W3G710-GI08-03

EC axial fan

sickled blades (S series)

with full square nozzle

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**W3G710-GI08-03**
Motor	**M3G150-NA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
State		prelim.
Speed	min^{-1}	1560
Power input	W	4200
Current draw	A	6.7
Max. back pressure	Pa	400
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	+60

ml = max. load · me = max. efficiency · fa = running at free air · cs = customer specs · cu = customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}		47.5	33.6	37.6
Efficiency grade N		49.9	36	40
Power input P_{ed}	kW	4.13		
Air flow q_v	m^3/h	16945		
Pressure increase p_{fs}	Pa	400		
Speed n	min^{-1}	1575		

Data established at point of optimum efficiency

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Technical features

Mass	58 kg
Size	710 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of blades	Die-cast aluminium
Material of wall ring	Sheet steel, pre-galvanised and coated in black plastic
Material of guard grille	Steel, phosphated and coated in black plastic
Number of blades	5
Blade angle	-5°
Direction of air flow	"V"
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"F"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Shaft horizontal or rotor on bottom; rotor on top on request
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- PFC, passive - Control input 0-10 VDC / PWM - Over-temperature protected electronics / motor - Over-temperature protected motor - Alarm relay - Integrated PID controller - Input for sensor 0-10 V or 4-20 mA - Output for slave 0-10 V - RS485 ebmBUS - Line undervoltage / phase failure detection - Motor current limit - Soft start - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA
EMC interference immunity	Acc. to EN 61000-6-2
EMC interference emission	Acc. to EN 61000-6-3
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Electrical leads	Via terminal box
Motor protection	Reverse polarity and locked-rotor protection
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	CE

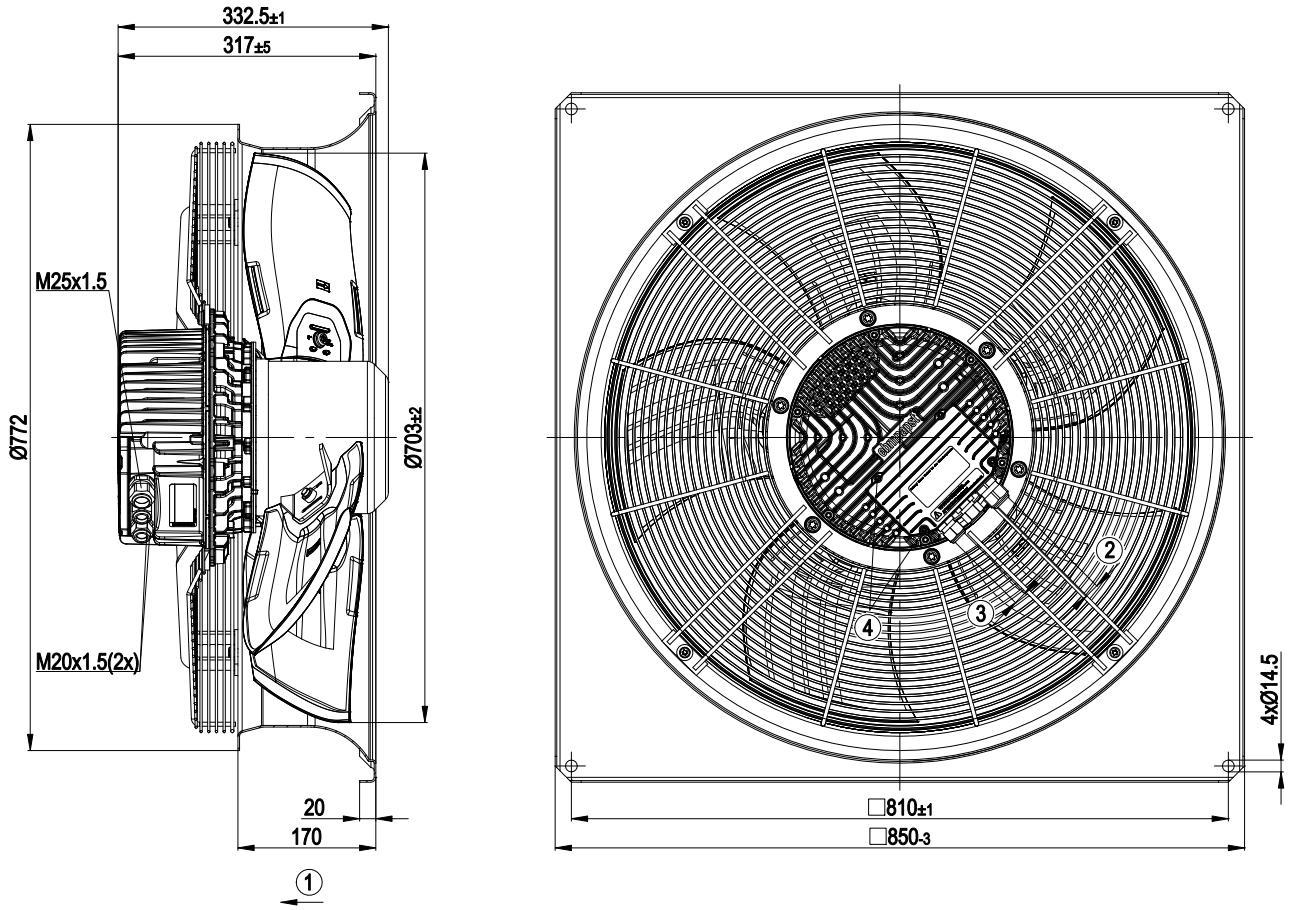
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Product drawing



1	Direction of air flow "V"
2	Cable diameter: min. 9 mm, max. 16 mm; tightening torque: 6±0.6 Nm
3	Cable diameter: min. 4 mm, max. 10 mm; tightening torque: 4±0.4 Nm
4	Tightening torque 3.5±0.5 Nm

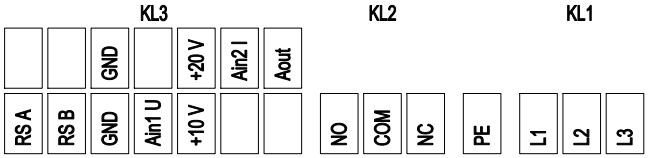
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Connection screen



No.	Pin	Signal	Function / assignment
PE		PE	Ground wire
KL1		L3	Power line, L3
KL1		L2	Power line, L2
KL1		L1	Power line, L1
KL2		NC	Alarm relay, normally closed connection
KL2		COM	Alarm relay, COMMON (2 A, 250 VAC, AC1)
KL2		NO	Alarm relay, normally open connection
KL3		+10 V	Supply for external potentiometer, 10 VDC(+/-3 %) max. 10 mA
KL3		Ain1U	Analogue set value input, 0-10 V (impedance 100 kΩ), can be used as an alternative to connection Ain2 I only
KL3		GND	GND
KL3		RSB	RS485 interface for ebmBus, RS B
KL3		RSA	RS485 interface for ebmBus, RS A
KL3		Aout	Analog output 0-10 V max. 5 mA, output of the current level control coefficient
KL3		Ain2 I	Analogue actual value input, 4-20 mA (impedance 100 Ω), can be used only as an alternative to connection Ain1 U only
KL3		+20 V	Supply for external sensor, 20 VDC (+25 %/-10 %) max. 40 mA
KL3		GND	GND

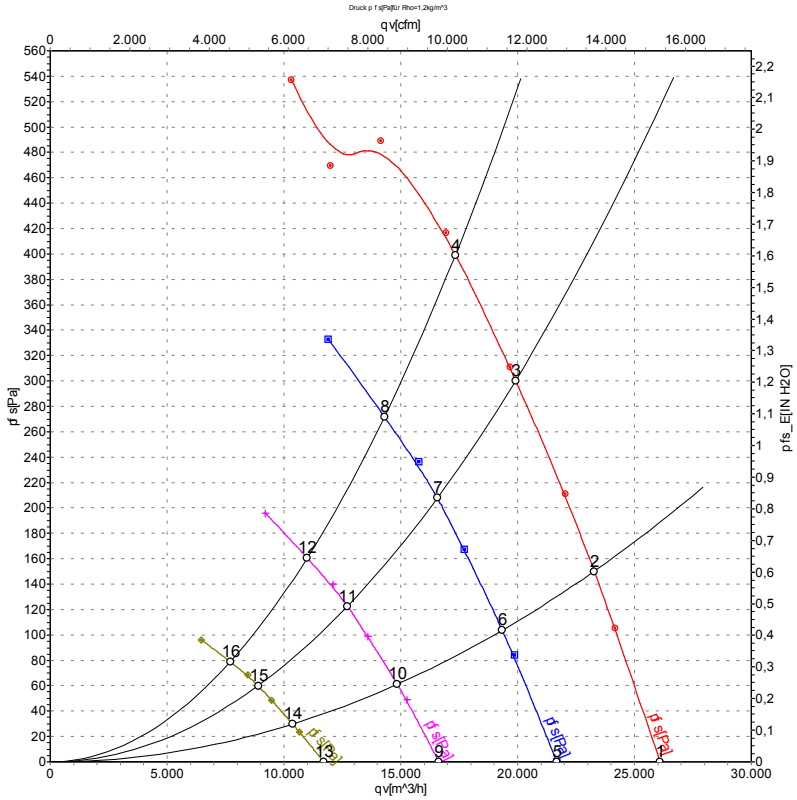
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Charts: Air flow 50 Hz



Measurement: LU-105068
Measurement: LU-118574
Measurement: LU-118575
Measurement: LU-118576

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	LwA_{out}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	dB(A)	m^3/h	Pa
1	400	50	1560	2891	4.68	77	83	84	26090	0
2	400	50	1560	3429	5.49	76	83	83	23270	150
3	400	50	1560	3863	6.16	79	85	85	19910	300
4	400	50	1560	4200	6.70	83	89	88	17340	400
5	400	50	1300	1516	2.64	72	79	78	21670	0
6	400	50	1300	1833	3.08	72	78	78	19340	104
7	400	50	1300	2092	3.46	74	81	80	16570	208
8	400	50	1300	2237	3.68	77	84	83	14300	273
9	400	50	1000	742	1.41	66	72	71	16620	0
10	400	50	1000	878	1.66	66	72	71	14850	62
11	400	50	1000	978	1.82	68	74	73	12720	123
12	400	50	1000	1045	1.93	71	77	76	11000	161
13	400	50	700	276	0.64	60	65	63	11720	0
14	400	50	700	326	0.73	60	65	63	10370	30
15	400	50	700	364	0.79	62	67	65	8895	60
16	400	50	700	383	0.82	63	69	68	7700	79

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · LwA_{out} = Sound power level outlet side
qv = Air flow · p_{fs} = Pressure increase

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