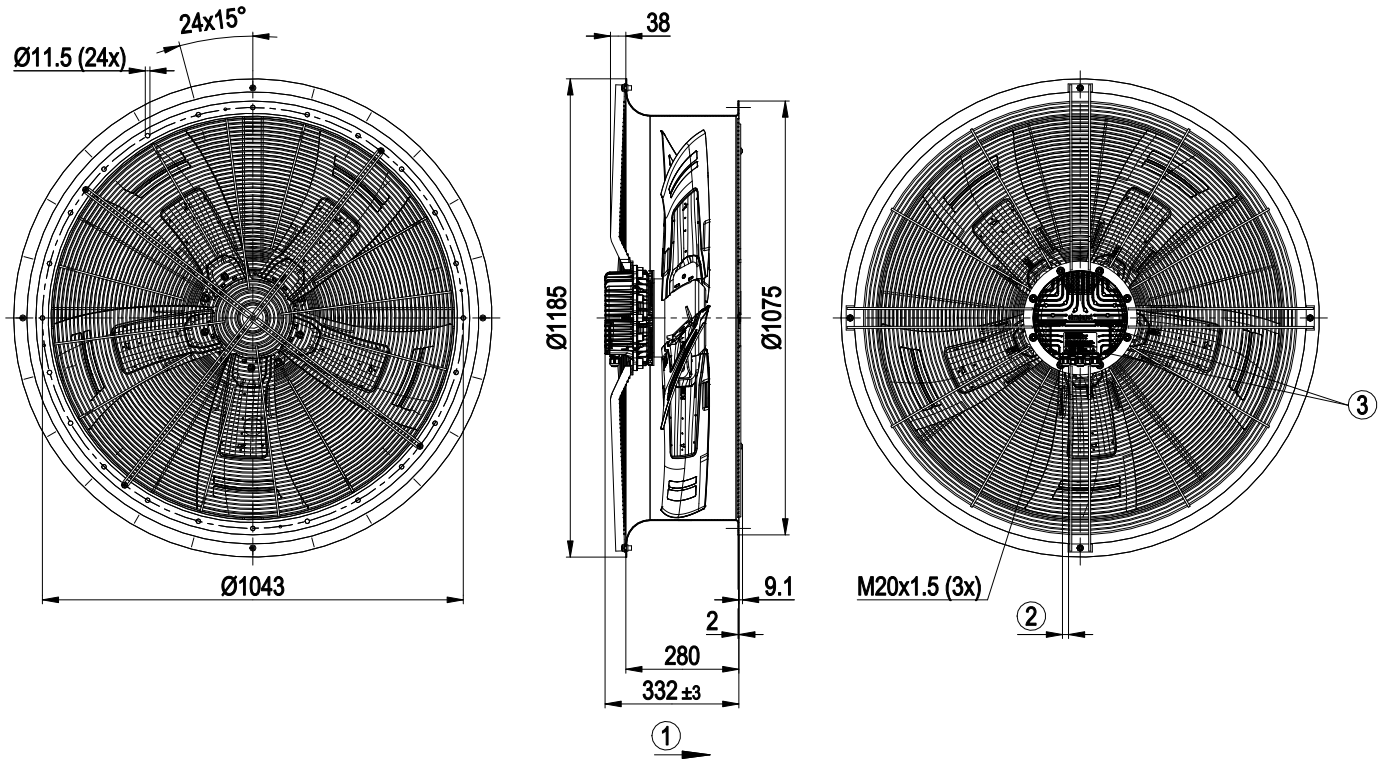
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Product drawing



1	Direction of air flow "A"
2	Cable diameter min. 5 mm, max. 13 mm, tightening torque 4±0.6 Nm
3	Tightening torque 3.5±0.5 Nm

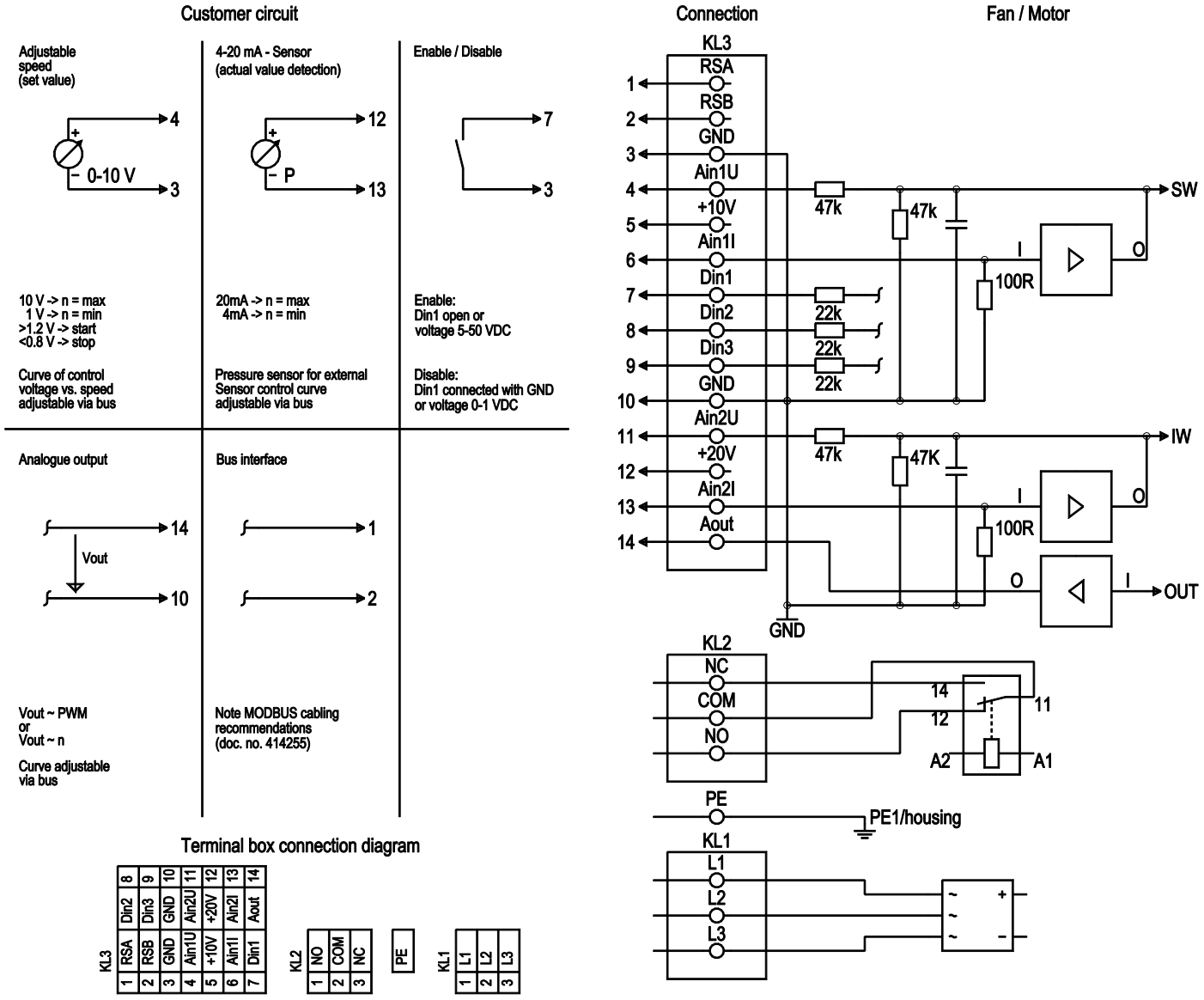
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Connection screen



No.	Conn.	Designation	Function / assignment
KL 1	1	L1	Mains connection, power supply; see technical data for nominal voltage range
KL 1	2	L2	Mains connection, power supply; see technical data for nominal voltage range
KL 1	3	L3	Mains connection, power supply; see technical data for nominal voltage range
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact, make for failure
KL2	2	COM	Status relay, floating status contact, changeover contact, common connection, contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact, break for failure
KL 3	1	RSA	Bus connection RS-485, RSA, MODBUS RTU; SELV
KL 3	2	RSB	Bus connection RS-485, RSB, MODBUS RTU; SELV
KL 3	3 / 10	GND	Signal ground for control interface; SELV
KL 3	4	Ain1 U	Analogue input 1, set value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain1; SELV

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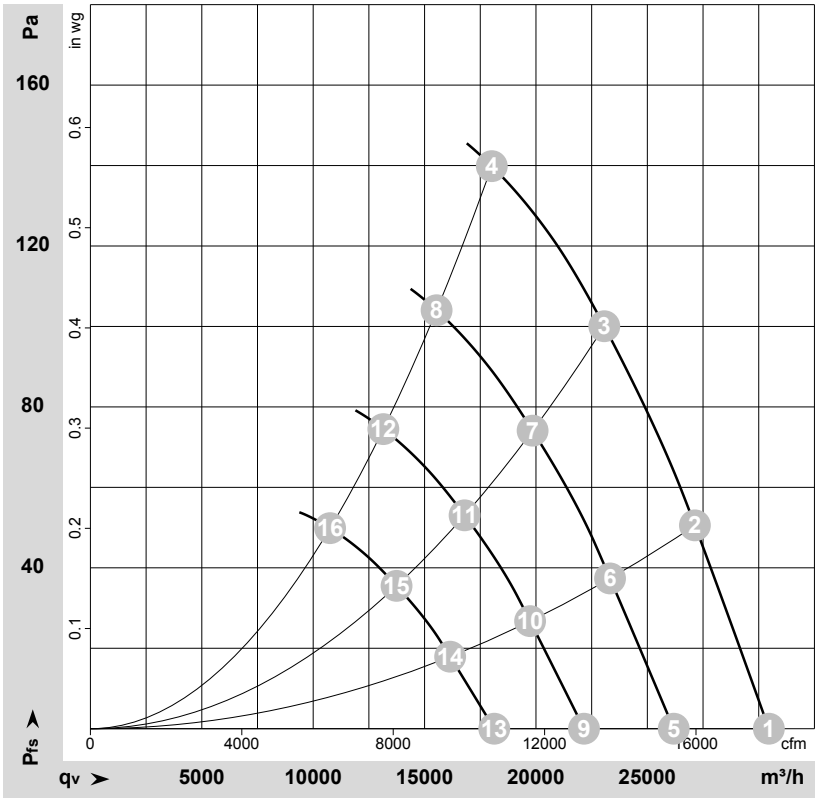
No.	Conn.	Designation	Function / assignment
KL 3	5	+ 10 V	Fixed voltage output 10 VDC, +10 V ±3%, max. 10 mA, short-circuit-proof, power supply for external devices (e.g. potentiometer); SELV
KL 3	6	Ain1 I	Analogue input 1, set value: 4-20 mA; Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain1 U; SELV
KL 3	7	Din1	Digital input 1: enabling of electronics, enabling: open pin or applied voltage 5-50 VDC disabling: bridge to GND or applied voltage <1 VDC reset function: triggers software reset after a level change to <1 VDC; SELV
KL 3	8	Din2	Digital input 2: parameter set switch 1/2, according to EEPROM setting, the valid/used parameter set can be selected via bus or via digital input DIN2. Parameter set 1: open pin or applied voltage 5-50 VDC Parameter set 2: bridge to GND or applied voltage <1 VDC; SELV
KL 3	9	Din3	Digital input 3: controller function of integrated controller, according to EEPROM setting, the controller function of the integrated controller is normally/inversely selectable per bus or per digital input Din 3 normal: open pin or applied voltage 5-50 VDC inverse: bridge to GND or applied voltage <1 VDC; SELV
KL 3	11	Ain2 U	Analogue input 2, actual value: 0-10 V, Ri = 100 kΩ, parametrisable curve, only usable as alternative to input Ain2; SELV
KL 3	12	+ 20 V	Fixed voltage output 20 VDC; +20 V +25/-10%, max. 50 mA; short-circuit-proof; supply voltage for external devices (e.g. sensors); SELV Alternatively: +24 VDC input for parametrization without mains power
KL 3	13	Ain2 I	Analogue input 2, actual value: 4-20 mA, Ri = 100 Ω, parametrisable curve, only usable as alternative to input Ain2 U; SELV
KL 3	14	Aout	Analogue output 0-10 VDC, max. 5 mA, output of the current motor level control coefficient / motor speed parametrisable curve; SELV

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Charts: Air flow 50 Hz



ρ = 1.15 kg/m³ ± 2 %

Measurement: LU-162486-1

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	400	50	750	1300	2.00	72	81	81	30455	0	17925	0.00
2	400	50	750	1536	2.34	71	79	80	27135	50	15970	0.20
3	400	50	750	1729	2.61	70	78	79	23065	100	13575	0.40
4	400	50	750	1828	2.75	77	84	85	18020	140	10605	0.56
5	400	50	650	835	1.27	68	77	77	26185	0	15410	0.00
6	400	50	650	972	1.48	67	75	76	23325	38	13730	0.15
7	400	50	650	1101	1.66	67	75	75	19850	74	11685	0.30
8	400	50	650	1172	1.77	73	81	81	15540	104	9145	0.42
9	400	50	550	506	0.77	64	73	73	22155	0	13040	0.00
10	400	50	550	589	0.90	63	71	72	19735	27	11615	0.11
11	400	50	550	667	1.01	62	70	71	16795	53	9885	0.21
12	400	50	550	710	1.07	69	76	77	13150	75	7740	0.30
13	400	50	450	277	0.42	59	68	68	18130	0	10670	0.00
14	400	50	450	323	0.49	58	66	67	16150	18	9505	0.07
15	400	50	450	365	0.55	57	65	66	13740	36	8090	0.14
16	400	50	450	389	0.59	64	71	72	10760	50	6330	0.20

U = Supply voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
q_V = Air flow · p_{fs} = Pressure increase

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