K3G450-AY86-07

EC centrifugal module - Plug fan

backward curved, single inlet

with support bracket

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ErP2015 EXCEEDS THE NORM

Nominal data

Type	**K3G450-AY86-07**
Motor	**M3G112-IA**

Phase		3~
Nominal voltage	VAC	400
Nominal voltage range	VAC	380 .. 480
Frequency	Hz	50/60
Type of data definition		ml
State		prelim.
Speed	min^{-1}	1750
Power input	W	1615
Current draw	A	2.5
Min. ambient temperature	°C	-25
Max. ambient temperature	°C	+50

ml = Max. load · me = Max. efficiency · fa = Running at free air · cs = Customer specs · cu = Customer unit
Subject to alterations

Data according to ErP directive

Installation category	A
Efficiency category	Static
Variable speed drive	Yes
Specific ratio*	1.01

* Specific ratio = 1 + p_{fs} / 100 000 Pa

		Actual	Request 2013	Request 2015
Overall efficiency η_{es}		67.6	49.7	53.7
Efficiency grade N		75.9	58	62
Power input P_{ed}	kW	1.61		
Air flow q_v	m^3/h	6100		
Pressure increase p_{fs}	Pa	602		
Speed n	min^{-1}	1735		

Data definition with optimum efficiency.
The ErP data is determined using a motor-impeller combination in a standardised measurement configuration.

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Technical features

Mass	31.9 kg
Size	450 mm
Surface of rotor	Coated in black
Material of electronics housing	Die-cast aluminium
Material of impeller	Aluminium sheet
Material of mounting plate	Sheet steel, galvanised
Material of support bracket	Steel, coated in black
Material of inlet nozzle	Sheet steel, galvanised
Number of blades	7
Direction of rotation	Clockwise, seen on rotor
Type of protection	IP 54
Insulation class	"B"
Humidity class	F4-1
Max. permissible ambient motor temp. (transp./ storage)	+80 °C
Min. permissible ambient motor temp. (transp./storage)	-40 °C
Mounting position	Refer to product drawing
Condensate discharge holes	Rotor-side
Operation mode	S1
Motor bearing	Ball bearing
Technical features	- External 24 V input (programming) - RS485 MODBUS RTU - PFC, passive - Control input 0-10 VDC / PWM - Over-temperature protected electronics / motor - Over-temperature protected motor - Alarm relay - Integrated PID controller - Input for sensor 0-10 V or 4-20 mA - Output for slave 0-10 V - Line undervoltage detection - Motor current limit - Soft start - Line undervoltage / phase failure detection - Output 10 VDC, max. 10 mA - Output 20 VDC, max. 50 mA - Over-temperature protected electronics
EMC interference immunity	Acc. to EN 61000-6-2 (industrial environment)
EMC interference emission	Acc. to EN 61000-6-3 (household environment)
Touch current acc. IEC 60990 (measuring network Fig. 4, TN system)	<= 3.5 mA
Motor protection	Thermal overload protector (TOP) wired internally
Protection class	I (if protective earth is connected by customer)
Product conforming to standard	EN 61800-5-1; CE

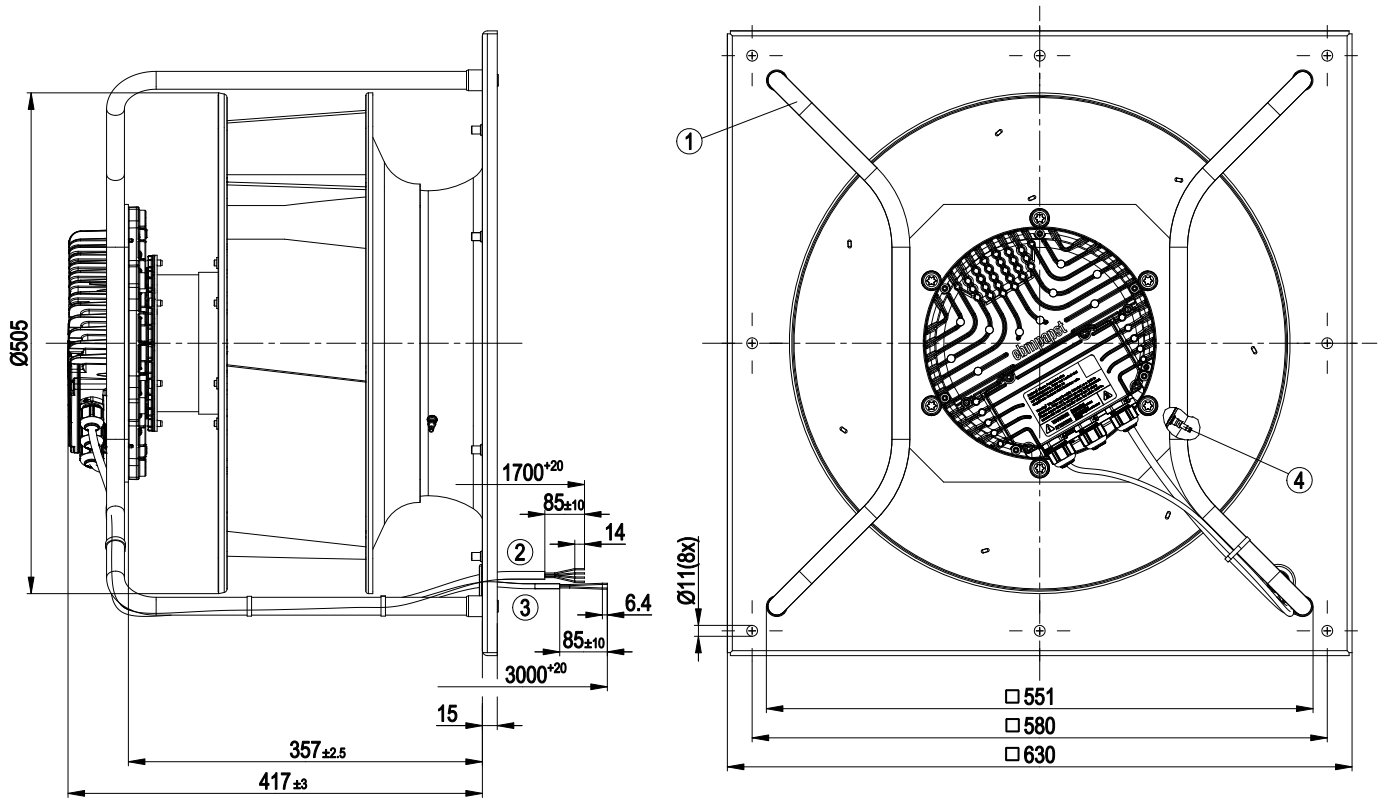
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Product drawing



1	Mounting position: shaft horizontal (install the support struts only vertically as shown in the view!) or rotor on bottom; rotor on top on request
2	Connection line silicone 4G 1.5mm², 4x crimped core-end sleeve
3	Connection line AWG22, 2x brass lead tips crimped
4	Inlet nozzle with bleeder connection for pressure relief (k-factor: 240)

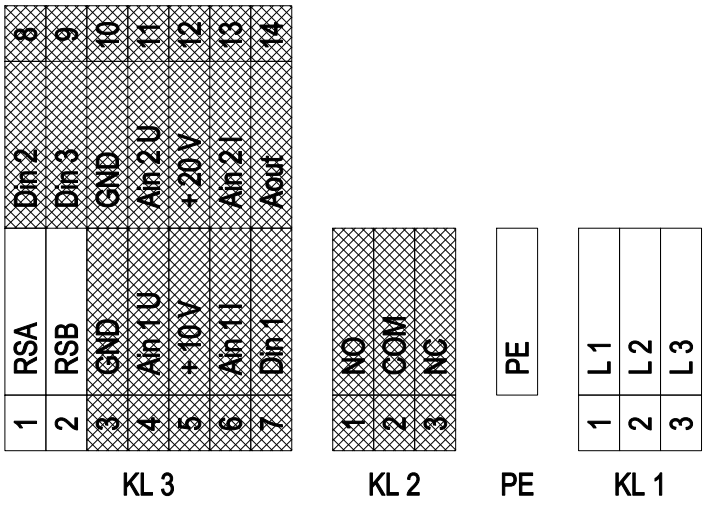
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Connection screen



Shading => terminals not assigned

No.	Pin	Signal	Function / assignment
KL 1	1	L1	Mains supply connection, supply voltage 3-phase 380-480 VAC; 50/60 Hz
KL 1	2	L2	Mains supply connection, supply voltage 3-phase 380-480 VAC; 50/60 Hz
KL 1	3	L3	Mains supply connection, supply voltage 3-phase 380-480 VAC; 50/60 Hz
PE		PE	Earth connection, PE connection
KL 2	1	NO	Status relay, floating status contact; normally open; make for failure
KL2	2	COM	Status relay; floating status contact; changeover contact; common connection; contact rating 250 VAC / max. 2 A (AC1) / min. 10 mA
KL2	3	NC	Status relay, floating status contact; break for failure
KL 3	1	RSA	Bus connection RS485; RSA; MODBUS RTU
KL 3	2	RSB	Bus connection RS485; RSB; MODBUS RTU
KL 3	3 / 10	GND	Reference ground for control interface
KL 3	4	Ain1 U	Analogue input 1 (set value); 0-10 V; Ri= 100 kΩ; parametrisable curves; only usable as alternative to input Ain1 I
KL 3	5	+ 10 V	Fixed voltage output 10 VDC; + 10 V +/-3%; max. 10 mA; short circuit proof; power supply for ext. devices (e.g. potentiometer)
KL 3	6	Ain1 I	Analogue input 1 (set value); 4-20 mA; Ri= 100 Ω; parametrisable curves; only usable as alternative to input Ain1 U
KL 3	7	Din1	Digital input 1: enabling of electronics; enabling: open pin or applied voltage 5 to 50 VDC; disabling: bridge to GND or applied voltage < 1 VDC; reset function: triggers software reset after a level change to <1 V
KL 3	8	Din2	Digital input 2: parameter set switch 1/2; according to EEPROM setting, the valid/used parameter set is selectable per BUS or per digital input DIN2. Parameter set 1: open pin or applied voltage 5 to 50 VDC; parameter set 2: bridge to GND or applied voltage < 1 VDC
KL 3	9	Din3	Digital input 3: Control characteristic of the integrated controller; according to EEPROM setting, the control characteristic of the integrated controller is normally/inversely selectable per BUS or per digital input; normal: open pin or applied voltage 5 to 50 VDC (control deviation = actual sensor value - set value) inverse: bridge to GND or applied voltage < 1 VDC (control deviation = set value - actual sensor value)
KL 3	11	Ain2 U	Analogue input 2; actual sensor value 0-10 V; Ri= 100 kΩ; parametrisable curve; only usable as alternative to input Ain2 I
KL 3	12	+ 20 V	Fixed voltage output 20 VDC; + 20V +25/-10%; max. 50 mA; short circuit proof; supply voltage for ext. devices (e.g. sensors)
KL 3	13	Ain2 I	Analogue input 2; actual sensor value 4-20 mA; Ri= 100 Ω; parametrisable curve; only usable as alternative to input Ain2 U

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No.	Pin	Signal	Function / assignment
KL 3	14	Aout	Analogue output 0-10 V; max. 5 mA; output of the current motor level control coefficient/of the current motor speed. Parametrisable curve.

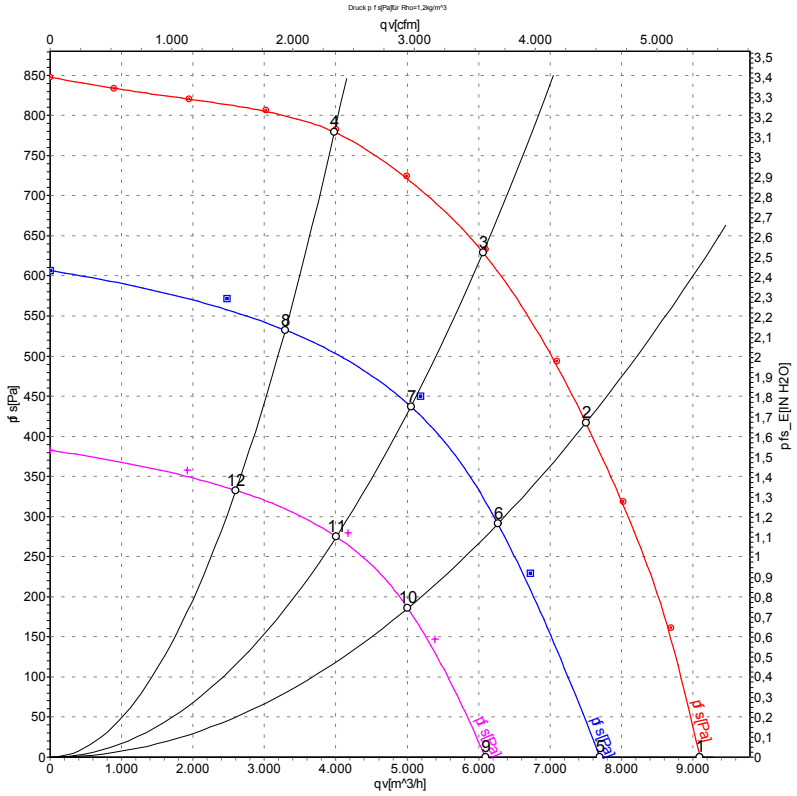
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Charts: Air flow 50 Hz



Measurement: LU-116793
Measurement: LU-117461
Measurement: LU-117462

Air performance measured as per ISO 5801 Installation category A. For detailed information on the measuring set-up, please contact ebm-papst. Suction-side noise levels: LwA measured as per ISO 13347 / LpA measured with 1m distance to fan axis. The values given are valid under the measuring conditions mentioned above and may vary according to the actual installation situation. With any deviation from the standard set-up, the specific values have to be checked and reviewed with the unit installed.

Measured values

	U	f	n	P_{ed}	I	LpA_{in}	LwA_{in}	qv	p_{fs}
	V	Hz	min^{-1}	W	A	dB(A)	dB(A)	m^3/h	Pa
1	400	50	1750	1036	1.61	80	87	9100	0
2	400	50	1750	1457	2.25	72	80	7505	420
3	400	50	1750	1615	2.50	70	77	6065	635
4	400	50	1750	1524	2.33	73	80	3980	785
5	400	50	1450	571	0.92	74	82	7695	0
6	400	50	1450	812	1.28	67	75	6270	294
7	400	50	1450	906	1.42	66	73	5055	456
8	400	50	1450	810	1.27	69	76	3290	535
9	400	50	1155	306	0.56	68	76	6095	0
10	400	50	1155	427	0.73	61	69	5010	188
11	400	50	1155	462	0.77	59	67	4005	285
12	400	50	1155	411	0.70	62	69	2600	334

U = Supply voltage · f = Frequency · n = Speed · P_{ed} = Power input · I = Current draw · LpA_{in} = Sound pressure level inlet side · LwA_{in} = Sound power level inlet side · qv = Air flow
p_{fs} = Pressure increase

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