K3G355-AI52-12

EC centrifugal module

backward-curved, single-intake

with support bracket

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Nominal data

Type	**K3G355-AI52-12**
Motor	**M3G112-EA**

Phase		1~
Nominal voltage	VAC	230
Nominal voltage range	VAC	200 .. 277
Frequency	Hz	50/60
Method of obtaining data		ml
Speed (rpm)	min^{-1}	2035
Power consumption	W	770
Current draw	A	3.5
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	55

ml = Max. load · me = Max. efficiency · fa = Free air · cs = Customer specification · ce = Customer equipment
Subject to change

Data according to Commission Regulation (EU) 327/2011

		Actual	Req. 2015
01 Overall efficiency η_{es}	%	56.4	50.1
02 Measurement category		A	
03 Efficiency category		Static	
04 Efficiency grade N		68.2	62
05 Variable speed drive		Yes	

09 Power consumption P_{ed}	kW	0.76
09 Air flow q_v	m^3/h	2820
09 Pressure increase p_{fs}	Pa	505
10 Speed (rpm) n	min^{-1}	2050
11 Specific ratio*		1.01

Data obtained at optimum efficiency level.
The ErP data is determined using a motor-impeller combination in a standardized measurement setup.

* Specific ratio = 1 + p_{fs} / 100 000 Pa

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Technical description

Weight	16.1 kg
Size	355 mm
Motor size	112
Rotor surface	Painted black
Electronics housing material	Die-cast aluminum
Impeller material	Sheet aluminum
Support plate material	Sheet steel, galvanized
Support bracket material	Steel, painted black
Inlet nozzle material	Sheet steel, galvanized
Number of blades	6
Direction of rotation	Clockwise, viewed toward rotor
Degree of protection	IP54
Insulation class	"B"
Moisture (F) / Environmental (H) protection class	H1
Max. permitted ambient temp. for motor (transport/storage)	+80 °C
Min. permitted ambient temp. for motor (transport/storage)	-40 °C
Installation position	See product drawing
Condensation drainage holes	On rotor side
Mode	S1
Motor bearing	Ball bearing
Technical features	- Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Output for slave 0-10 V - Input for sensor 0-10 V or 4-20 mA - Alarm relay - Integrated PID controller - Motor current limitation - PFC, active - RS-485 ebmBUS - Soft start - Control input 0-10 VDC / PWM - Control interface with SELV potential safely disconnected from the mains - Thermal overload protection for electronics/motor - Line undervoltage / phase failure detection
Touch current according to IEC 60990 (measuring circuit Fig. 4, TN system)	<= 3.5 mA
Electrical hookup	Terminal box
Motor protection	Thermal overload protector (TOP) internally connected
Protection class	I (with customer connection of protective earth)
Conformity with standards	EN 61800-5-1; CE
Approval	EAC

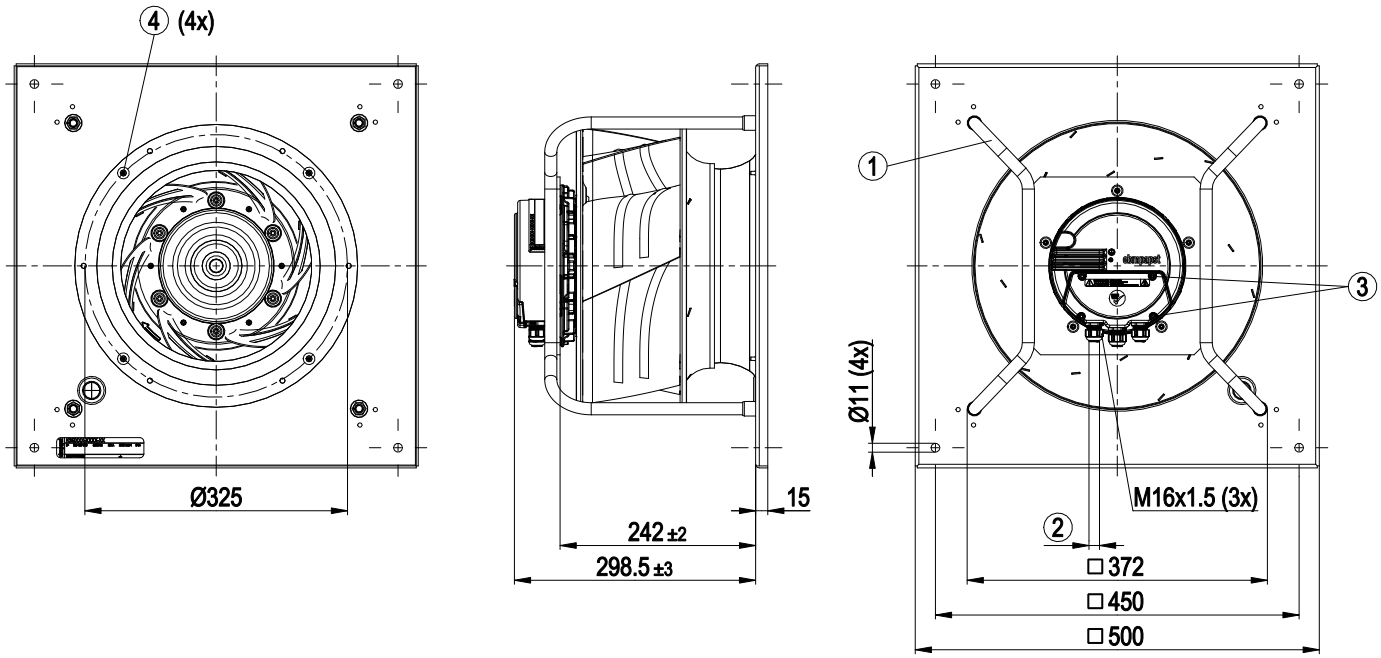
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Product drawing



1	Installed position: shaft horizontal (install support struts only vertically as illustrated) or rotor on bottom; rotor on top on request
2	Cable diameter min. 4 mm, max. 10 mm, tightening torque 2.5 ± 0.4 Nm
3	Tightening torque 3.5 ± 0.5 Nm
4	Attachment for inlet ring and FlowGrid

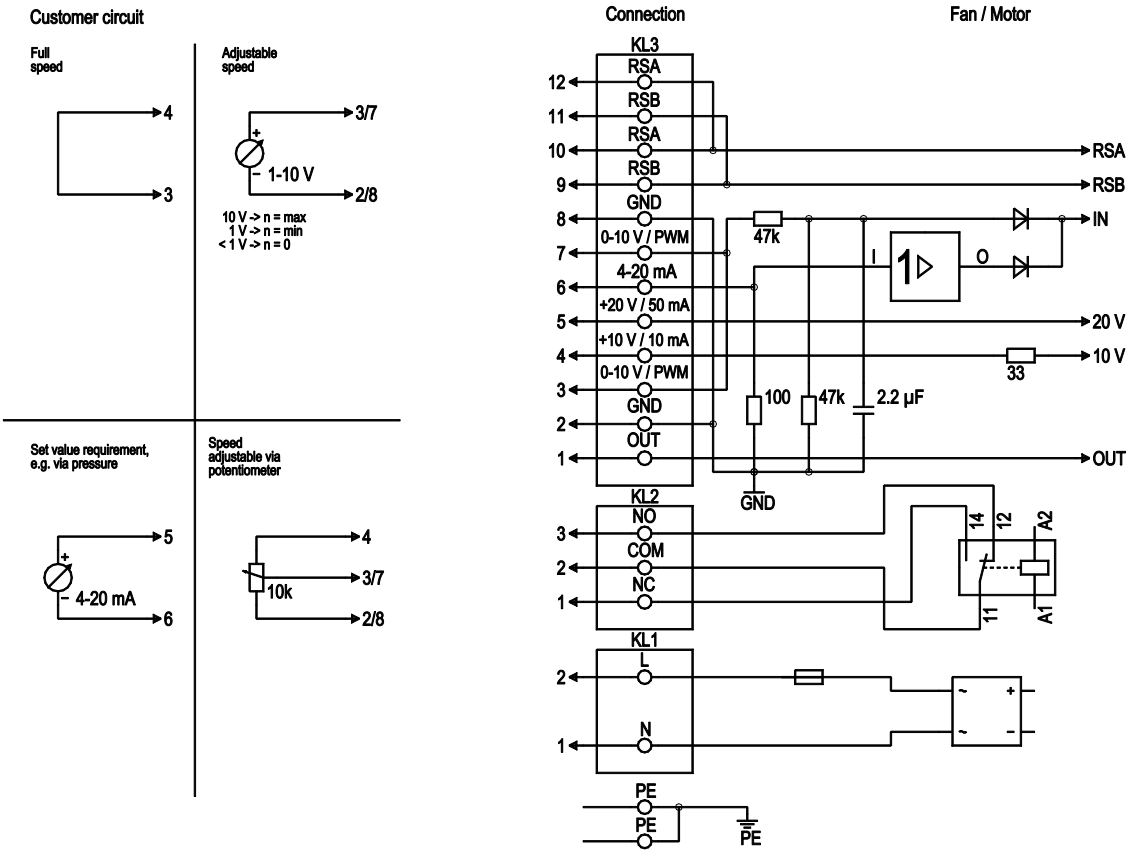
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Connection diagram



No.	Conn.	Designation	Function/assignment
PE		PE	Protective earth terminal
KL1	1, 2	N, L	Power supply 50/60 Hz
KL2	1	NC	Floating status contact, break for failure
KL2	2	COM	Floating status contact, changeover contact, common connection (2 A, max. 250 VAC, min. 10 mA, AC1)
KL2	3	NO	Floating status contact, make for failure
KL3	1	OUT	Analog output, 0-10 VDC, max. 3 mA, SELV, output of current motor modulation level: 1 V corresponds to 10% modulation level. 10 V corresponds to 100% modulation level.
KL3	2, 8	GND	Reference ground for control interface, SELV
KL3	3, 7	0-10 V	Use control / current sensor value input 0-10 VDC, impedance 100 kΩ only as alternative to 4-20 mA input, SELV
KL3	4	+10 V	Voltage output 10 VDC (±3 %), max. 10 mA, power supply for external devices (e.g. potentiometer), SELV
KL3	5	+20 V	Voltage output 20 VDC (+25% / -10%), max. 50 mA, power supply for external devices (e.g. sensors); SELV
KL3	6	4-20 mA	Use control / current sensor value input 4-20 mA, impedance 100 Ω only as alternative to 0-10 V input, SELV
KL3	9, 11	RSB	RS485 interface for ebmBUS, RSB, SELV
KL3	10, 12	RSA	RS485 interface for ebmBUS, RSA, SELV

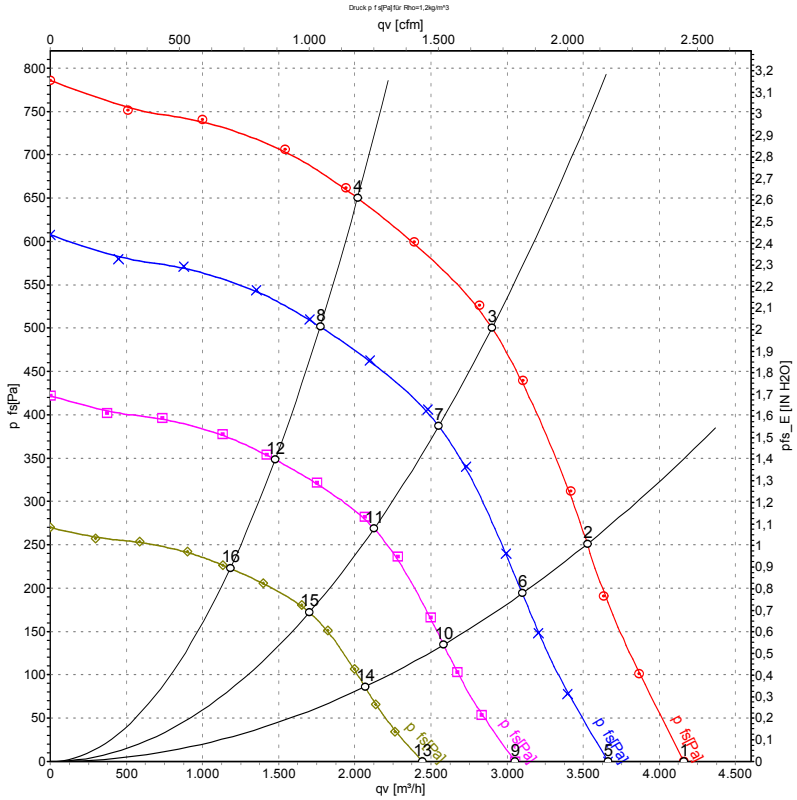
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Curves: Air performance 50 Hz



Measurement: LU-136332-1

Air performance measured according to ISO 5801 installation category A. For detailed information on the measurement setup, contact ebm-papst. Intake sound level: Sound power level according to ISO 13347 / sound pressure level measured at 1 m distance from fan axis. The values given are valid under the specified measuring conditions and may vary due to conditions of installation. For deviations from the standard configuration, the parameters have to be checked on the installed unit.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	q_V	p_{fs}	q_V	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa	cfm	in. wg
1	230	50	2035	594	2.59	78	86	92	4160	0	2450	0.00
2	230	50	2035	694	3.03	74	82	88	3525	250	2075	1.00
3	230	50	2035	770	3.50	68	75	82	2900	500	1705	2.01
4	230	50	2035	689	3.01	68	76	81	2020	650	1190	2.61
5	230	50	1800	405	1.77	76	83	90	3665	0	2155	0.00
6	230	50	1800	472	2.06	71	79	85	3100	194	1825	0.78
7	230	50	1800	520	2.27	65	73	79	2550	388	1500	1.56
8	230	50	1800	466	2.04	66	73	79	1770	502	1045	2.02
9	230	50	1500	234	1.02	72	79	86	3050	0	1795	0.00
10	230	50	1500	273	1.19	67	75	81	2585	135	1520	0.54
11	230	50	1500	301	1.31	61	69	75	2125	269	1250	1.08
12	230	50	1500	270	1.18	62	69	75	1475	348	870	1.40
13	230	50	1200	120	0.52	67	74	81	2440	0	1435	0.00
14	230	50	1200	140	0.61	62	70	77	2065	86	1215	0.35
15	230	50	1200	154	0.67	56	64	70	1700	172	1000	0.69
16	230	50	1200	138	0.60	57	64	70	1180	223	695	0.90

U = Voltage · f = Frequency · n = Speed (rpm) · P_{ed} = Power consumption · I = Current draw · LpA_{in} = Sound pressure level intake side · LwA_{in} = Sound power level intake side
LwA_{out} = Sound power level outlet side · q_V = Air flow · p_{fs} = Pressure increase

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